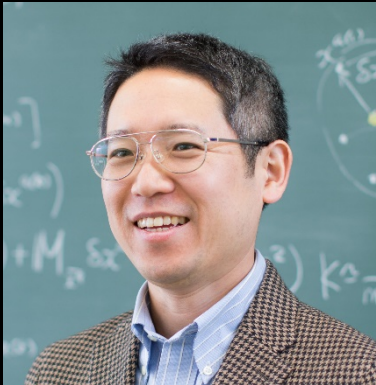


Big Data Assimilation

A New Science

for Weather Prediction and Beyond



Takemasa Miyoshi

Ph.D. (Meteorology)
Data Assimilation Scientist

Data Assimilation Research Team

RIKEN



Who am I?

B.S. from Kyoto U



JMA administration (2y)



JMA NWP (1.25y)



UMD (2y, M.S. and Ph.D.)



JMA NWP (3.5y)



UMD (4y)



RIKEN (6y+)

<http://data-assimilation.riken.jp/~miyoshi/>

Takemasa Miyoshi, Ph.D.

Team Leader

Data Assimilation Research Team
RIKEN Center for Computational Science

Deputy Director

RIKEN interdisciplinary Theoretical and Mathematical Sciences
(iTHEMS) Program

Chief Scientist

Prediction Science Laboratory
RIKEN Cluster for Pioneering Research

Visiting Professor

University of Maryland, College Park

Affiliate Professor

Graduate School of Science, Kyoto University

Visiting Principal Scientist

Application Laboratory, JAMSTEC

Research Counselor

Servicio Meteorológico Nacional (National Meteorological Service),
Argentina



Education

- **2005** Ph.D. in Meteorology, University of Maryland, College Park, Maryland, USA ([Dissertation PDF](#))
- **2004** M.S. in Meteorology, University of Maryland, College Park, Maryland, USA ([Scholarly Paper PDF](#))
- **2000** B.S. in Physics, Faculty of Science, Kyoto University, Kyoto, Japan



<http://tedxsannomiya.com/en/speakers/takemasa-miyoshi/>

Japan's flagship institute for computational science

Missions:

- 1) Development & operation of the **Japanese flagship supercomputer**
- 2) Center of Excellence for research on computational science



Japan's flagship institute for computational science

Missions:

- 1) Development & operation of the **Japanese flagship supercomputer**
- 2) Center of Excellence for research on computational science

New **“Fugaku”** or **“富岳”** is being developed





©RIKEN



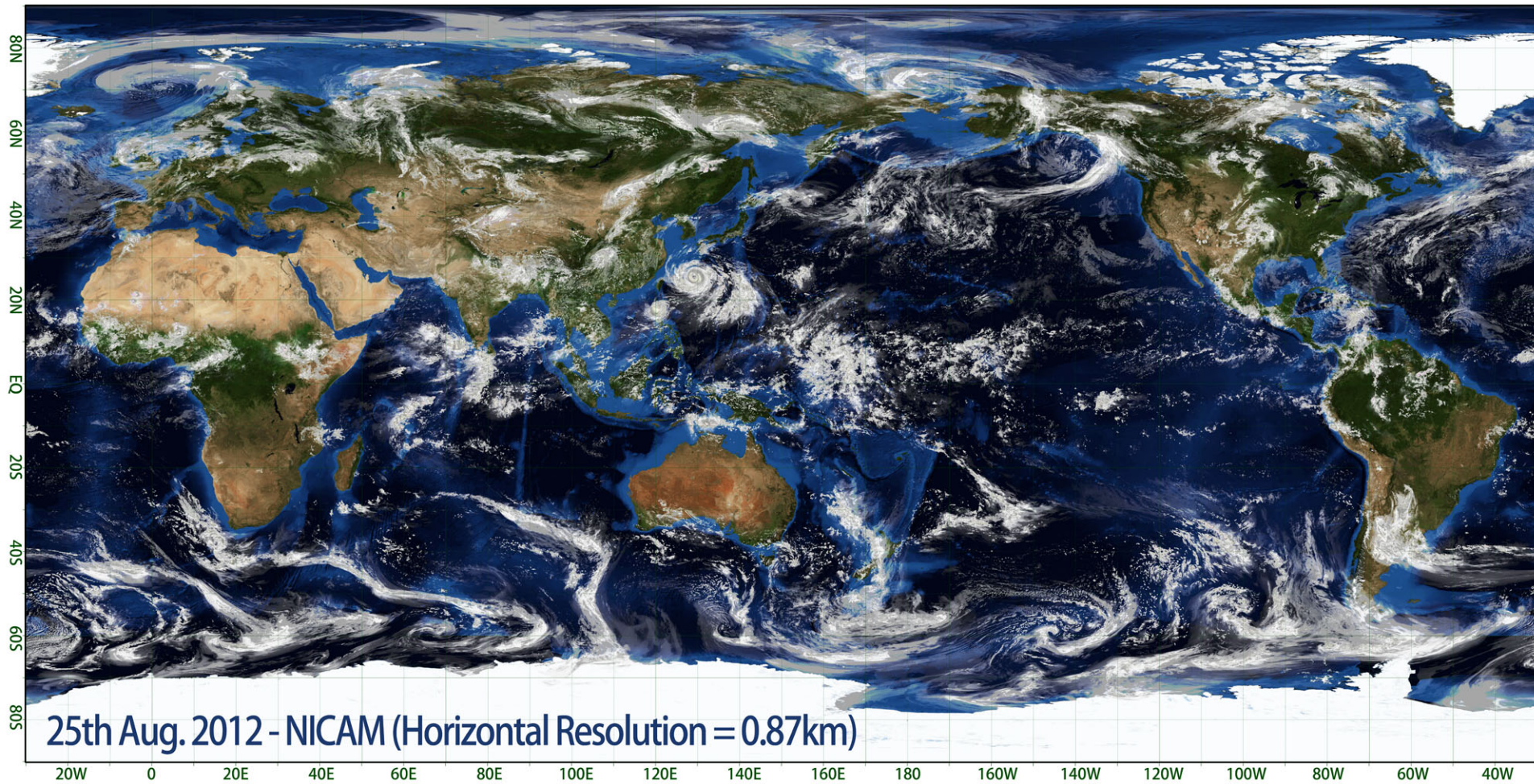
TimeStep: 7

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Visualized by Ryuji Yoshida

cf. TEDxSannomiya

<http://tedxsannomiya.com/speakers/takemasa-miyoshi/>

Global 870-m simulation *(Miyamoto et al. 2013)*

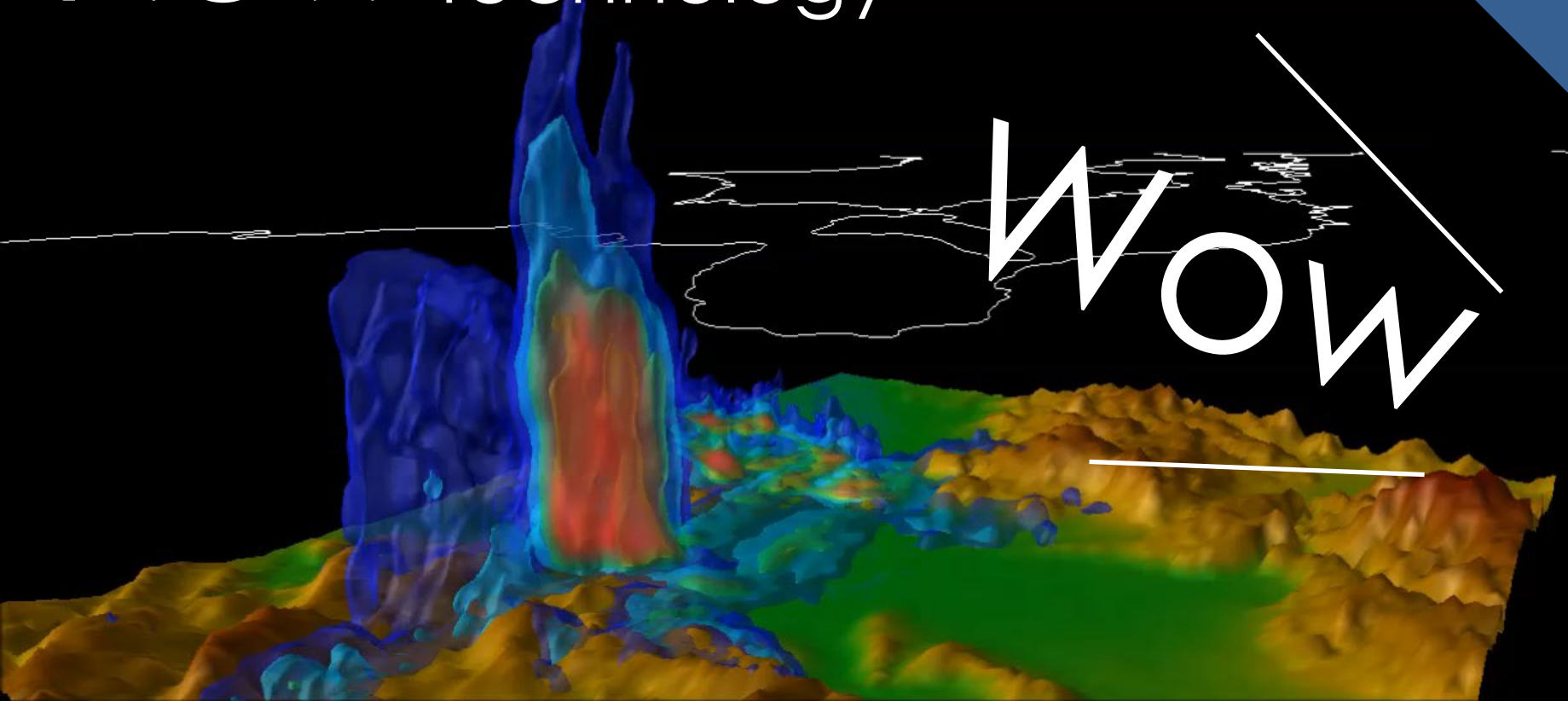


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Visualized by Ryuji Yoshida

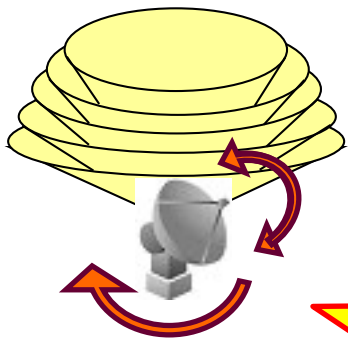
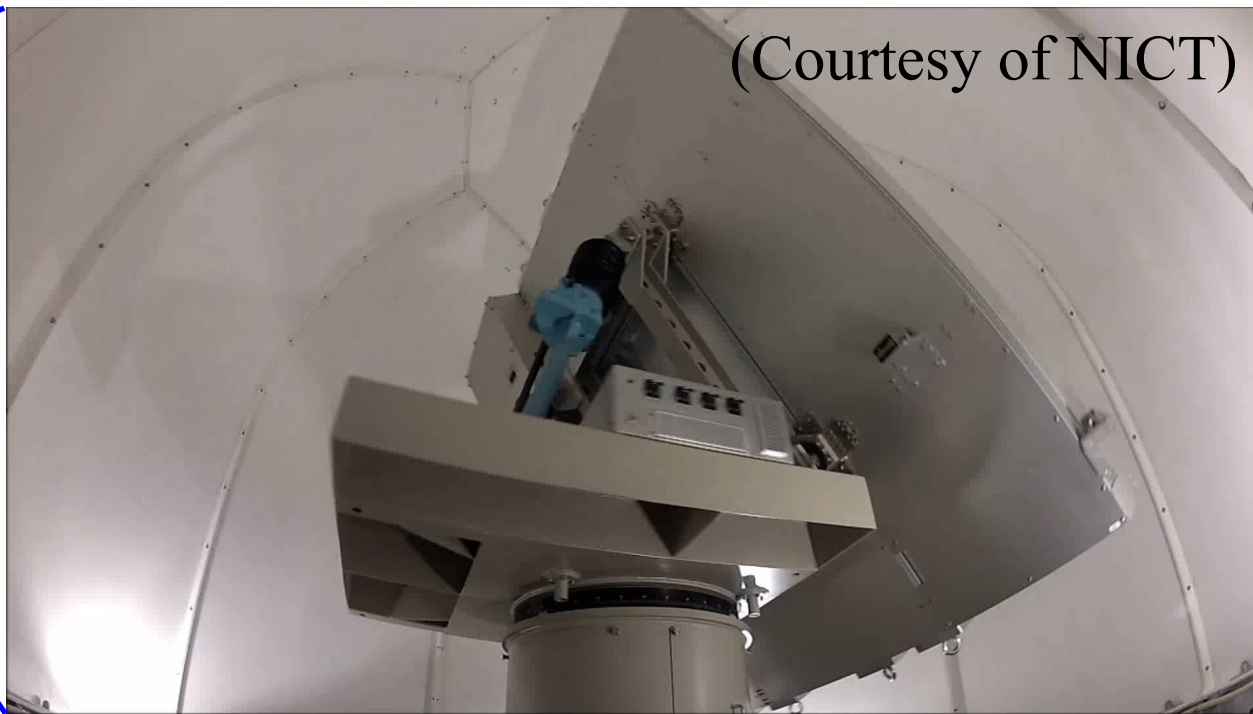
New radar technology



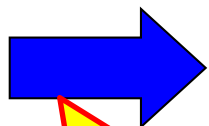
WOW



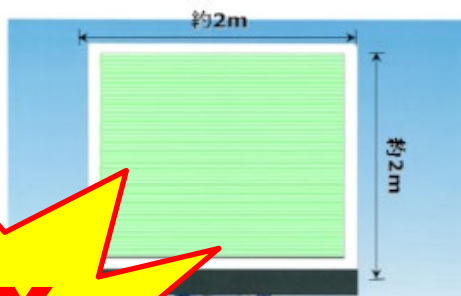
Phased Array Weather Radar (PAWR)



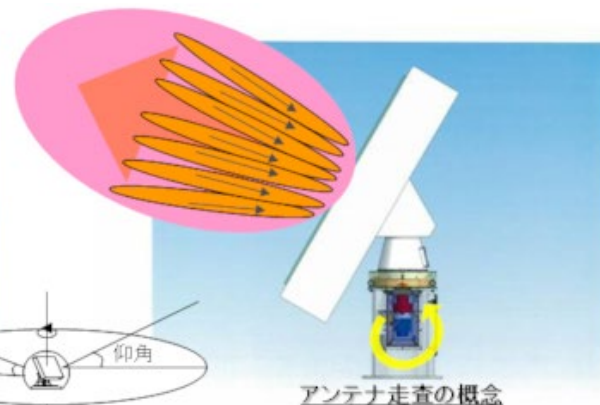
3-dim measurement using a parabolic antenna (150 m, 15 EL angles in 5 min)



100x data size



線装置の外観

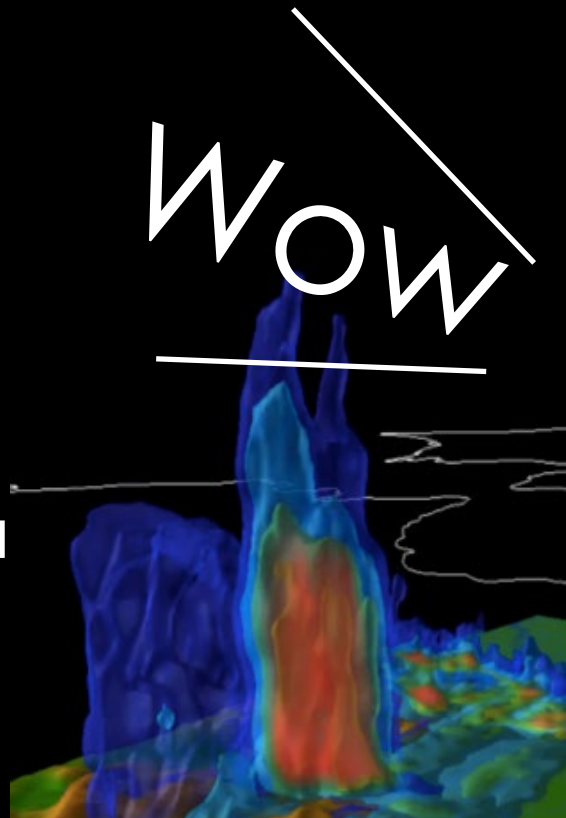


アンテナ走査の概念

3-dim measurement using a phased array antenna (100 m, 100 EL angles in 30 sec)



+

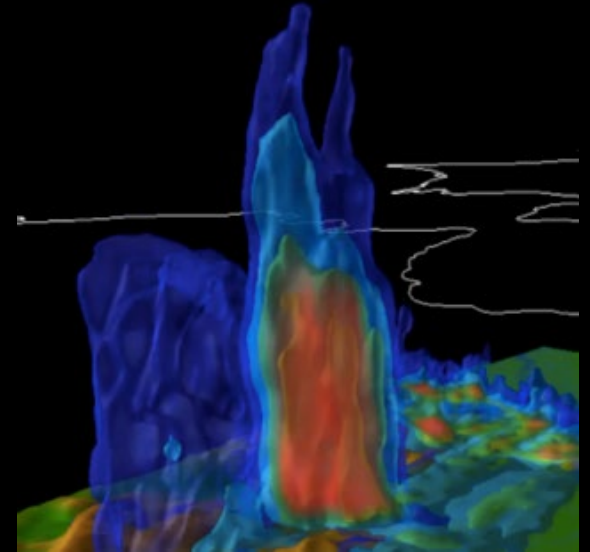


=



Data Assimilation





=

~~Sudden heavy rain~~

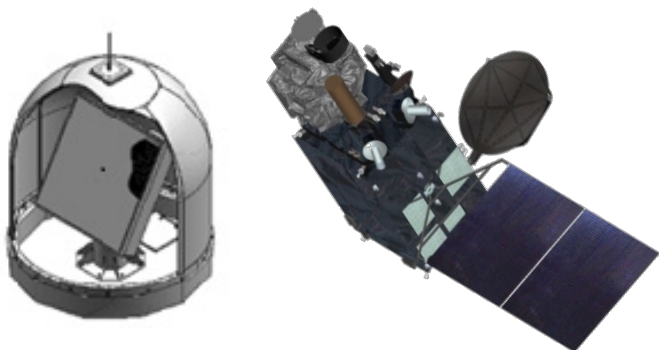
Big Data Assimilation

Observations

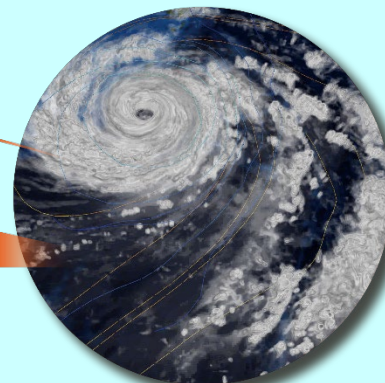


Big Data

New sensors, IoT



Simulations



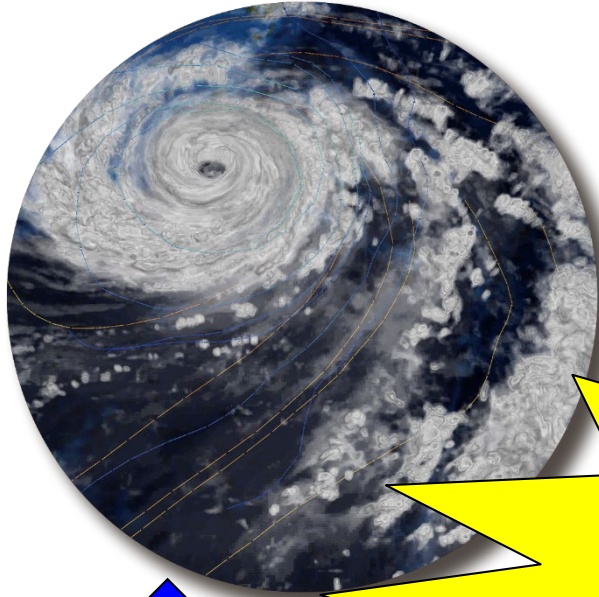
Big Data

Powerful supercomputer



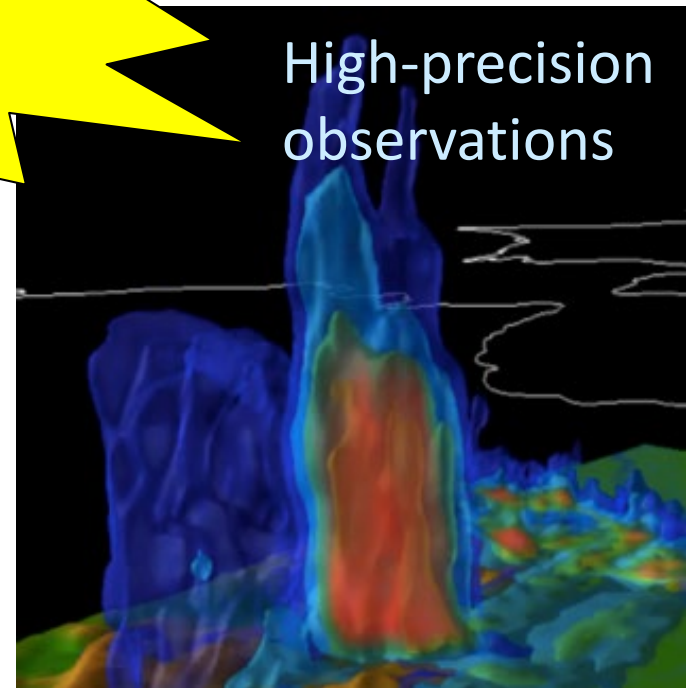
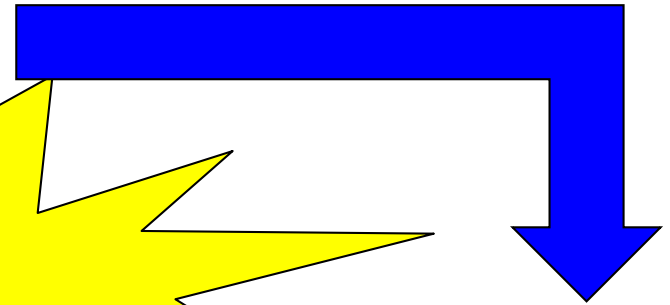
Pioneering “Big Data Assimilation” Era

High-precision Simulations

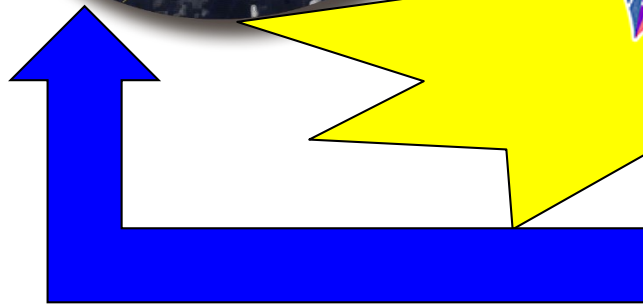


JST 国立研究開発法人
科学技術振興機構 CREST
Japan Science and Technology Agency

Future-generation technologies
available 10 years in advance



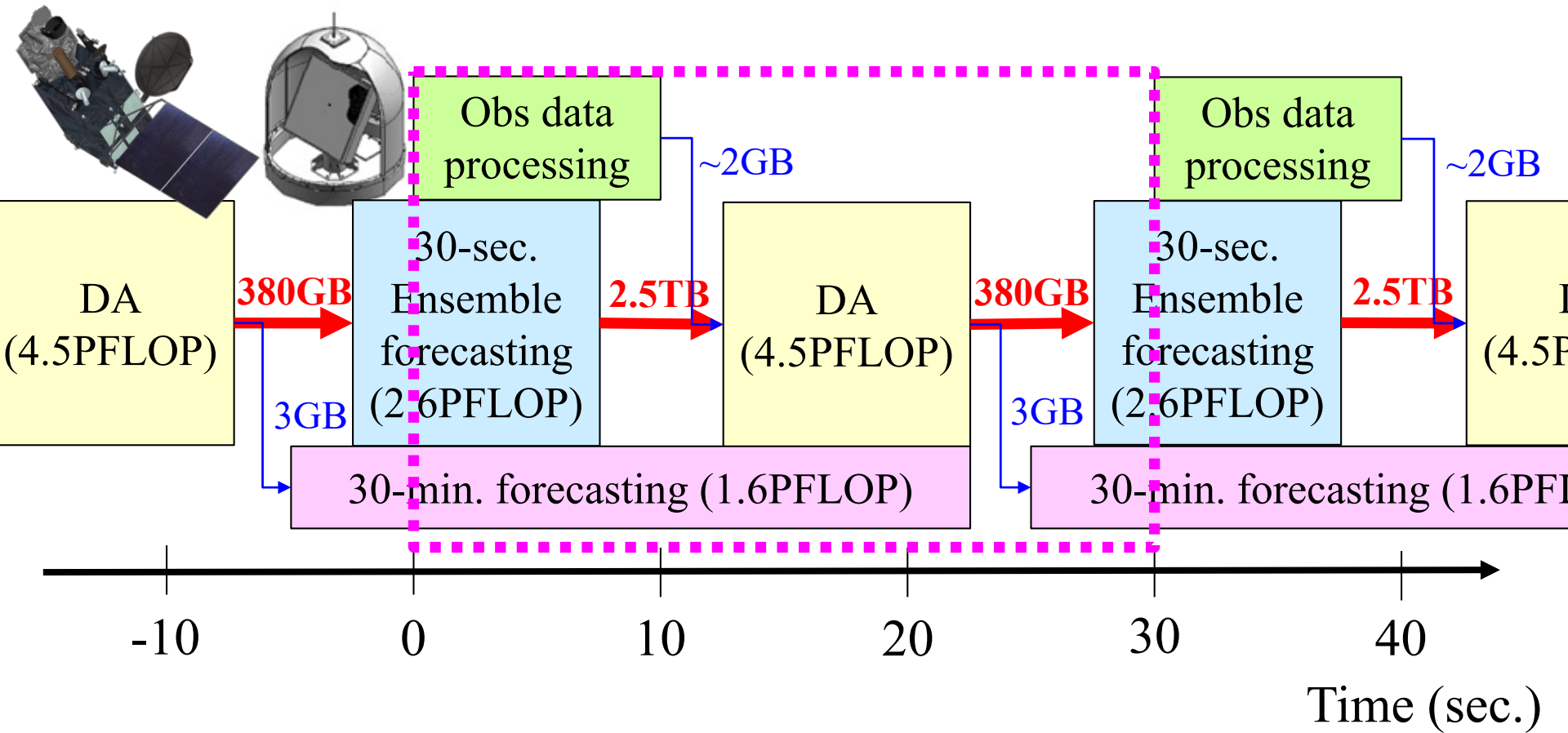
High-precision
observations



Mutual feedback

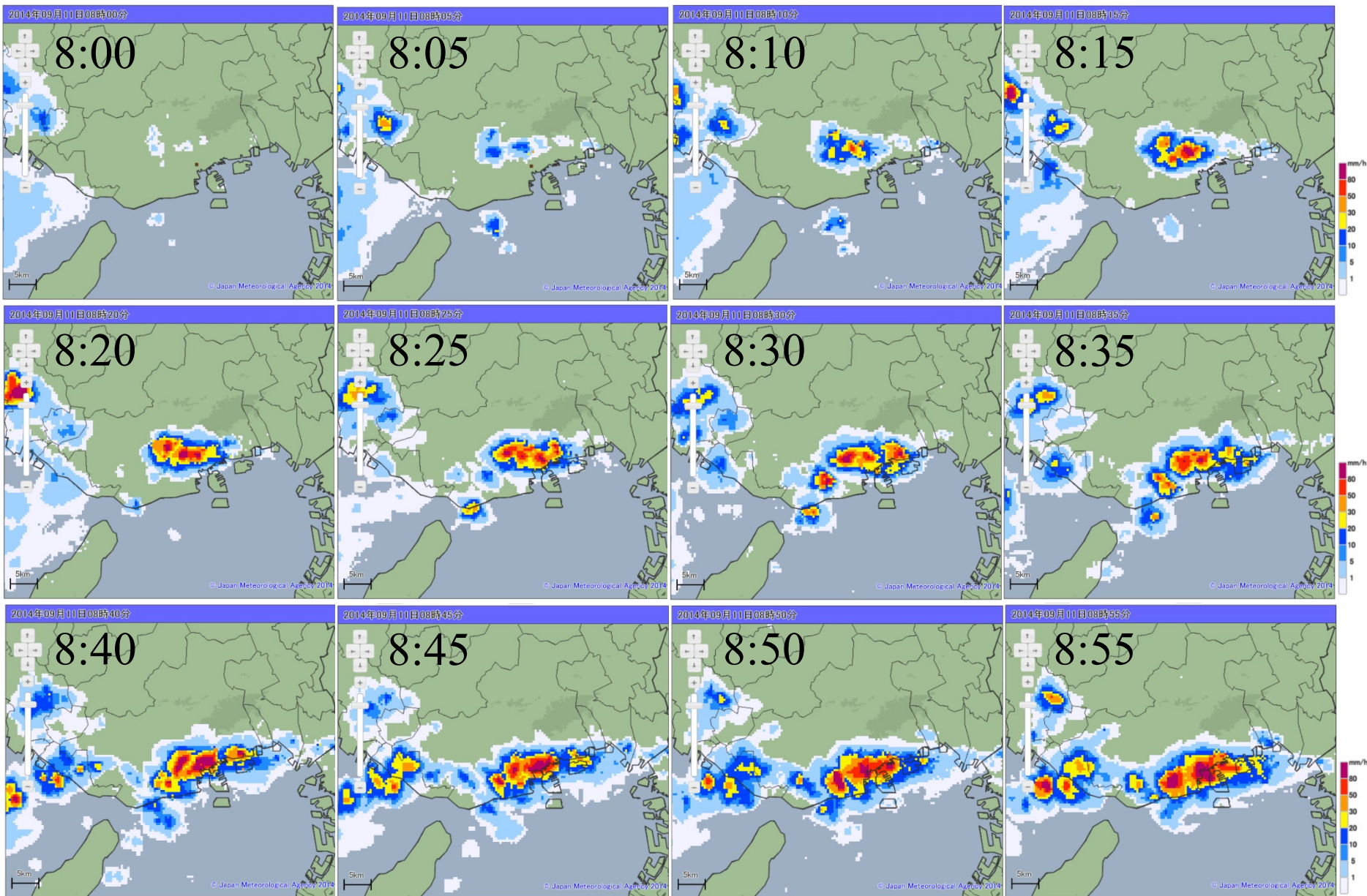


Revolutionary super-rapid 30-sec. cycle



120 times more rapid than
hourly update cycles

9/11/2014 morning, sudden rain



9/11/2014, sudden local rain

RIKEN Advanced Institute for Computational Science
Data Assimilation Research Team

2014.09.11 08:01:00

Observation

Simulation
(100m Big DA)

>41,000 views
#6 of RIKEN channel

10km
Simulation
(w/o DA)

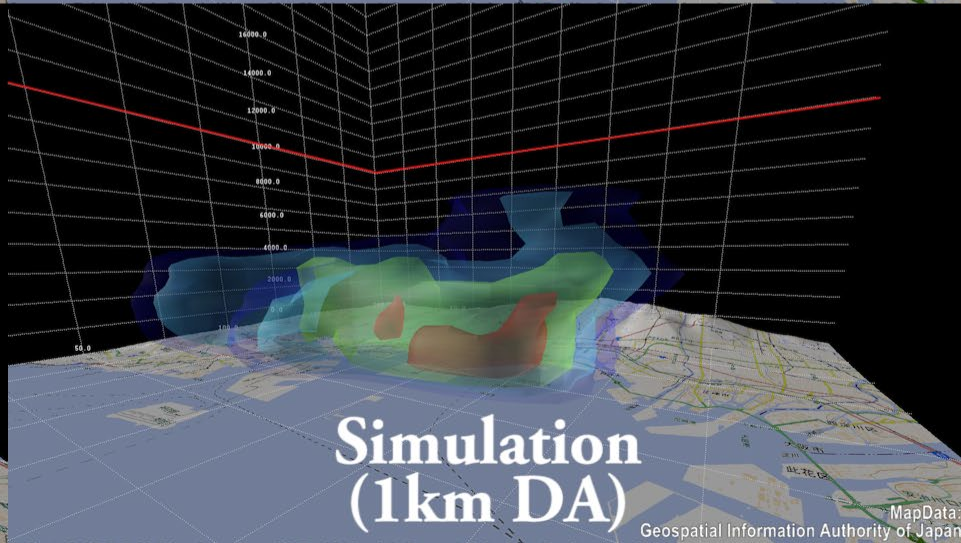
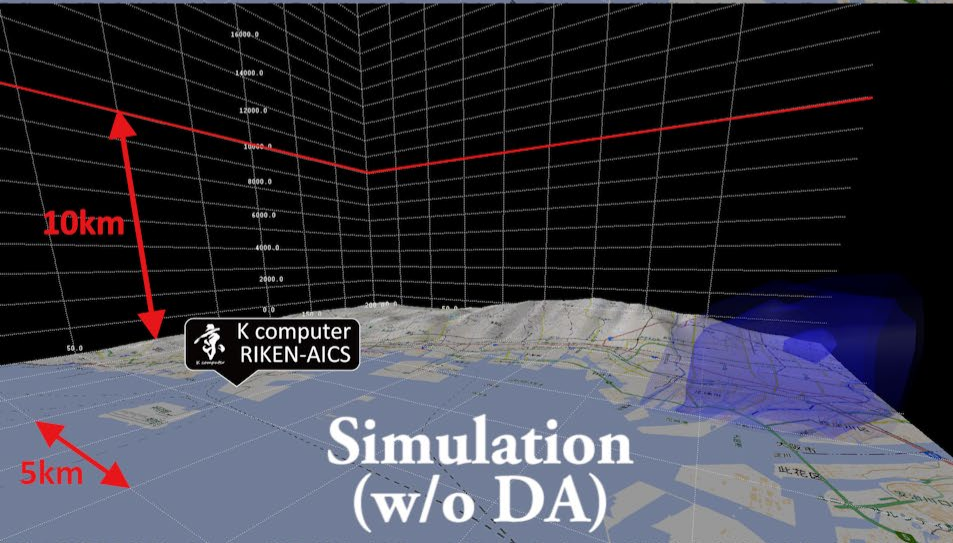
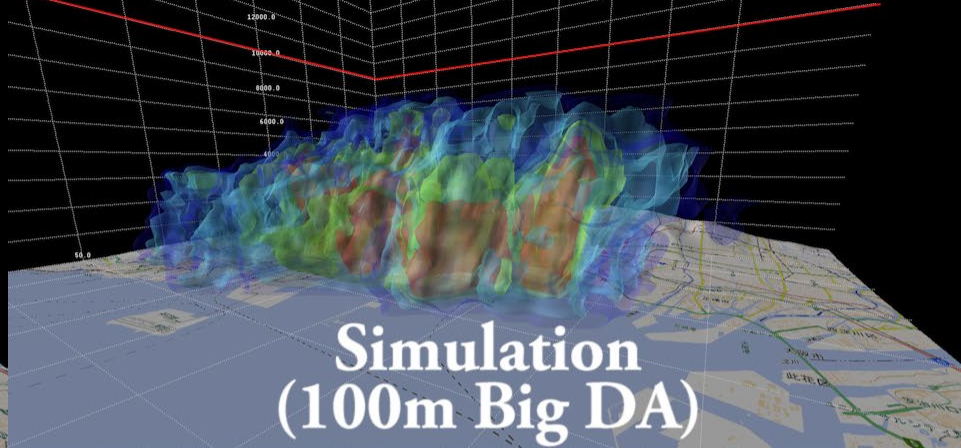
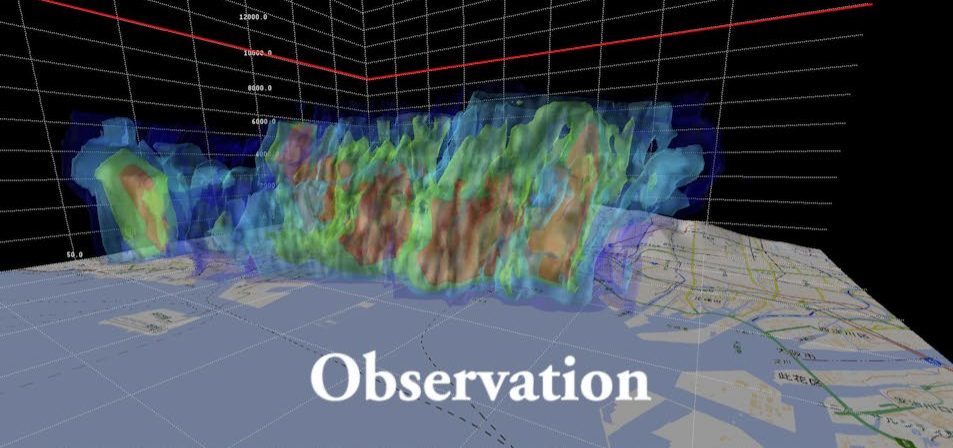
Simulation
(1km DA)



9/11/2014, sudden local rain

RIKEN Advanced Institute for Computational Science
Data Assimilation Research Team

2014.09.11 08:25:00



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Himawari-8 data assimilated simulation enables 10-minute updates of rain and flood predictions

Using the power of Japan's K computer, scientists from the RIKEN Advanced Institute for Computational Science and collaborators have shown that incorporating satellite data at frequent intervals—ten minutes in the case of this study—into weather prediction models can significantly improve the rainfall predictions of the models and allow more precise predictions of the rapid development of a typhoon.

Weather prediction models attempt to predict future weather by running simulations based on current conditions taken from various sources of data. However, the inherently complex nature of the systems, coupled with the lack of precision and timeliness of the data, makes it difficult to conduct accurate predictions, especially with weather systems such as sudden precipitation.

As a means to improve models, scientists are using powerful supercomputers to run simulations based on more frequently updated and accurate data. The team led by Takemasa Miyoshi of AICS decided to work with data from Himawari-8, a geostationary satellite that began operating in 2015. Its instruments can scan the entire area it covers every ten minutes in both visible and infrared light, at a resolution of up to 500 meters, and the data is provided to meteorological agencies. Infrared measurements are useful for indirectly gauging rainfall, as they make it possible to see where clouds are located and at what altitude.

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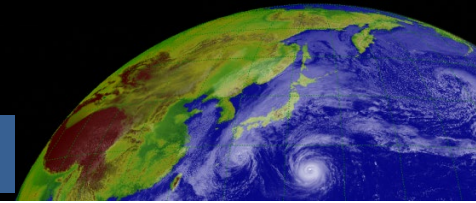
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Himawari-8: a new generation geostationary meteorological satellite



frequent, colorful, precise

~50x
more data

MTSAT-2 VIS 02. APR. 2015 16:00UTC

Himawari-8 02. APR. 2015 16:00UTC

16UTC 2 to 13UTC 3 April 2015
MTSAT-2 (VIS)
Every 1 hour

16UTC 2 to 13UTC 3 April 2015
Himawari-8 (True Color)
Every 10 minutes

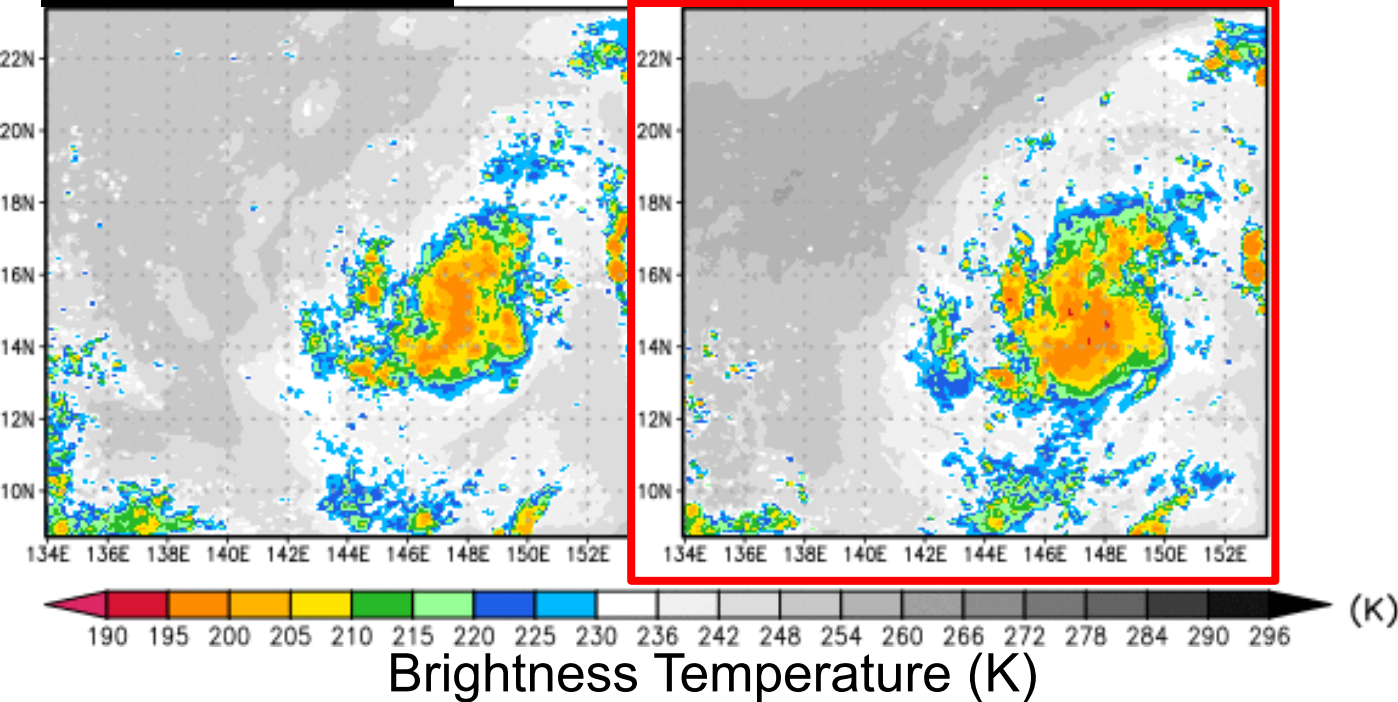
(Courtesy of JMA)

Himawari-8 “*Big Data Assimilation*”

Typhoon Soudelor (2015)

Simulation

Data Assimilation



Honda, Miyoshi, et al. (2018)

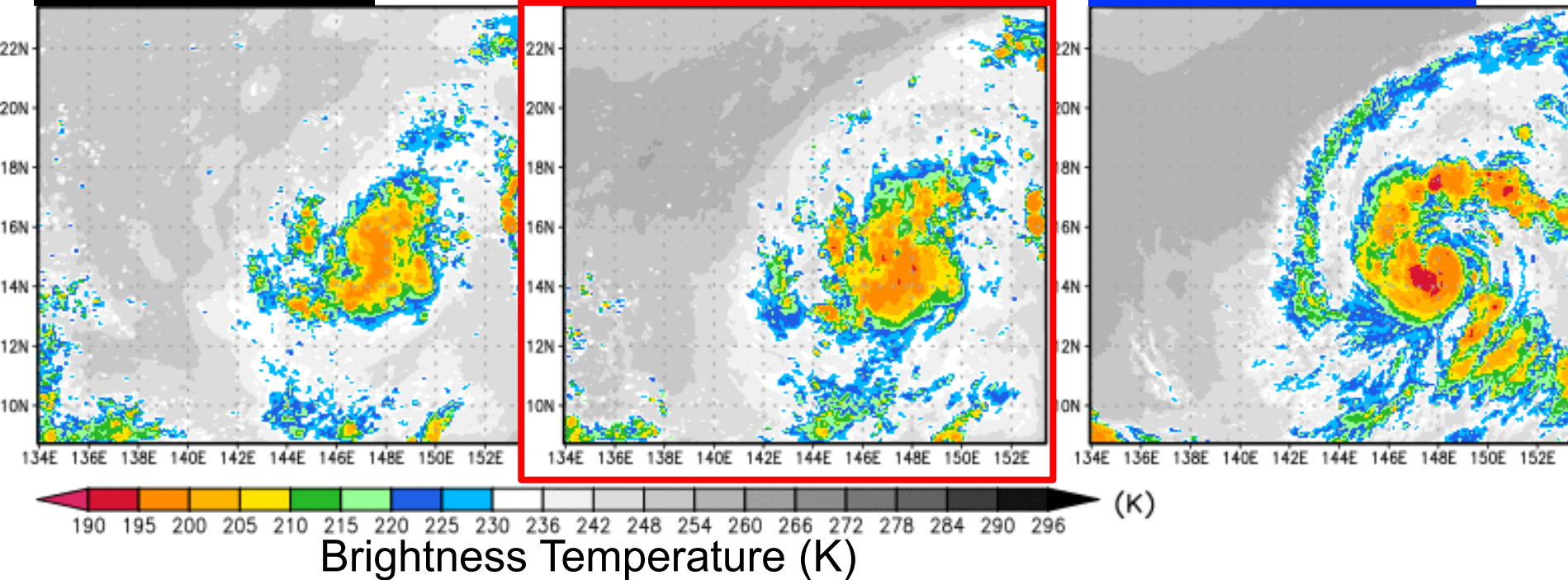
Himawari-8 “*Big Data Assimilation*”

Typhoon Soudelor (2015)

Simulation

Data Assimilation

Observation



Honda, Miyoshi, et al. (2018)

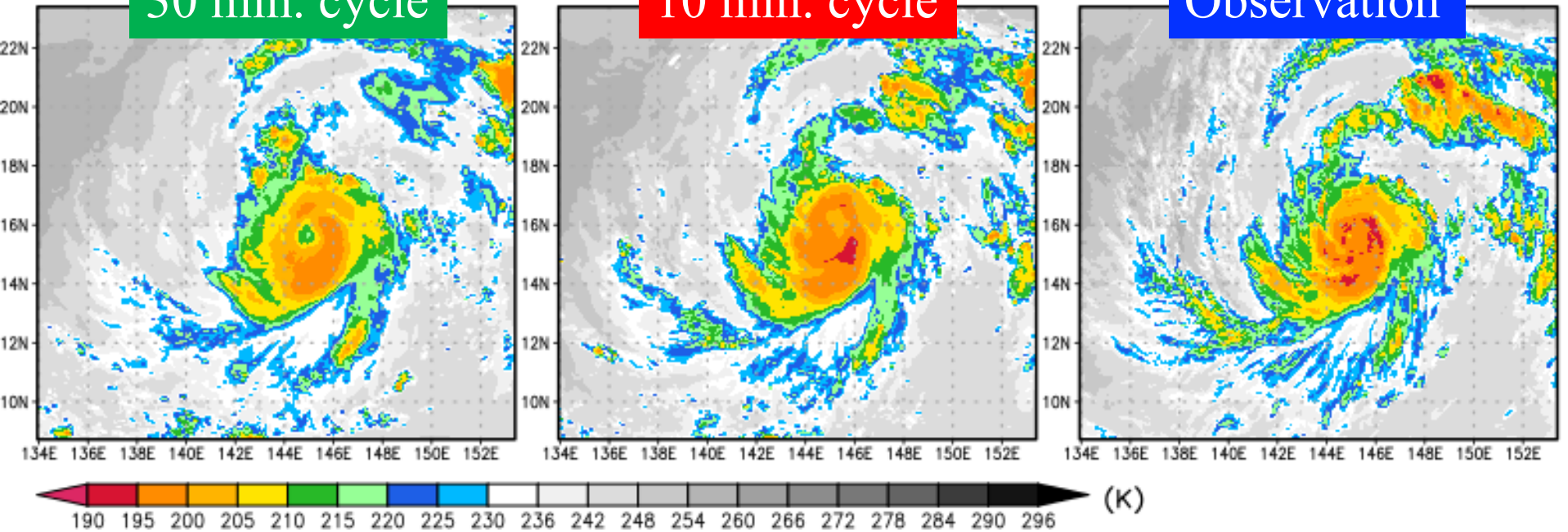
Every 10 min. vs. 30 min. DA

Analyzed/Observed Brightness Temperature B09 ($6.9\mu\text{m}$), at 17:50z02Aug2015

30 min. cycle

10 min. cycle

Observation

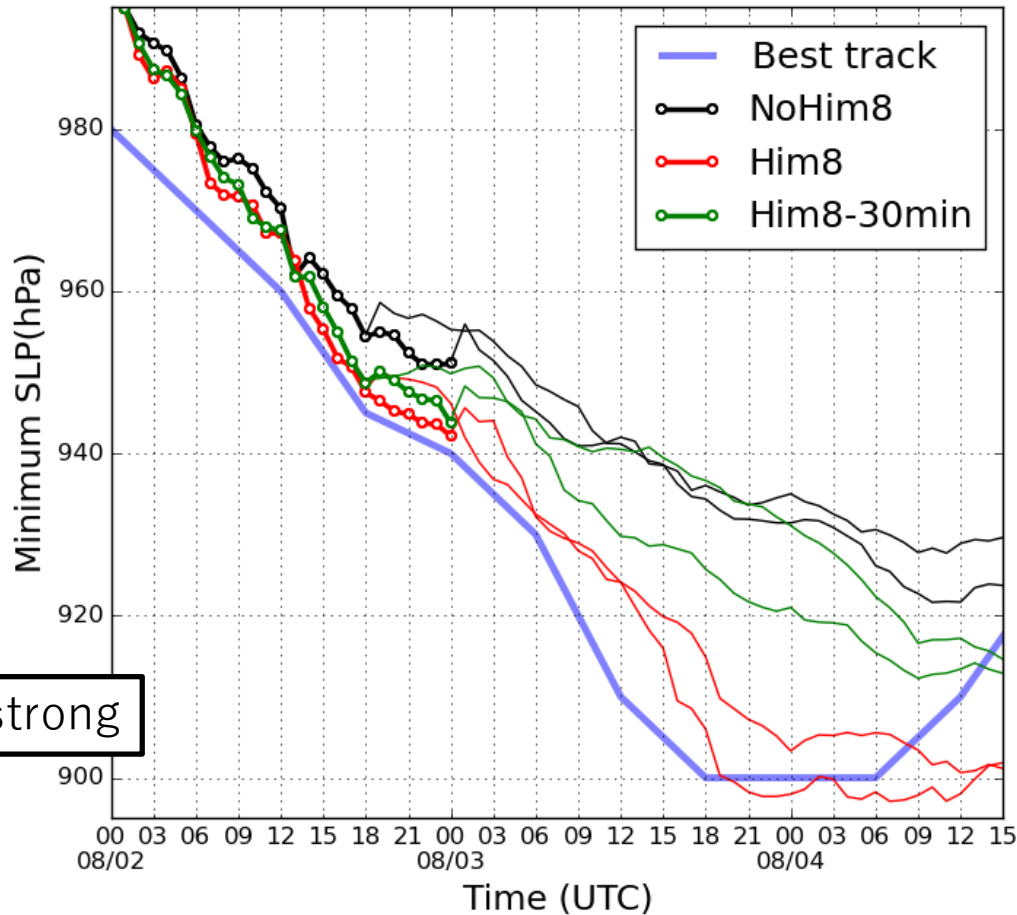


Brightness Temperature (K)

Intensity forecast (30 min. vs. 10 min.)

weak

Analysis and Forecasts (MSLP)



strong

Assimilating every 10-min. is essential.

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July 23, 2014

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K computer runs largest ever ensemble simulation of global weather

Ensemble forecasting is a key part of weather forecasting today. Computers typically run multiple simulations, called ensembles, using slightly different initial conditions or assumptions, and then analyze them together to try to improve forecasts. Now, in research published in *Geophysical Research Letters*, using Japan's flagship 10-petaFLOPS K computer, researchers from the RIKEN Advanced Institute for Computational Science (AICS) have succeeded in running 10,240 parallel simulations of global weather, the largest number ever performed, using data assimilation to reduce the range of uncertainties.

The assimilation of the 10,240 ensemble data sets was made possible by a cross-disciplinary collaboration of data assimilation experts and eigenvalue solver scientists at RIKEN AICS. The "Local Ensemble Transform Kalman Filter" (LETKF), an already efficient system, was further improved by a factor of eight using the "EigenExa" high-performance eigenvalue solver software, making possible a three-week computation of data from the 10,240 ensembles for simulated global weather. By analyzing the 10,240 equally probable estimates of atmospheric states, the team discovered that faraway observations, even going beyond 10,000 kilometers in distance, may have an immediate impact on eventual state of the estimation. This finding suggests the need for further research on advanced methods that can make better use of faraway observations, as this could potentially lead to an improvement of weather forecasts.

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July 23, 2014

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K computer runs largest ever ensemble simulation of global weather

Ensemble forecasting, called ensembles, try to improve forecasts by running multiple simulations. The 10-petaFLOPS K computer has succeeded in using data assimilation

A simulated study using the T30/L7 SPEEDY AGCM (Miyoshi, Kondo, Imamura 2014)

The assimilation of the 10,240 ensemble data sets was made possible by a cross-disciplinary collaboration of data assimilation experts and eigenvalue solver scientists at RIKEN AICS. The "Local Ensemble Transform Kalman Filter" (LETKF), an already efficient system, was further improved by a factor of eight using the "EigenExa" high-performance eigenvalue solver software, making possible a three-week computation of data from the 10,240 ensembles for simulated global weather. By analyzing the 10,240 equally probable estimates of atmospheric states, the team discovered that faraway observations, even going beyond 10,000 kilometers in distance, may have an immediate impact on eventual state of the estimation. This finding suggests the need for further research on advanced methods that can make better use of faraway observations, as this could potentially lead to an improvement of weather forecasts.

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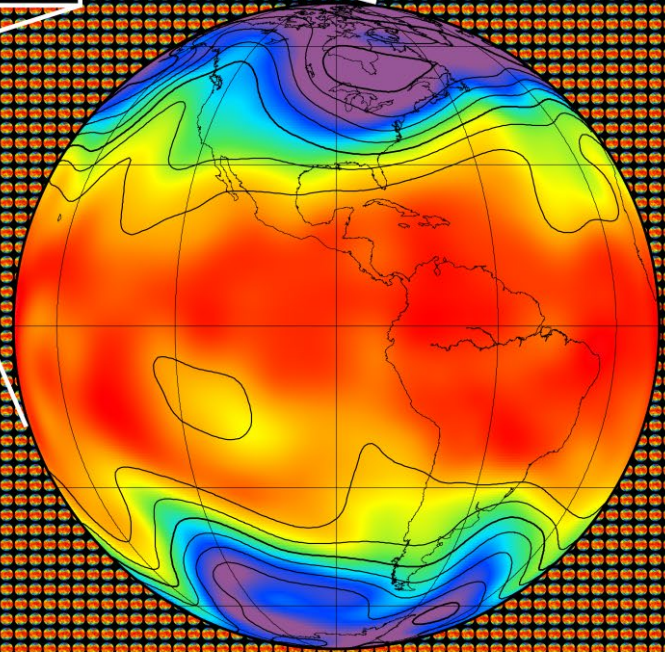
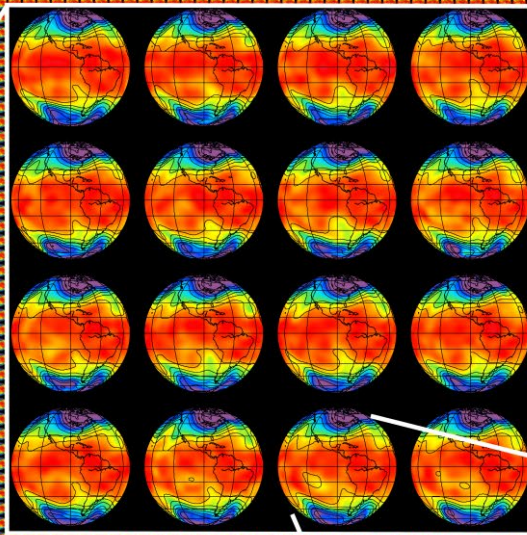
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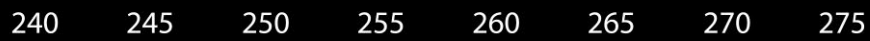
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10240 parallel earths



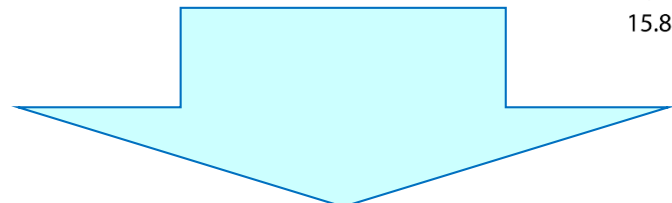
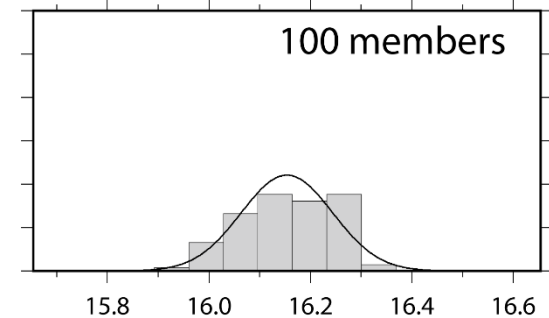
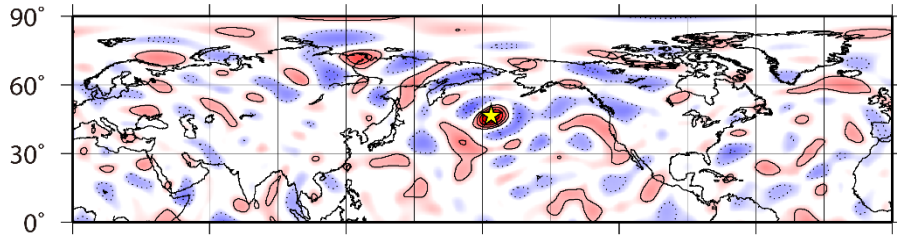
500 hPa Temperature [K]



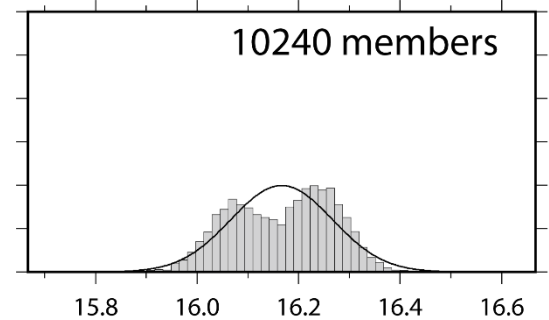
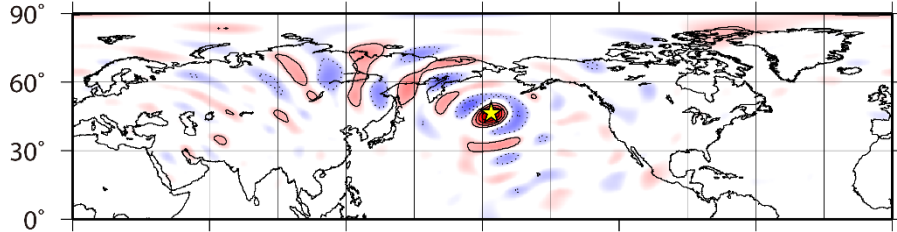
Advantage of large ensemble

(Miyoshi, Kondo, Imamura 2014)

100 members



10240 members

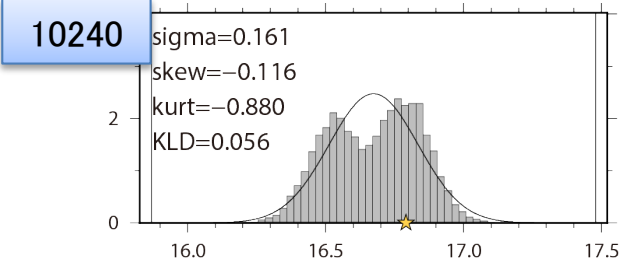
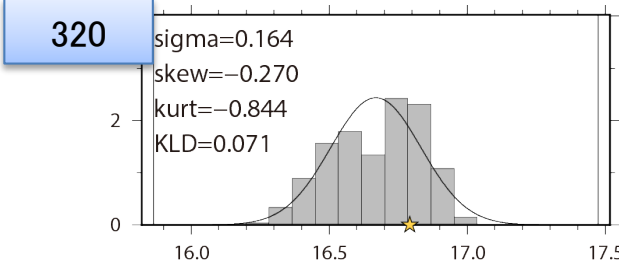
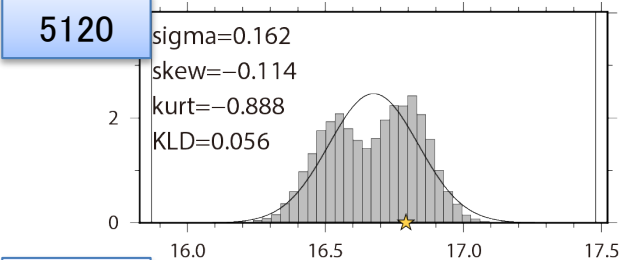
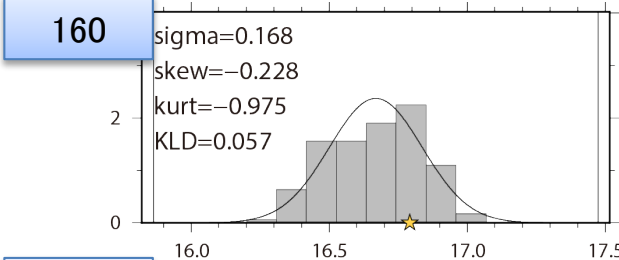
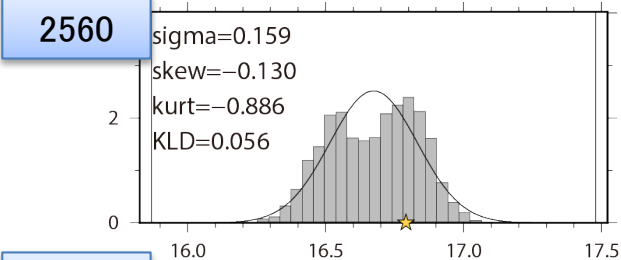
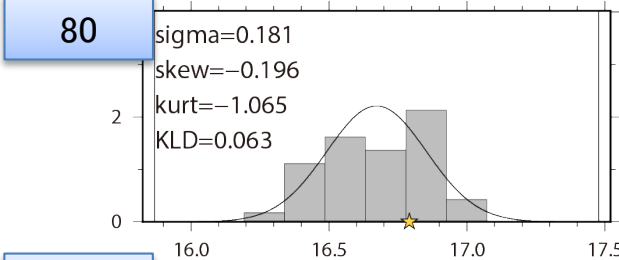
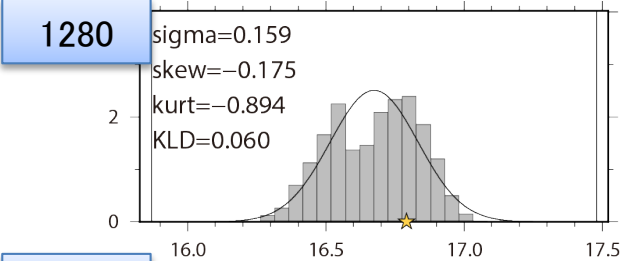
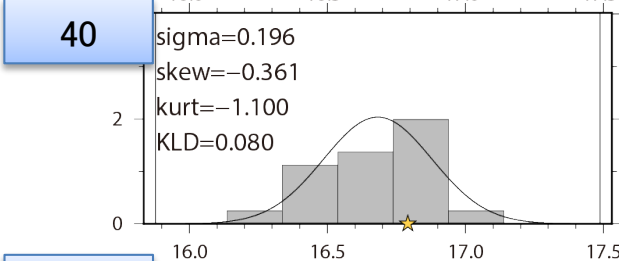
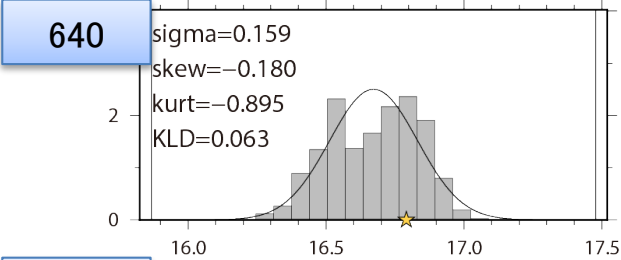
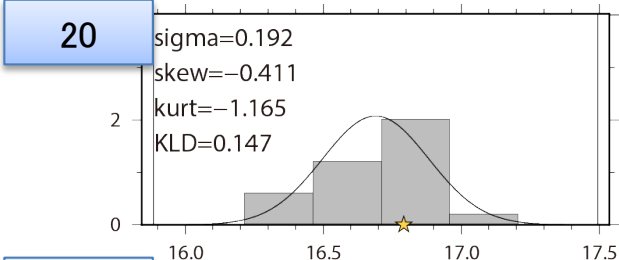


Sampling noise reduced

High-precision probabilistic representation

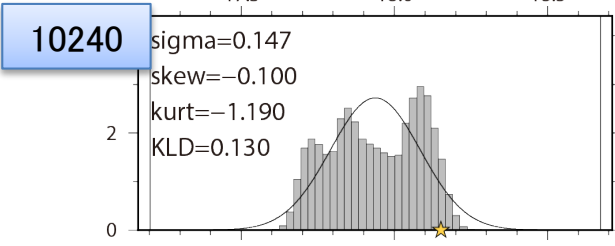
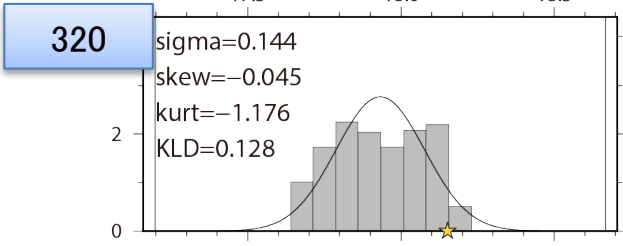
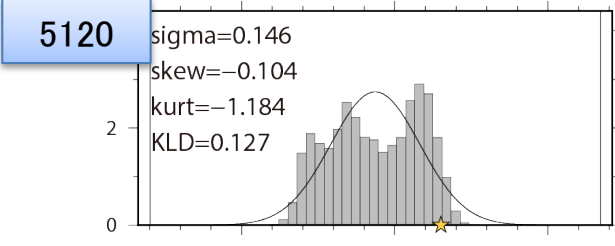
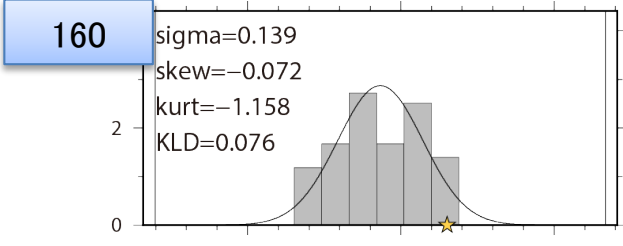
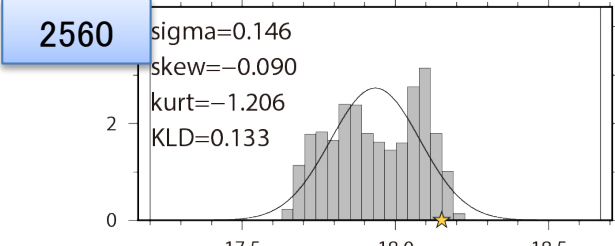
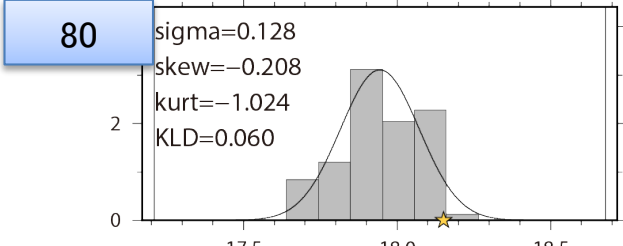
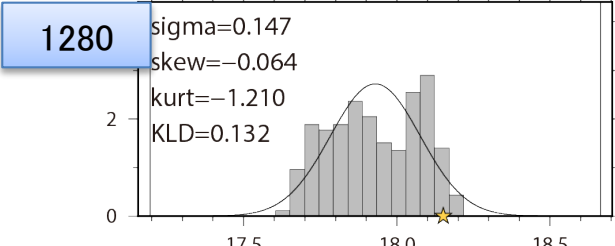
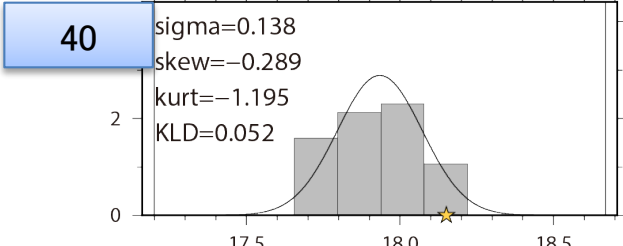
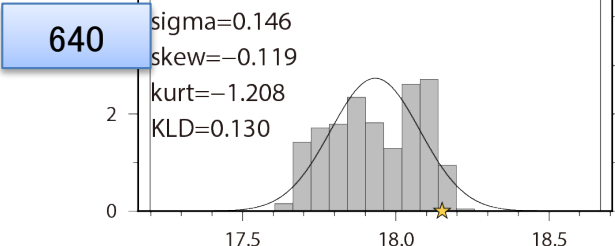
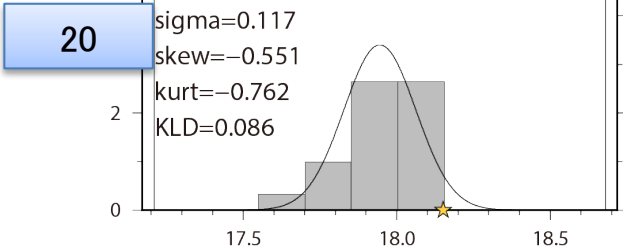
Histogram, Q, lev=1, 1982/02/01 06Z

1.856N, 120.000E

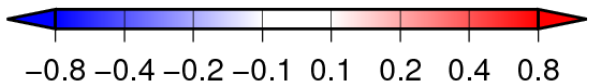
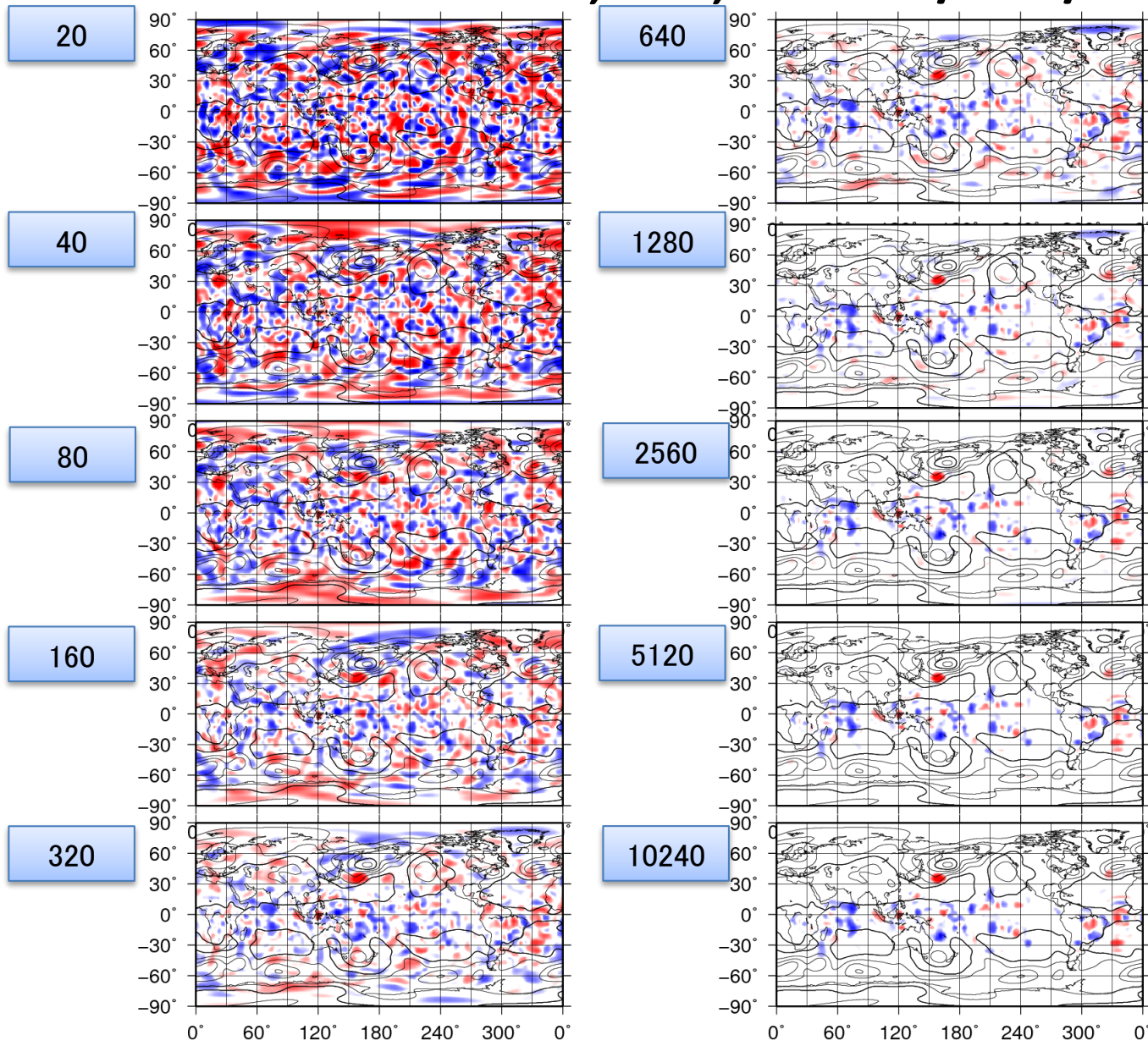


Histogram, Q, lev=1, 1982/02/01 06Z

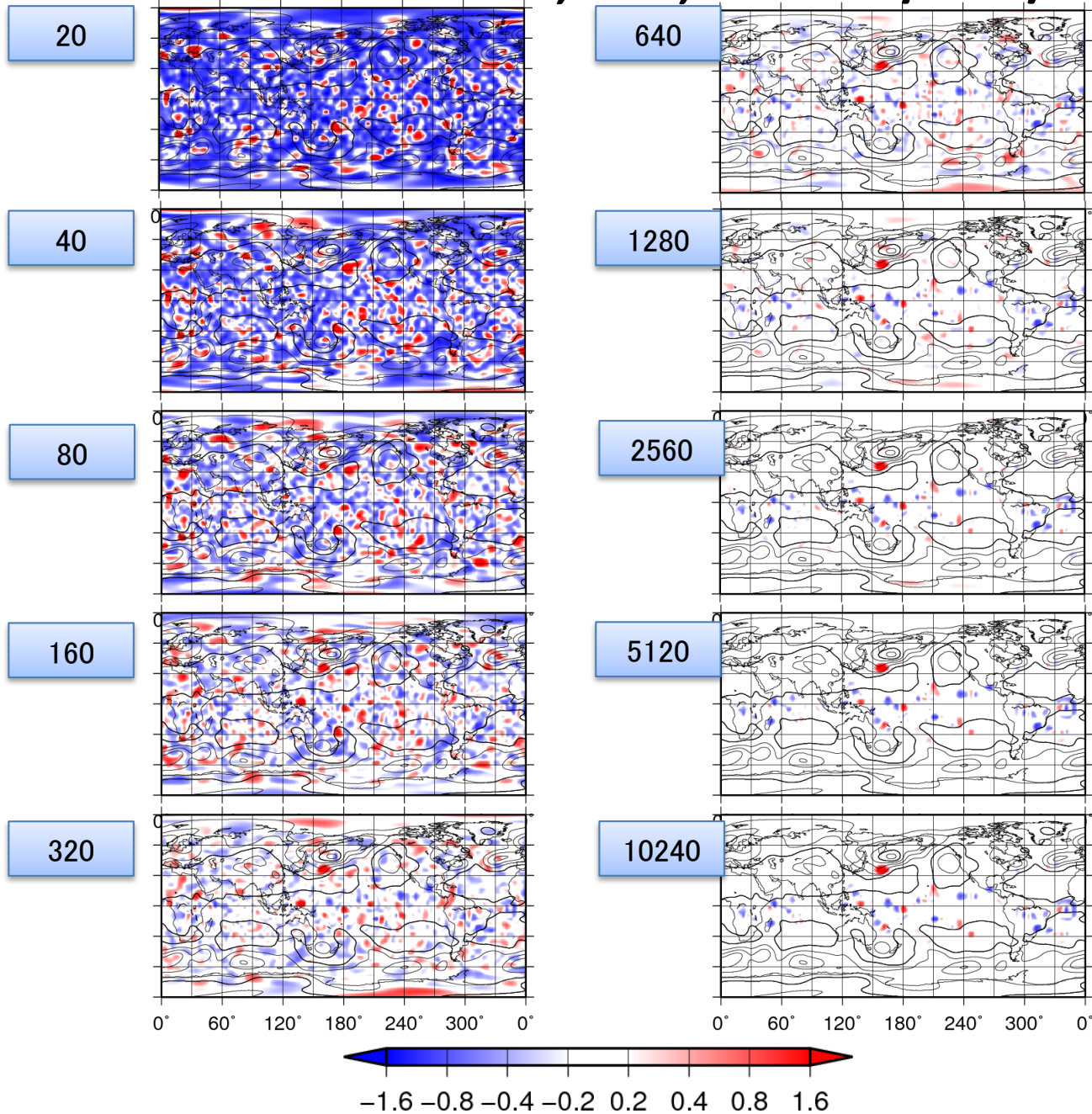
1.856N, 176.25E



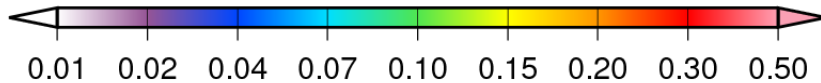
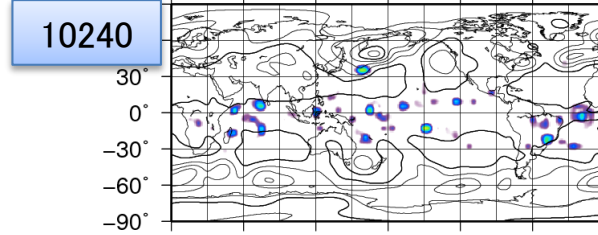
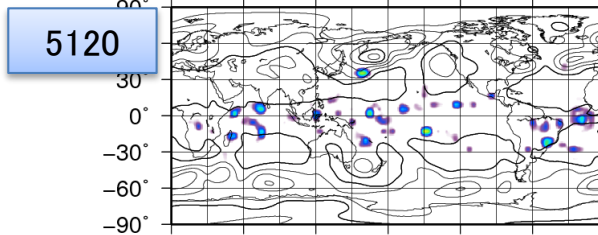
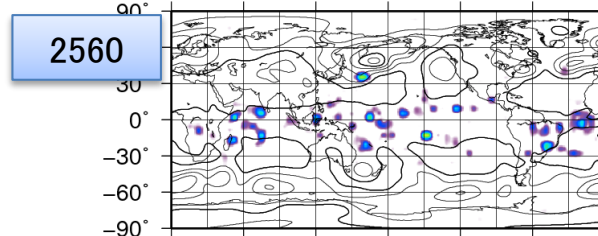
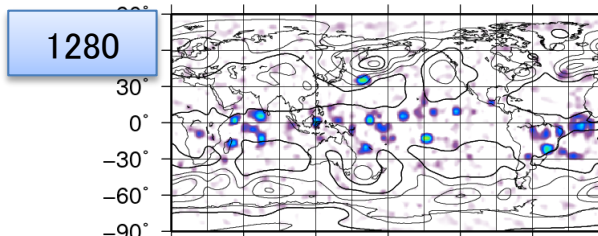
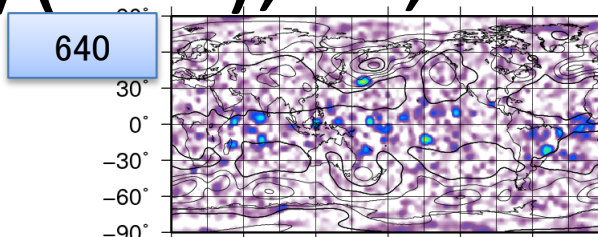
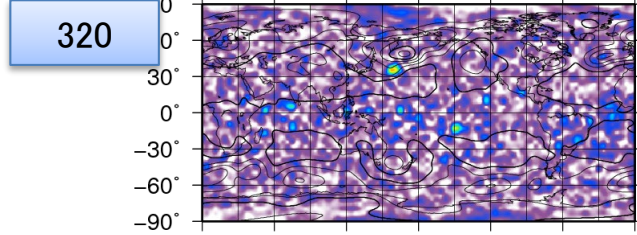
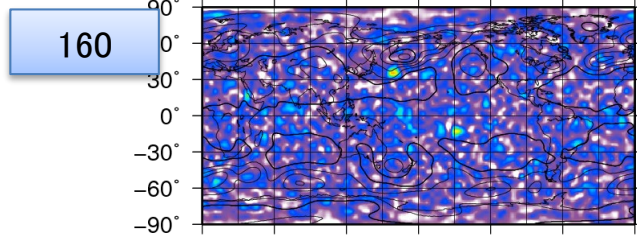
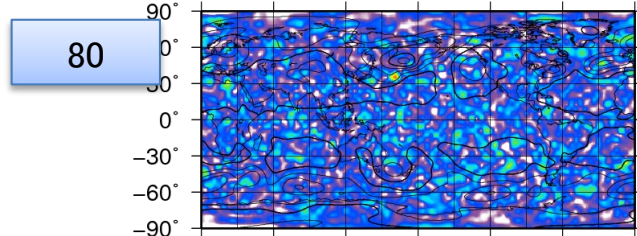
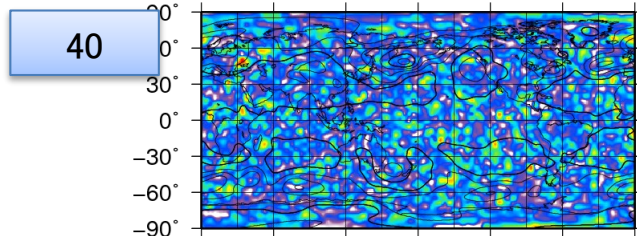
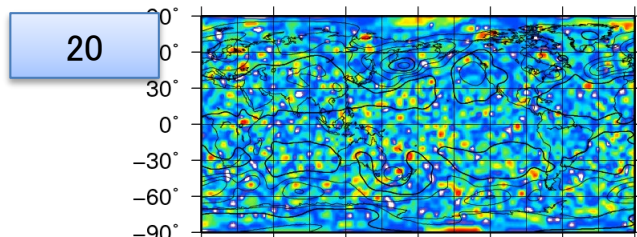
Skewness, Ps, 1982/02/01 06Z



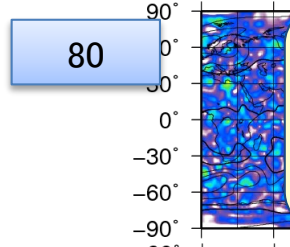
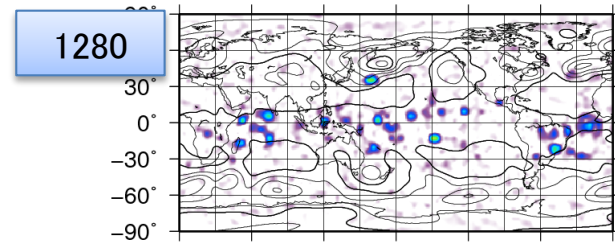
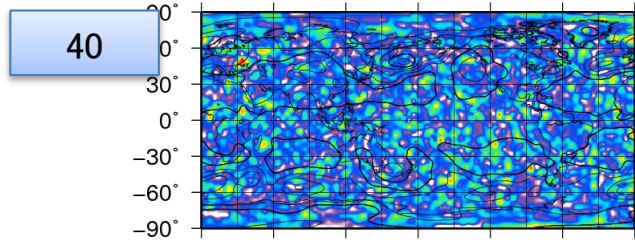
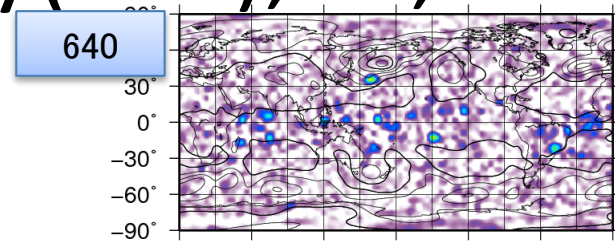
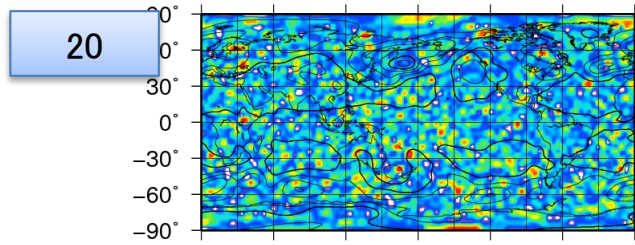
Kurtosis, Ps, 1982/02/01 06Z



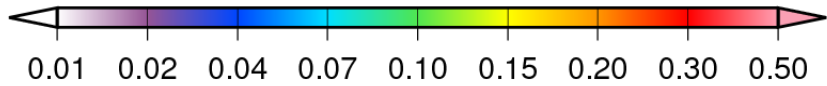
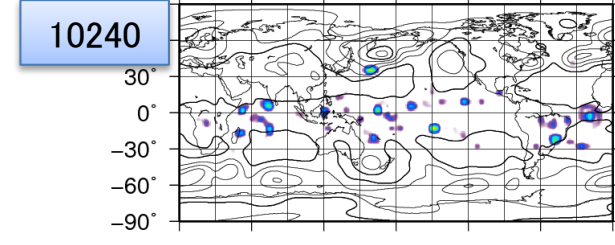
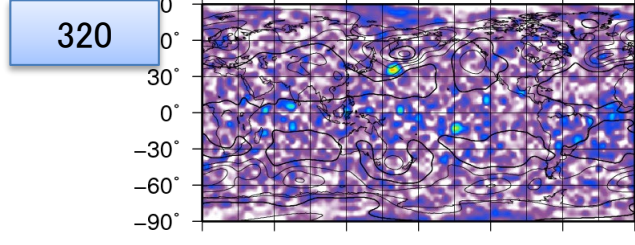
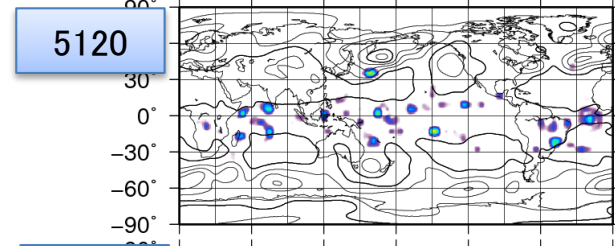
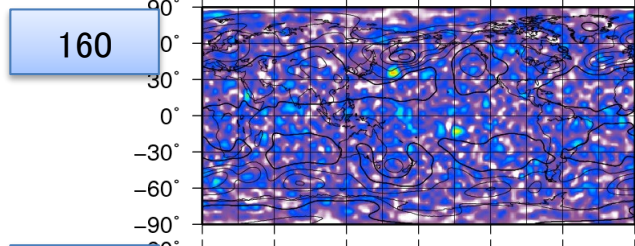
Non-Gaussianity(KLD), Ps, 1982/02/01 06Z



Non-Gaussianity(KLD), Ps, 1982/02/01 06Z

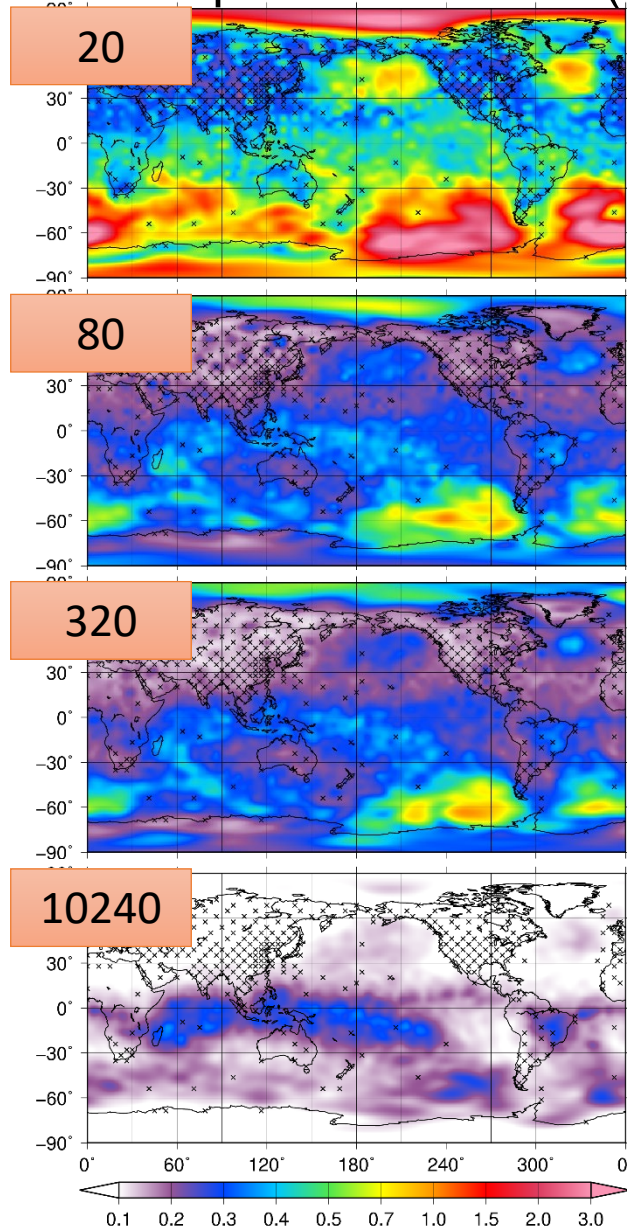


>1000 members necessary for capturing Non-Gaussianity

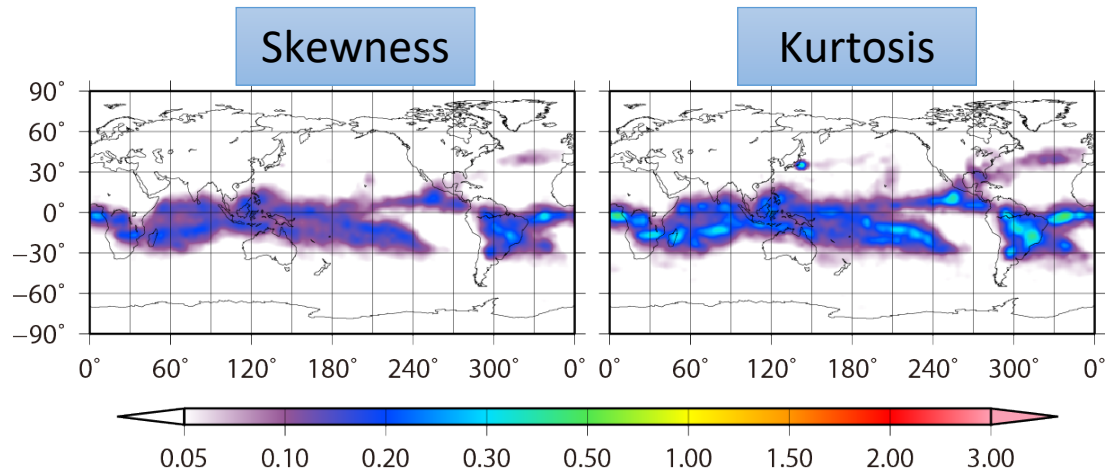


RMSE \Leftrightarrow Non-Gaussianity *(Kondo, Miyoshi 2016)*

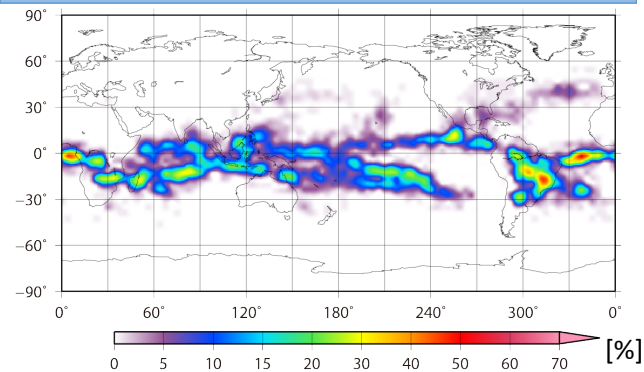
Surface-pressure RMSE (hPa)



Non-Gaussianity based on 10240 members

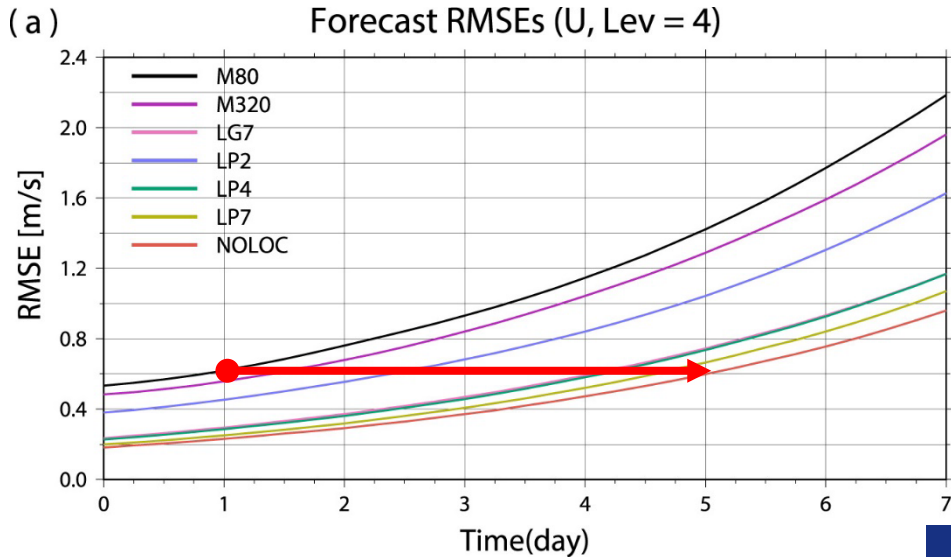


Frequency of Non-Gaussianity



Larger errors \Leftrightarrow Non-Gaussian regions

To improve data assimilation



1-day fcst error = 5-day fcst error

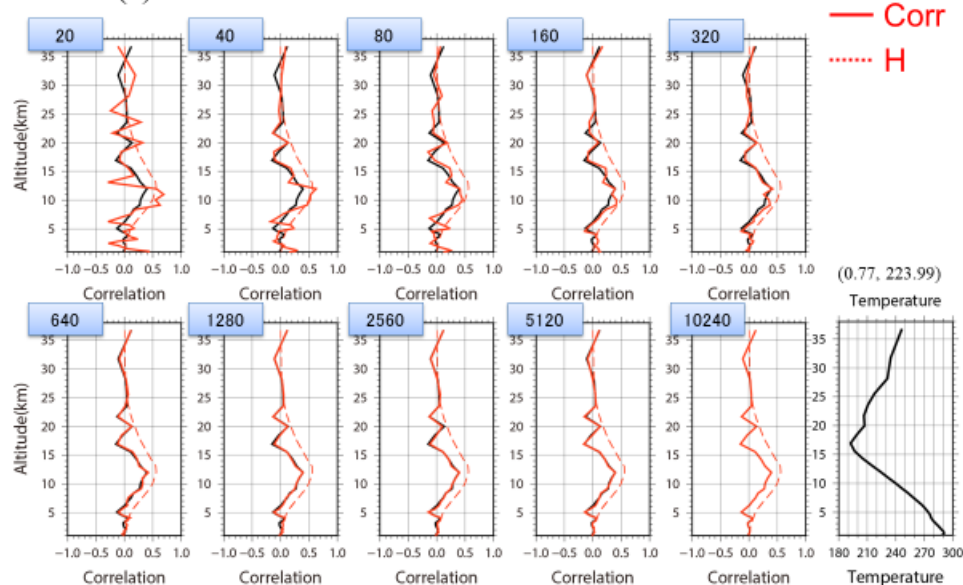
80 members

10240 members
w/o localization

Corr(x, Hx) for NOAA-18 AMSU-A Ch.7

H(x): RTTOV :: NICAM → Satellite data

(Kondo et al. 2016)



Implications to vertical
localization for satellite data

Computer

MULTIMEDIA



12

GUEST EDITOR'S INTRODUCTION
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 Exascale Supercomputing and Beyond
 VLADIMIR GETOV

Cover feature!



NOVEMBER 2015
FEATURES

15

Big Ensemble Data
 Assimilation
 in Numerical
 Weather Prediction

TAKEMASA MIYOSHI, KEIICHI KONDO,
 AND KOJI TERASAKI

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COVER FEATURE **GRAND CHALLENGES IN SCIENTIFIC COMPUTING**

Big Ensemble Data Assimilation in Numerical Weather Prediction

VIDEO

Takemasa Miyoshi, RIKEN Advanced Institute for Computational Science,
 University of Maryland, and Japan Agency for Marine-Earth Science and Technology
Keiichi Kondo and Koji Terasaki, RIKEN Advanced Institute for Computational Science

Powerful computers and advanced sensors enable precise simulations of the atmospheric state, requiring data assimilation to connect simulations to real-world sensor data using statistical mathematics and dynamical systems theory. Numerical weather prediction (NWP) thus enables simulations that more closely represent the real world. The authors explore the NWP-associated challenges in managing big data through supercomputing.

High-performance computing (HPC) is essential for numerical weather prediction (NWP), the method by which computer models of the atmosphere are used to predict the weather. Advances in computing power enable higher resolution and more complex physical representations of the atmosphere. Although these more advanced representations have led to more accurate weather forecasts from supercomputers than the first models from 1950, the technology is still far from ideal.¹

In NWP, synchronizing the computer simulation with the real world is essential to accurately determine

the atmosphere's current state and likely evolution. Although more precise simulations and more powerful computing are helpful in improving accuracy, data assimilation (DA) plays a key role in improving integration between the computer simulation and real-world observation data.^{2,3} DA also employs HPC; in fact, global NWP systems devote equivalent computational resources to DA and 10-day forecast simulation.

To accurately represent the probability density function (PDF) in the ensemble Kalman filter (EnKF)—an advanced DA approach widely used in NWP—within the global atmosphere, we used a large sample size and the



Pushing the limits

Big Data × *Big Simulations*

Big ensemble (10240 ensemble members)

Rapid update (30-second update)

High resolution (100-m mesh)

→ Future NWP



Pushing the limits

Big Data × *Big Simulations*

Big ensemble (10240 ensemble members)

Rapid update (30-second update)

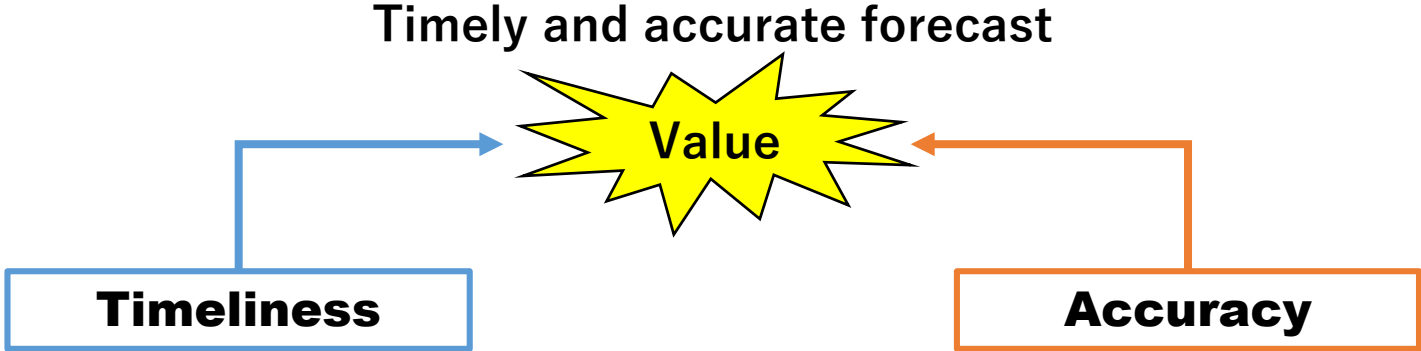
High resolution (100-m mesh)

→ Future NWP

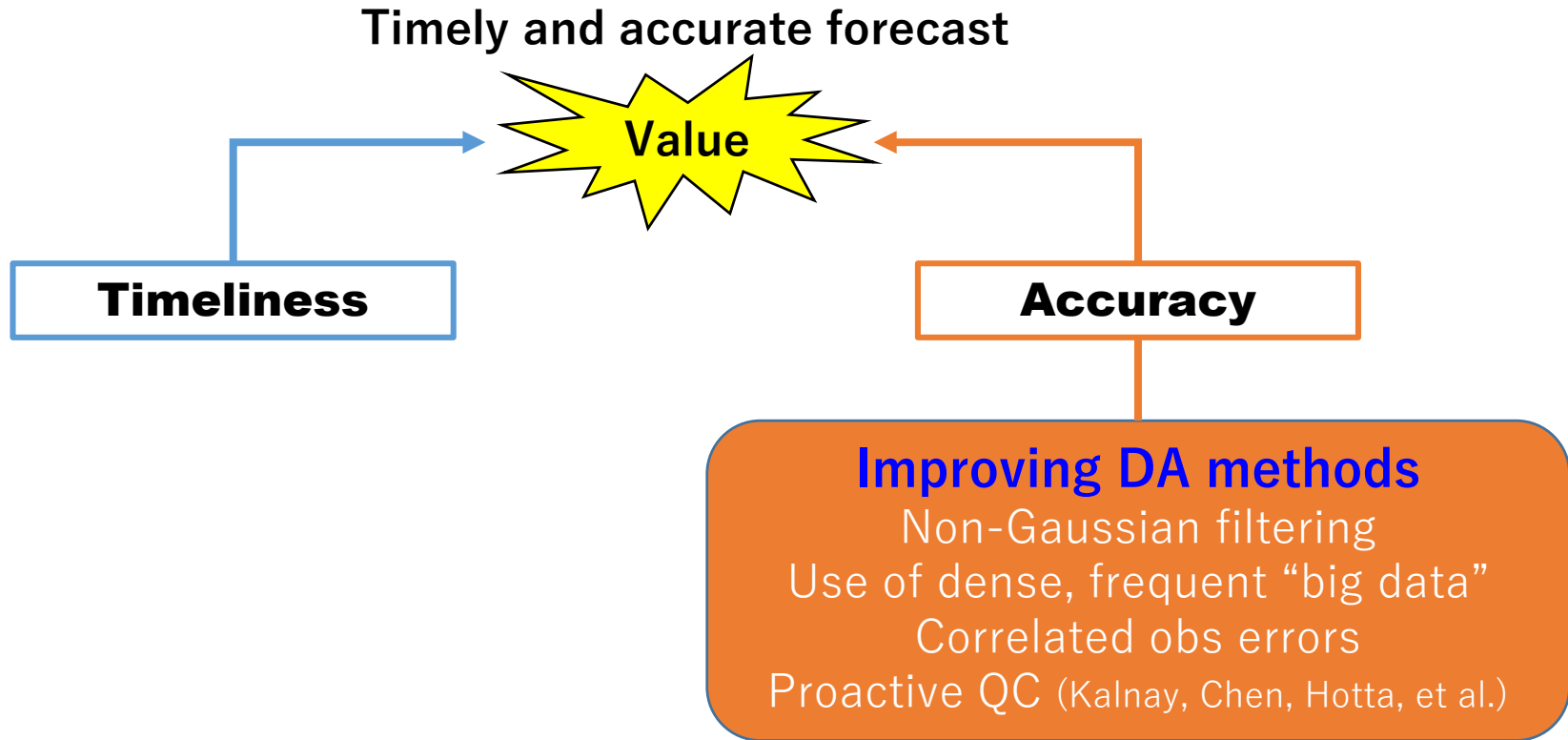
With new **“Fugaku”**, we will run a
3.5-km-mesh global LETKF w/ 1000 members.



Research directions

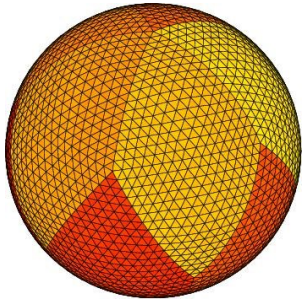


Research directions

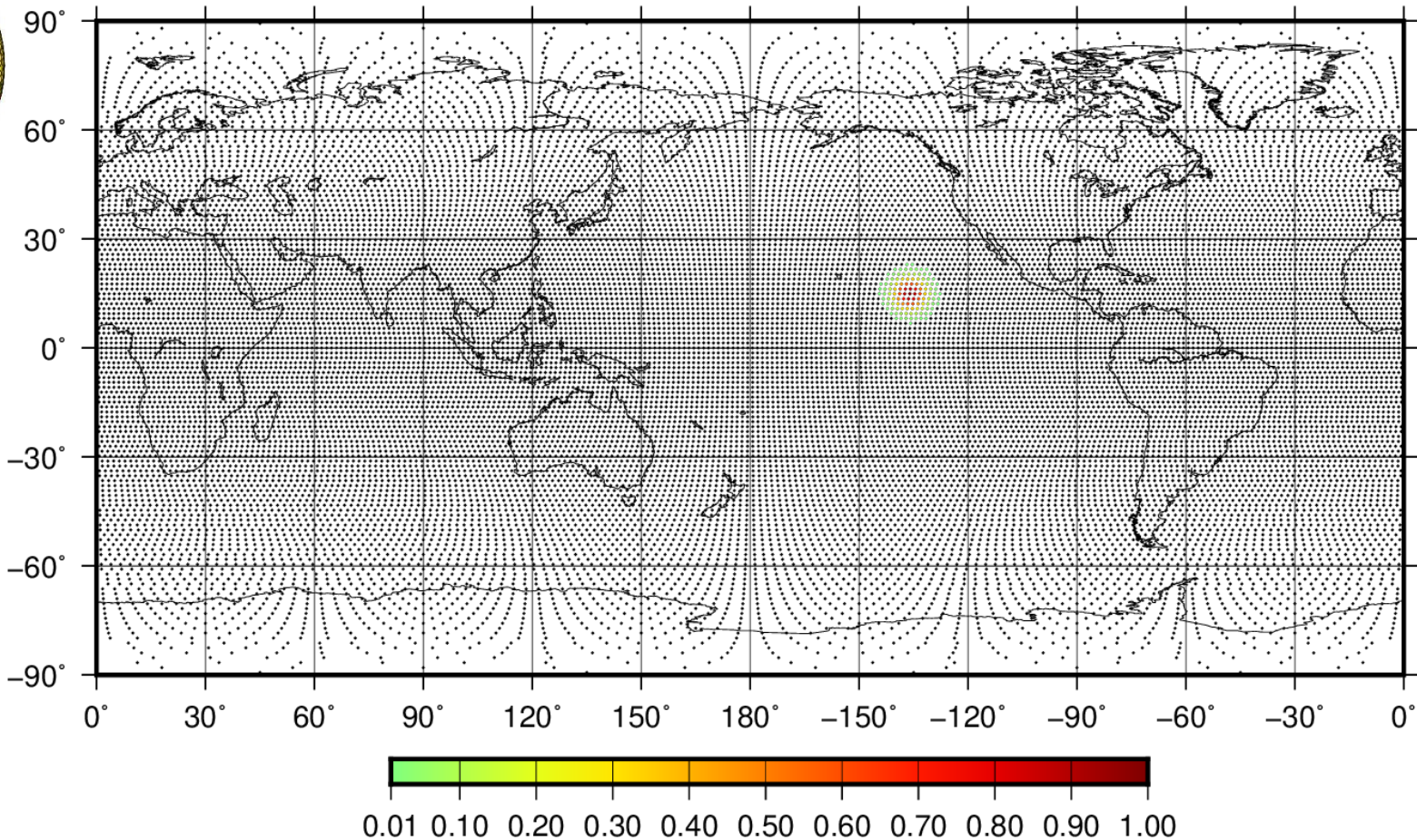


OSSE with Full-R

NICAM-LETKF
system

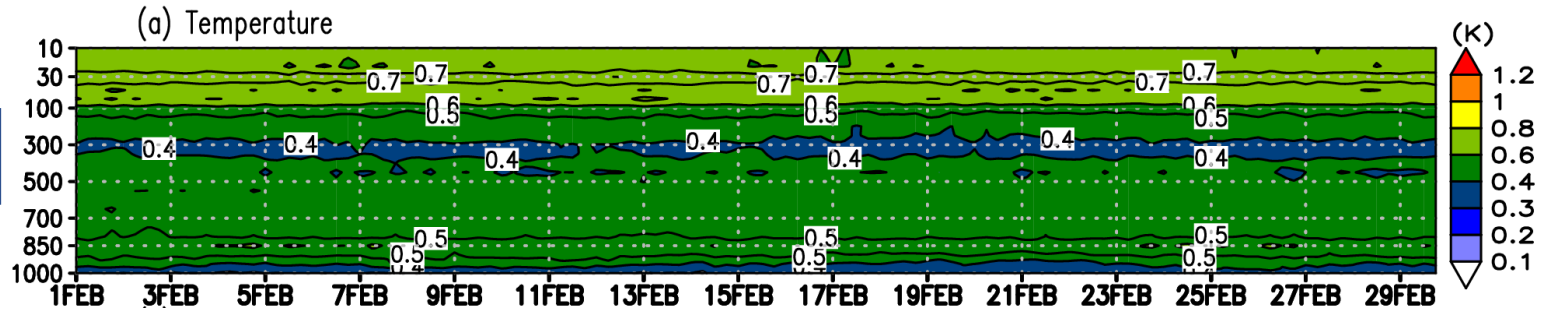


Observation coverage ($\Delta x=150\text{km}$) &
observation error correlation for an observation

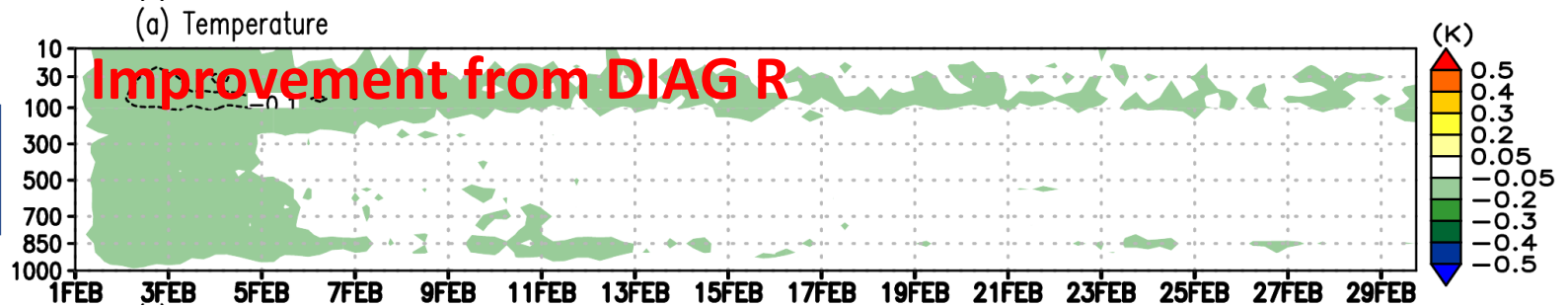


Results: Temperature RMSE (K)

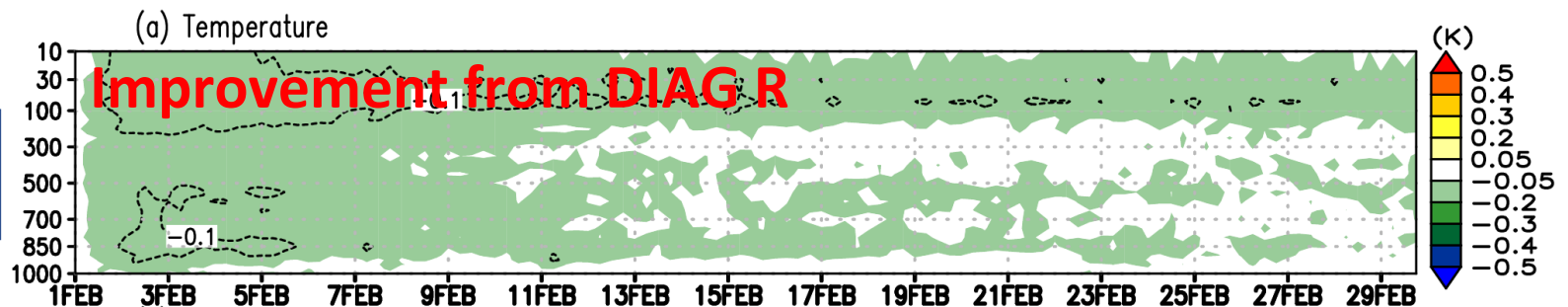
DIAG R



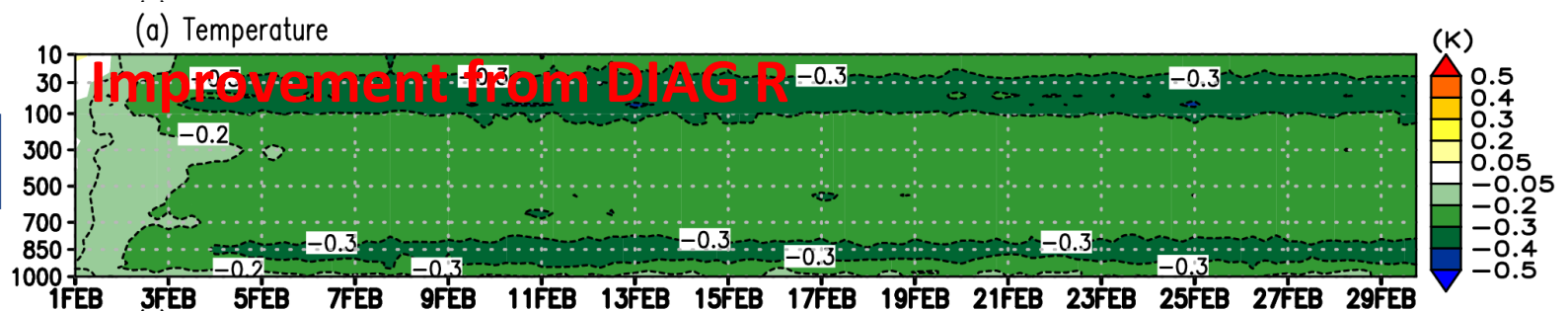
DIAG
R*2.25



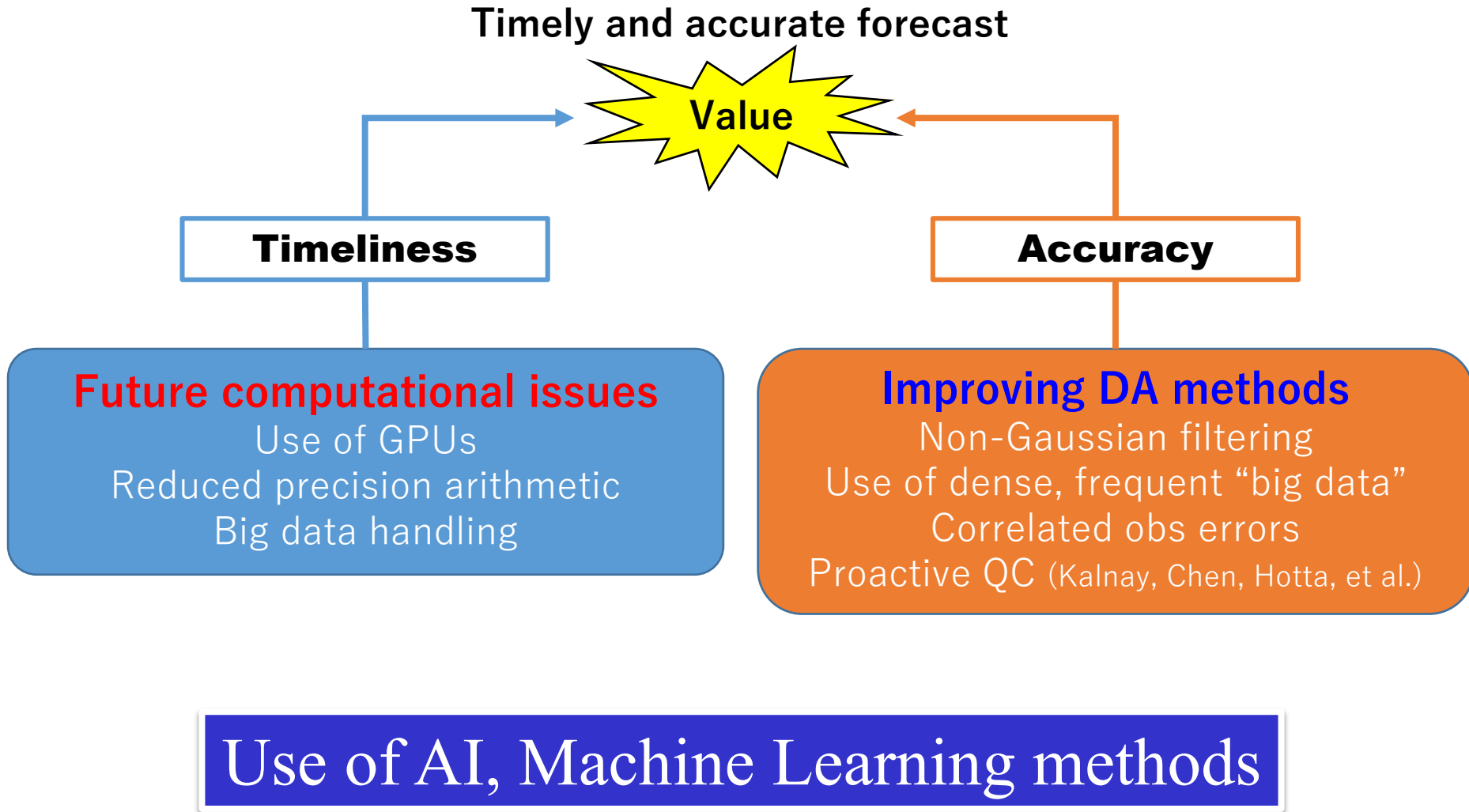
DIAG R w/
THINNING



FULL R



Research directions





RESEARCH ARTICLE

10.1029/2018MS001341

Key Points:

- Lowering precision could accelerate an ensemble Kalman filter
- The level of precision used should fit the level of model error
- We perform tests with a spectral dynamical core

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samuel.hatfield@physics.ox.ac.uk

Citation:

Hatfield, S. E., Düben, P. D., Chantry, M., Kondo, K., Miyoshi, T., & Palmer, T. N. (2018). Choosing the optimal numerical precision for data assimilation in the presence of model error. *Journal of Advances in Modeling Earth Systems*, 10, 2177–2191. <https://doi.org/10.1029/2018MS001341>

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Choosing the Optimal Numerical Precision for Data Assimilation in the Presence of Model Error

Sam Hatfield¹ , Peter Düben² , Matthew Chantry¹ , Keiichi Kondo³, Takemasa Miyoshi⁴ , and Tim Palmer¹ 

¹Atmospheric, Oceanic and Planetary Physics, University of Oxford, Oxford, UK, ²European Centre for Medium Range Weather Forecasts, Reading, UK, ³Japan Meteorological Agency, Meteorological Research Institute, Tsukuba, Japan, ⁴RIKEN Center for Computational Science, Kobe, Japan

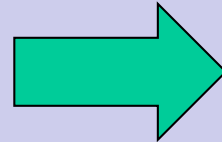
Abstract The use of reduced numerical precision within an atmospheric data assimilation system is investigated. An atmospheric model with a spectral dynamical core is used to generate synthetic observations, which are then assimilated back into the same model using an ensemble Kalman filter. The effect on the analysis error of reducing precision from 64 bits to only 22 bits is measured and found to depend strongly on the degree of model uncertainty within the system. When the model used to generate the observations is identical to the model used to assimilate observations, the reduced-precision results suffer substantially. However, when model error is introduced by changing the diffusion scheme in the assimilation model or by using a higher-resolution model to generate observations, the difference in analysis quality between the two levels of precision is almost eliminated. Lower-precision arithmetic has a lower computational cost, so lowering precision could free up computational resources in operational data assimilation and allow an increase in ensemble size or grid resolution.

Plain Language Summary In order to produce a weather forecast, we must have a good estimate of the current state of the atmosphere. We can observe the atmosphere using satellites and other

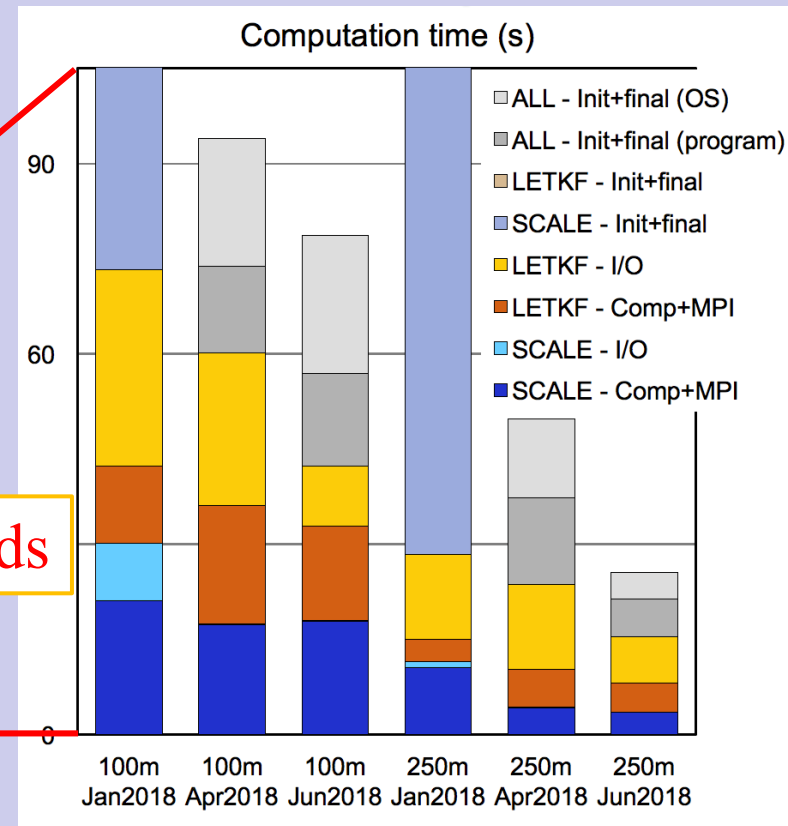
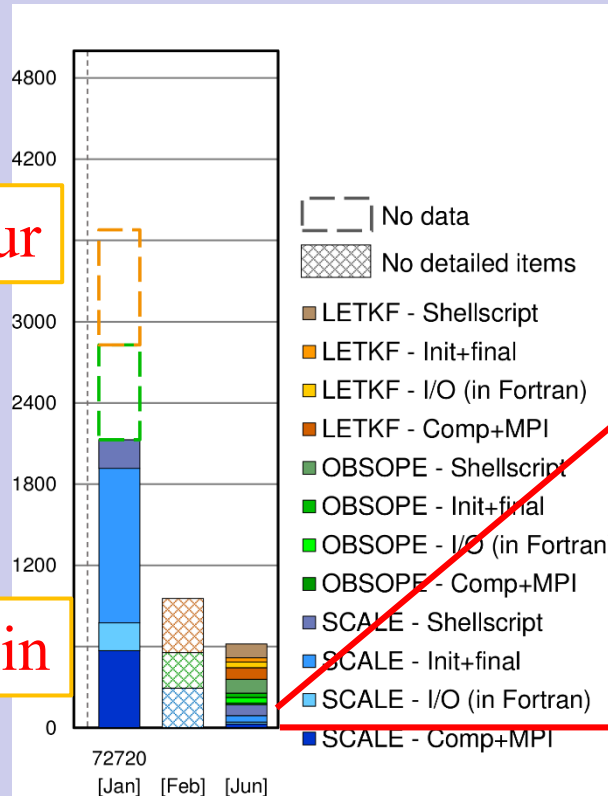
Compute time (73440 nodes of K computer)

ensemble forecasts + data assimilation

2016 results reported
in mid-term evaluation



2018 results

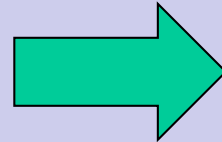


100 m / 250 m

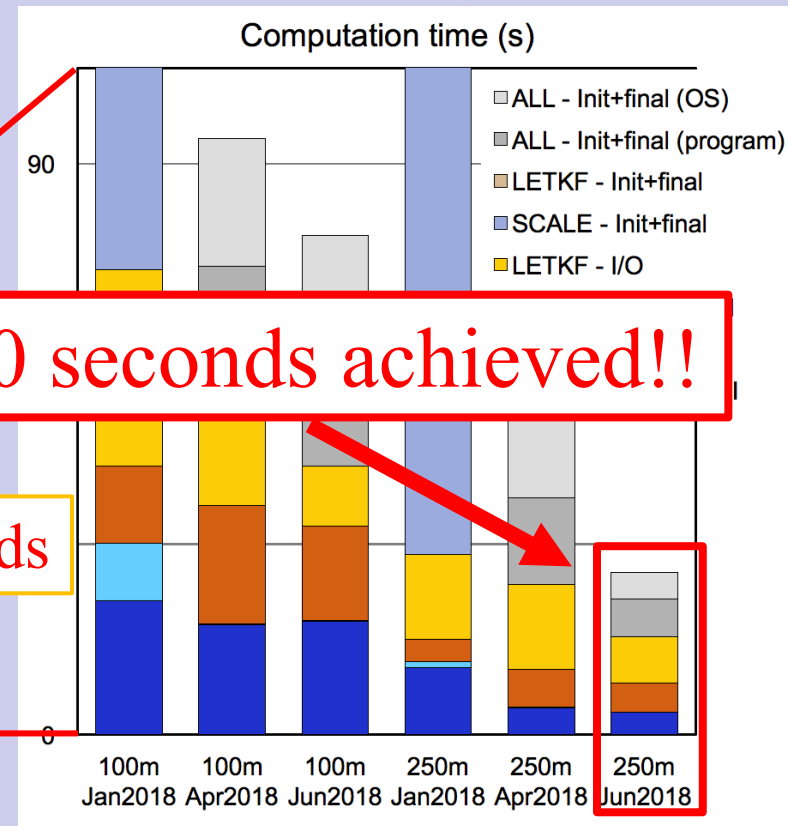
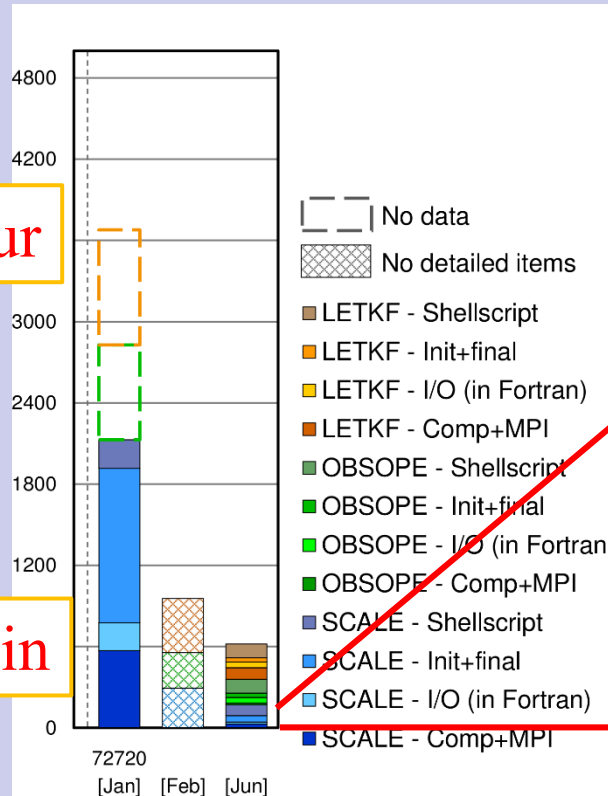
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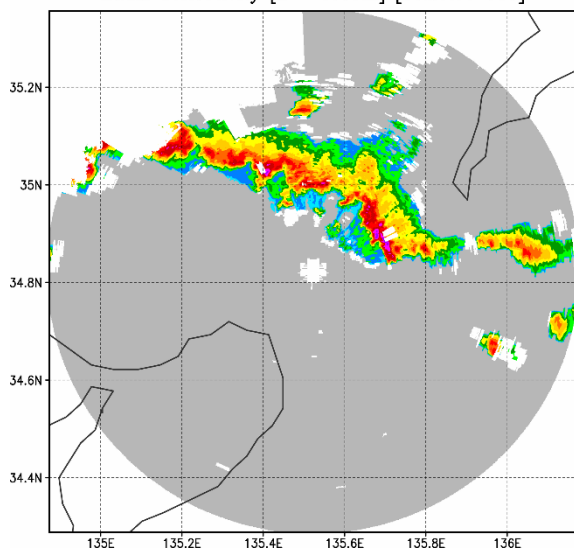


250-m mesh vs. 100-m mesh forecasts

Analysis - 06:20 UTC 13 July, 2013

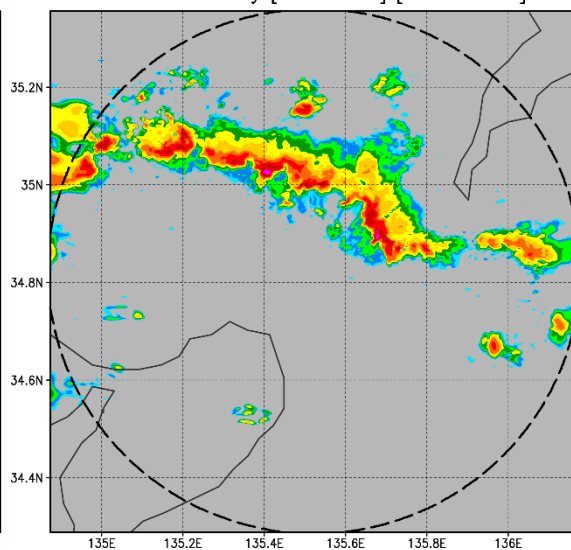
Observation

Radar reflectivity [Z = 3068m] [06:20:00 UTC]



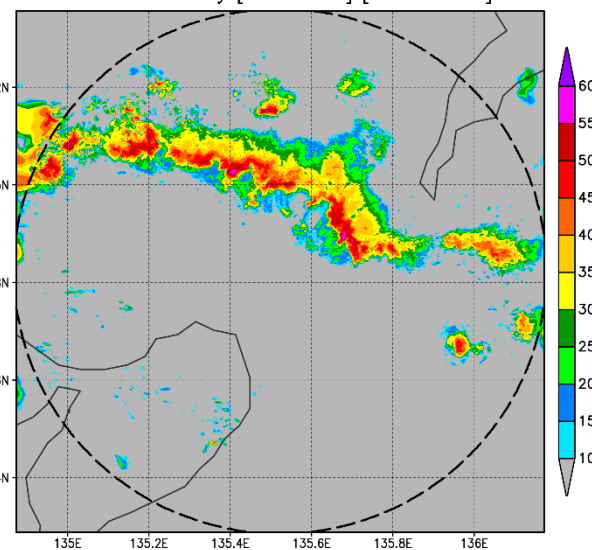
250 M

Radar reflectivity [Z = 3068m] [06:20:00 UTC]



100 M

Radar reflectivity [Z = 3068m] [06:20:00 UTC]

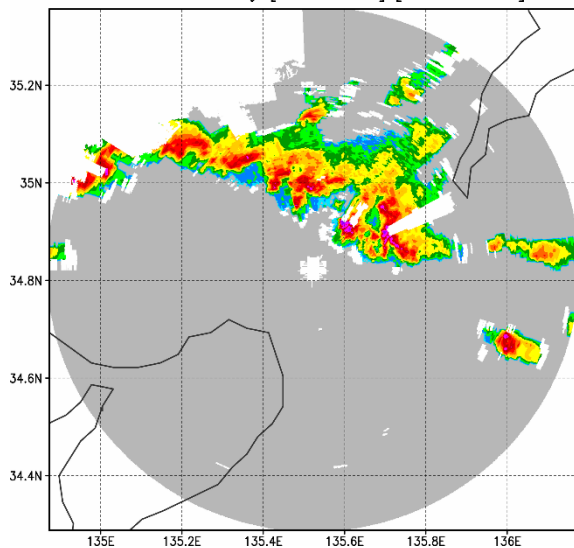


250-m mesh vs. 100-m mesh forecasts

5-min forecast - 06:25 UTC 13 July, 2013

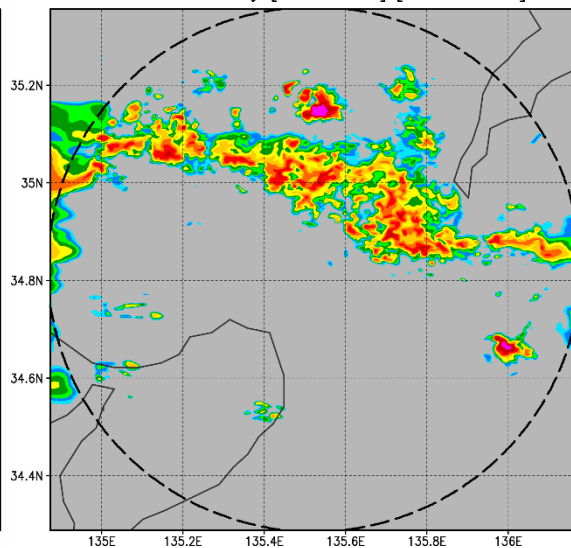
Observation

Radar reflectivity [Z = 3068m] [06:25:00 UTC]



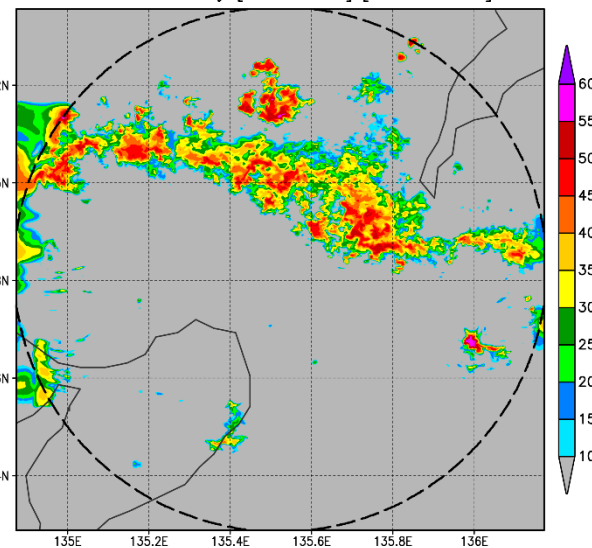
250 M

Radar reflectivity [Z = 3068m] [06:25:00 UTC]



100 M

Radar reflectivity [Z = 3068m] [06:25:00 UTC]

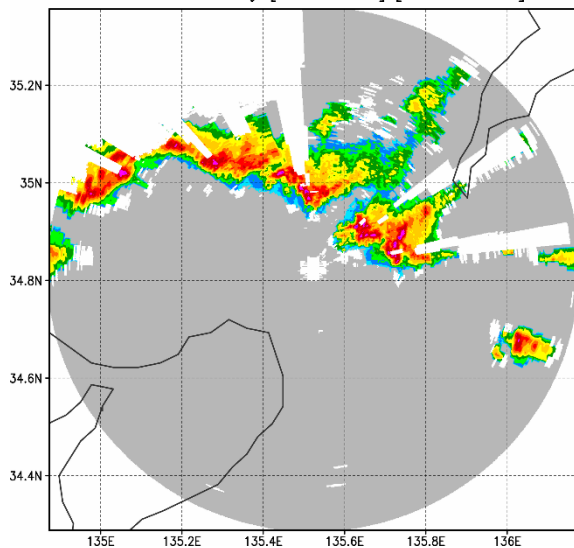


250-m mesh vs. 100-m mesh forecasts

10-min forecast - 06:30 UTC 13 July, 2013

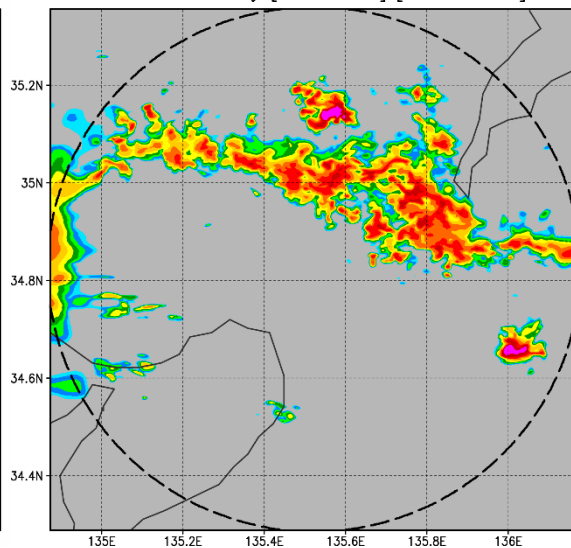
Observation

Radar reflectivity [Z = 3068m] [06:30:00 UTC]



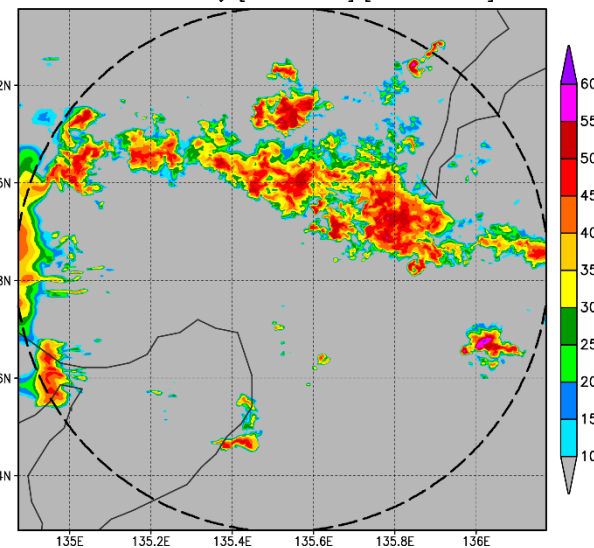
250 M

Radar reflectivity [Z = 3068m] [06:30:00 UTC]



100 M

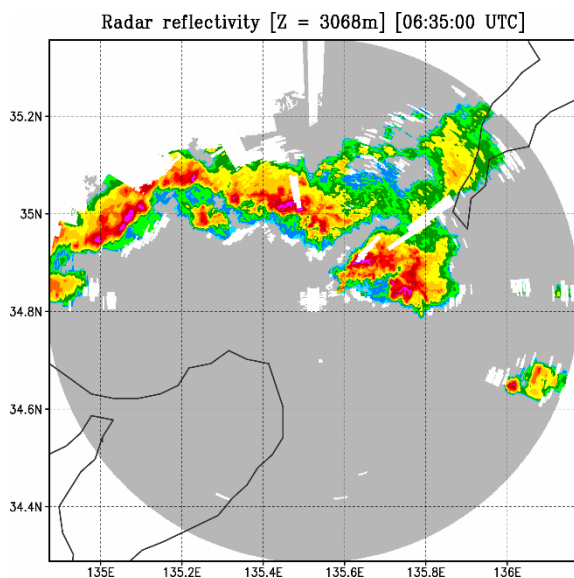
Radar reflectivity [Z = 3068m] [06:30:00 UTC]



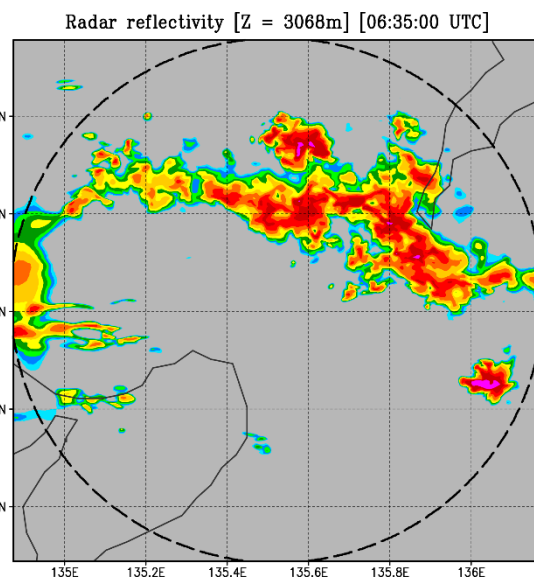
250-m mesh vs. 100-m mesh forecasts

15-min forecast - 06:35 UTC 13 July, 2013

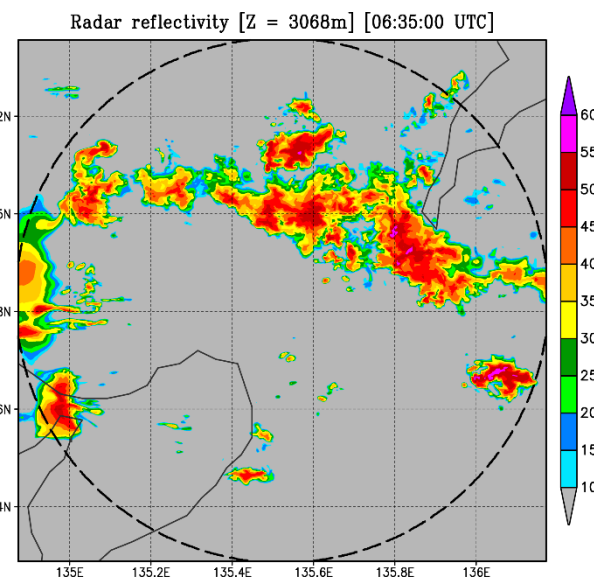
Observation



250 M



100 M

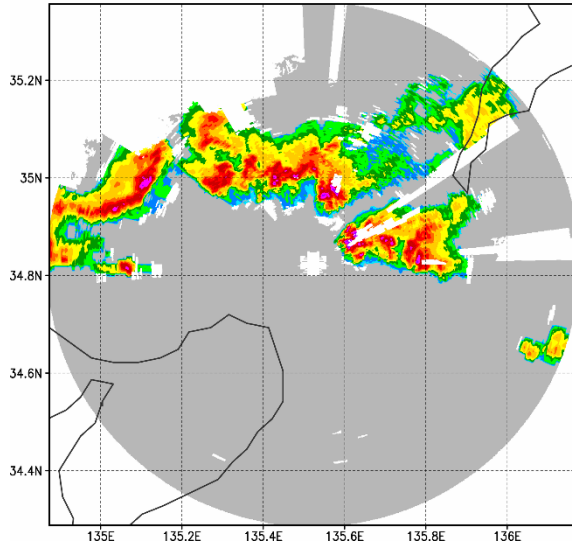


250-m mesh vs. 100-m mesh forecasts

20-min forecast - 06:40 UTC 13 July, 2013

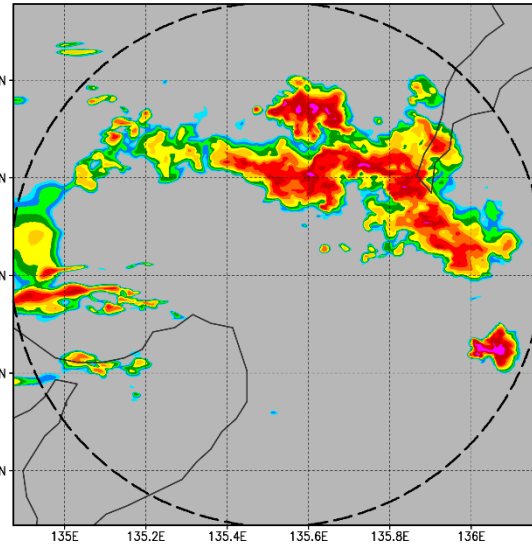
Observation

Radar reflectivity [Z = 3068m] [06:40:00 UTC]



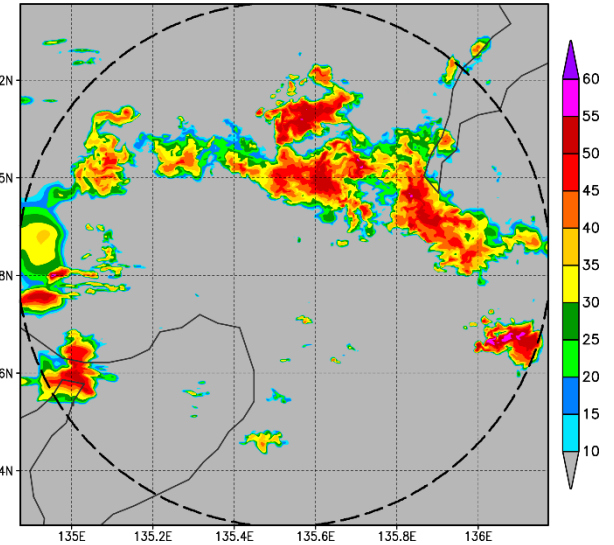
250 M

Radar reflectivity [Z = 3068m] [06:40:00 UTC]



100 M

Radar reflectivity [Z = 3068m] [06:40:00 UTC]

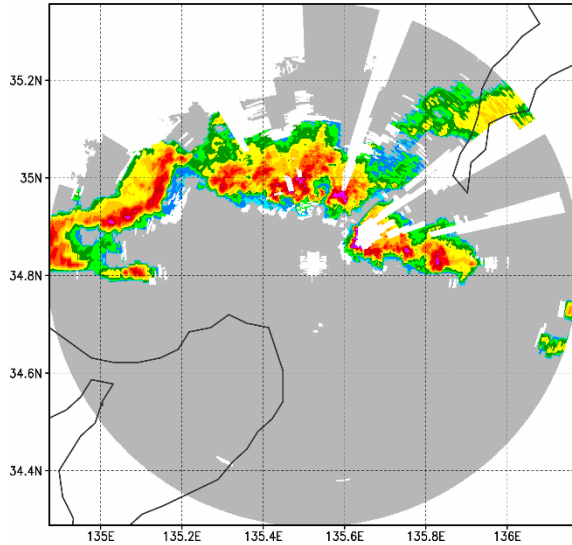


250-m mesh vs. 100-m mesh forecasts

25-min forecast - 06:45 UTC 13 July, 2013

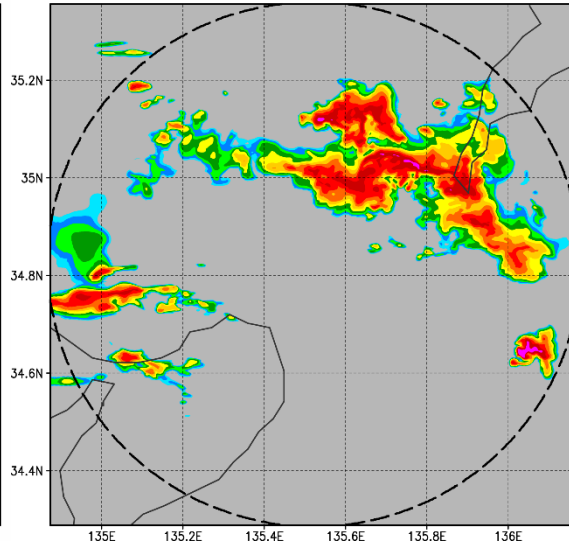
Observation

Radar reflectivity [Z = 3068m] [06:45:00 UTC]



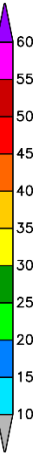
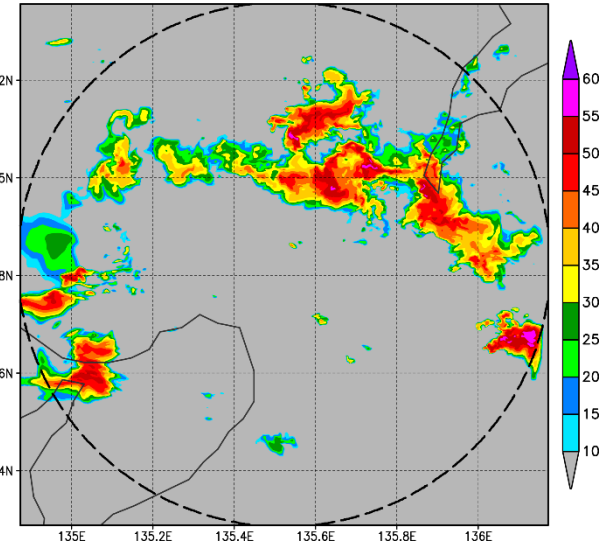
250 M

Radar reflectivity [Z = 3068m] [06:45:00 UTC]



100 M

Radar reflectivity [Z = 3068m] [06:45:00 UTC]

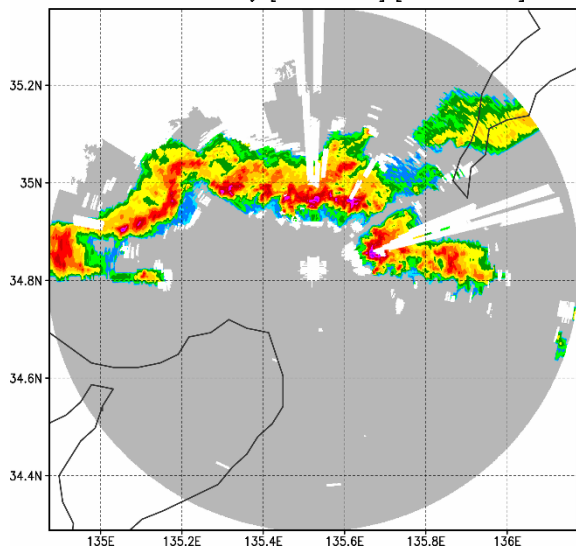


250-m mesh vs. 100-m mesh forecasts

30-min forecast - 06:50 UTC 13 July, 2013

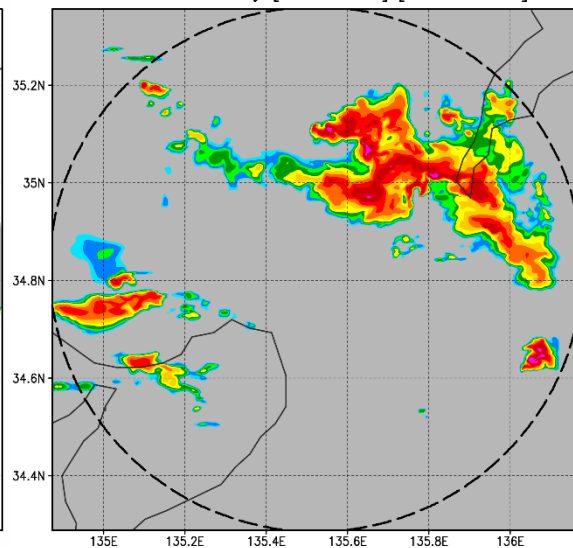
Observation

Radar reflectivity [Z = 3068m] [06:50:00 UTC]



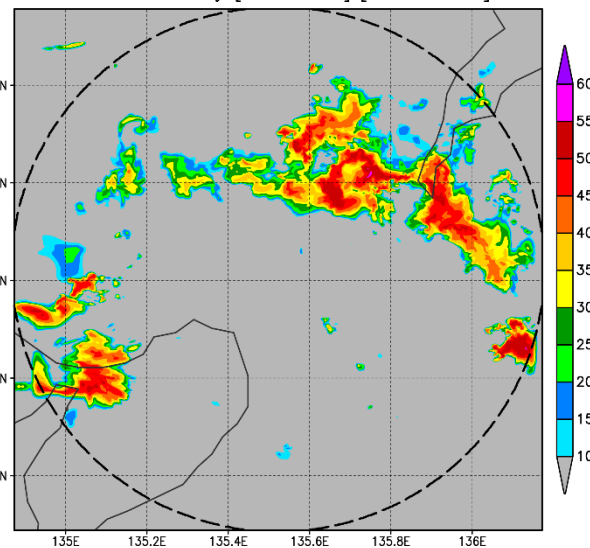
250 M

Radar reflectivity [Z = 3068m] [06:50:00 UTC]



100 M

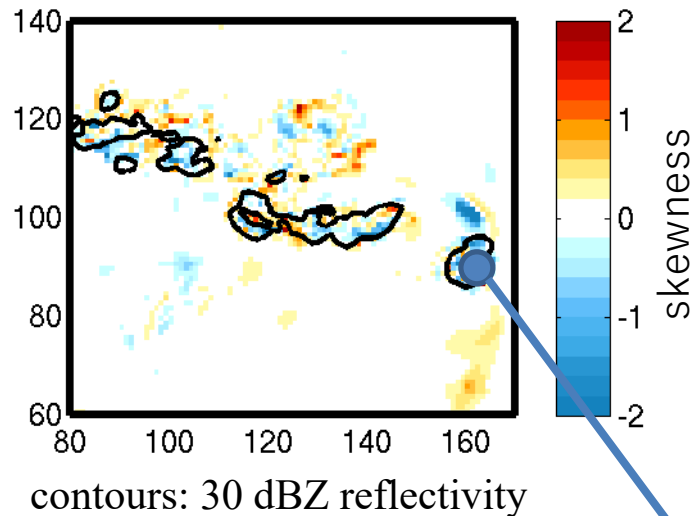
Radar reflectivity [Z = 3068m] [06:50:00 UTC]



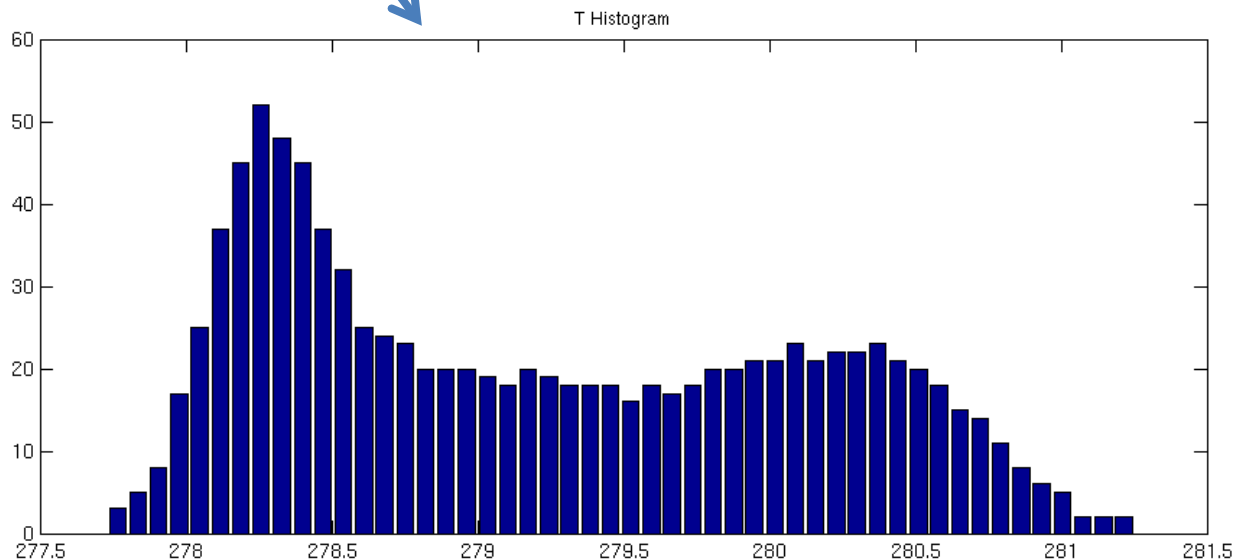
1-km-mesh, 1000-member LETKF

T skewness at z=3845 m

(Ruiz et al. in prep.)



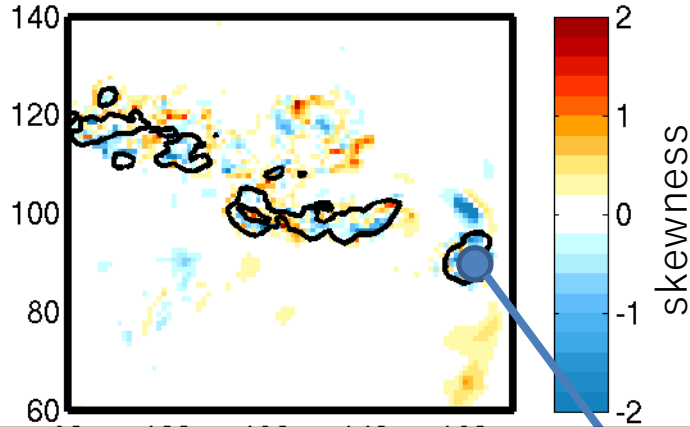
Even 30-second update shows strong non-Gaussianity with 1000 members.



1-km-mesh, 1000-member LETKF

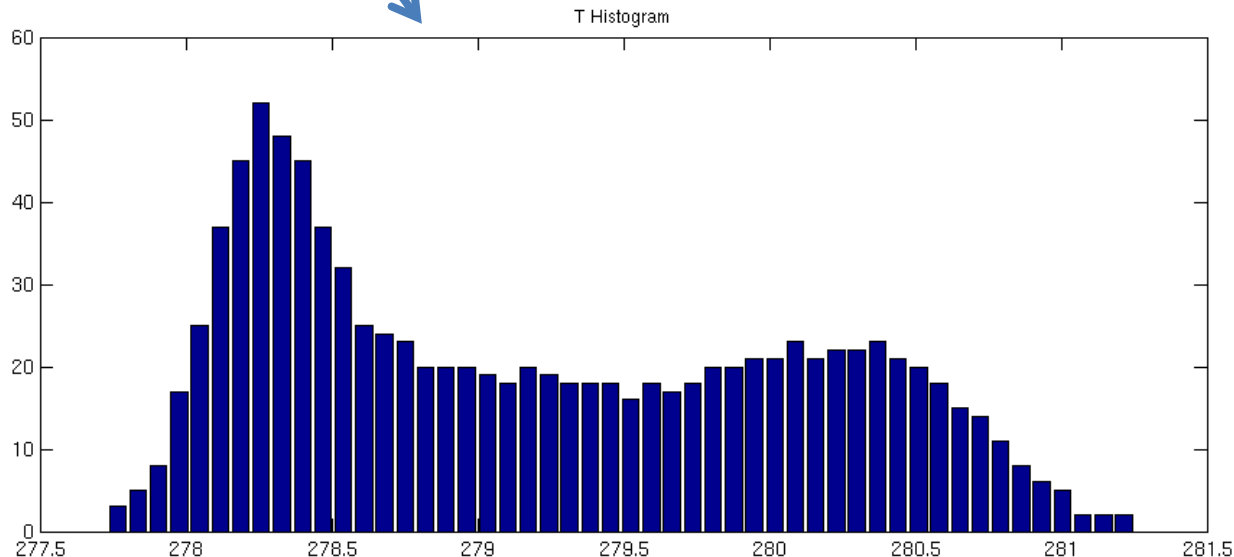
T skewness at z=3845 m

(Ruiz et al. in prep.)



Even 30-second update shows strong non-Gaussianity with 1000 members.

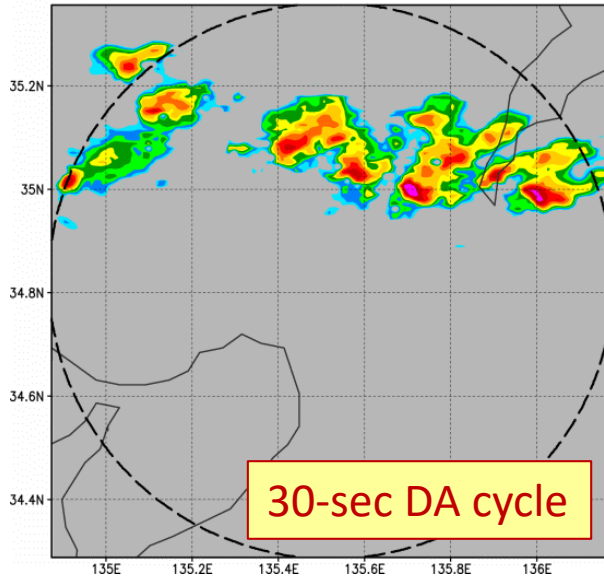
30-sec. update may not be fast enough!



30-min forecast: 15:10L – 15:40L

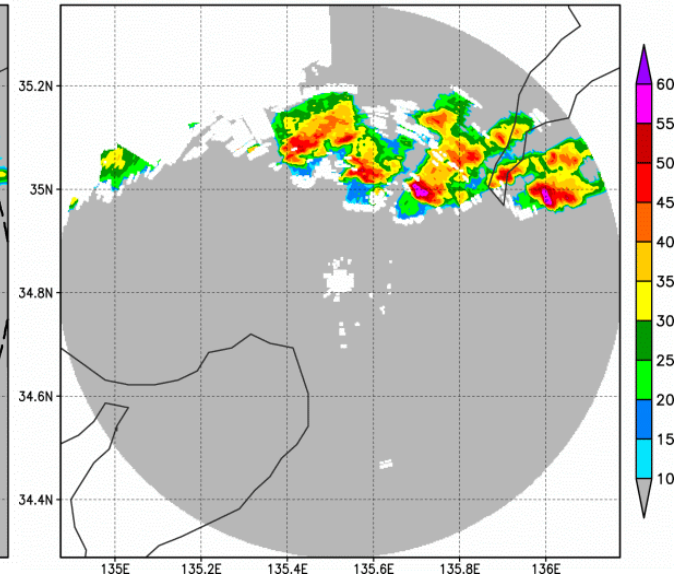
D4_1KM (deterministic)

Radar reflectivity [Z = 3068m] [06:10:00 UTC]



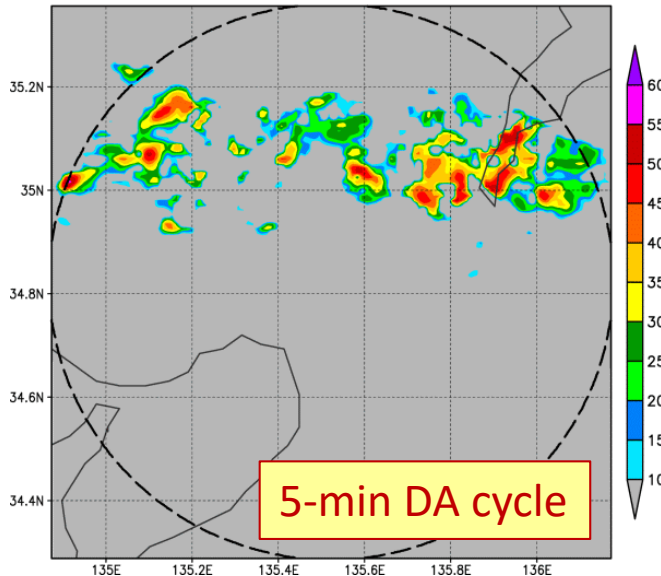
OBS after QC

Radar reflectivity [Z = 3068m] [06:10:00 UTC]



D4_1KM (deterministic)

Radar reflectivity [Z = 3068m] [06:10:00 UTC]

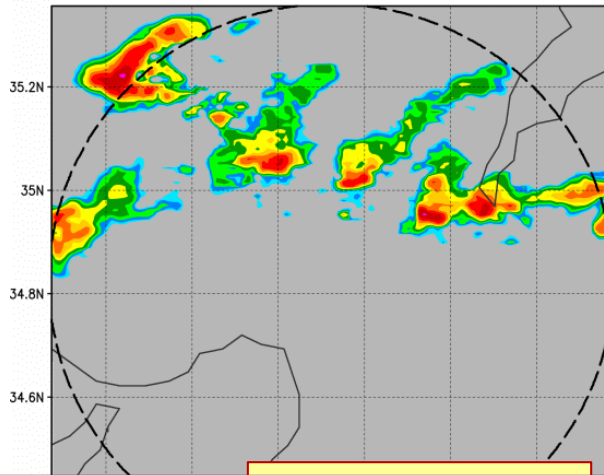


Lien et al. (in prep.)

30-min forecast: 15:40L – 16:10L

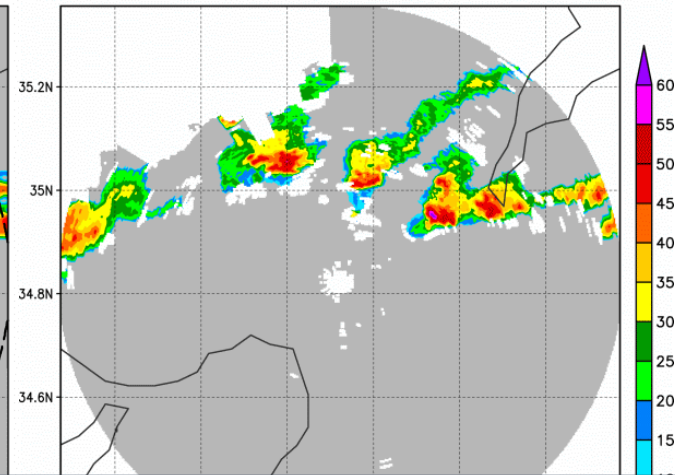
D4_1KM (deterministic)

Radar reflectivity [Z = 3068m] [06:40:00 UTC]



OBS after QC

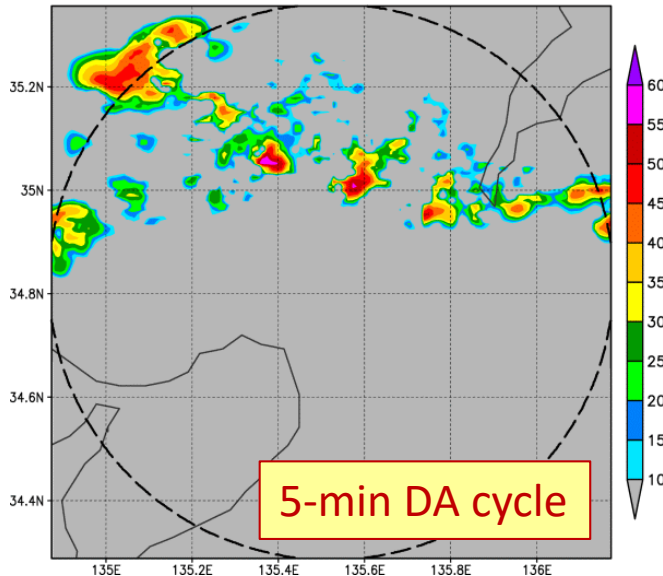
Radar reflectivity [Z = 3068m] [06:40:00 UTC]



30-sec. update certainly helps.

D4_1KM (deterministic)

Radar reflectivity [Z = 3068m] [06:40:00 UTC]

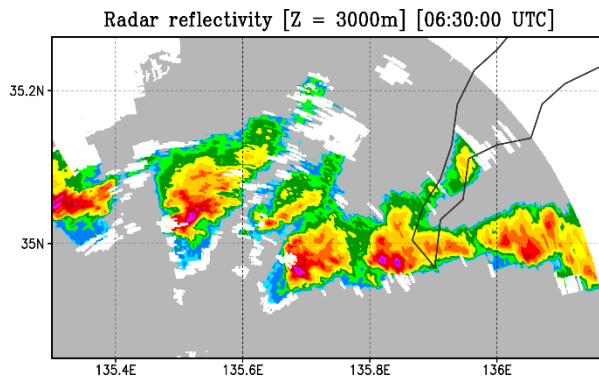


Lien et al. (in prep.)

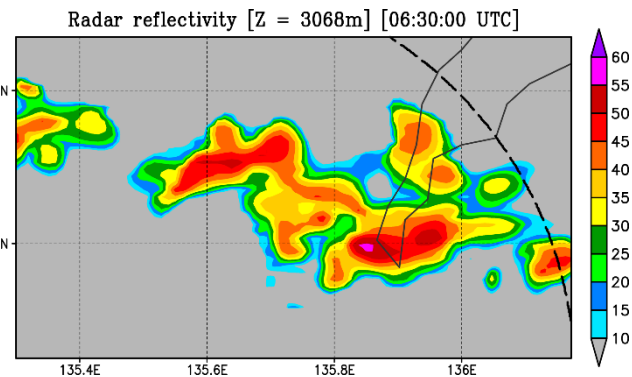
20-min forecast: 15:30L

Lien et al. (in prep.)

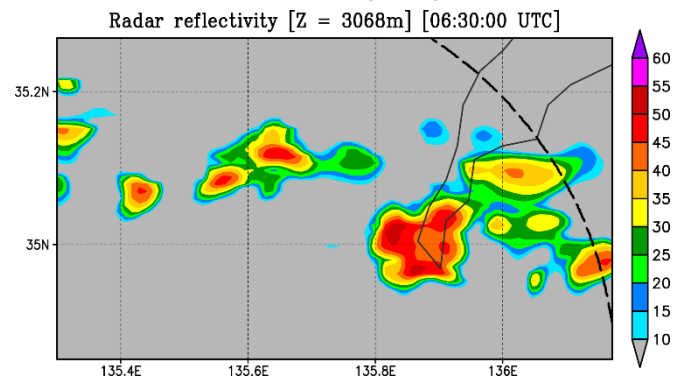
OBS after QC



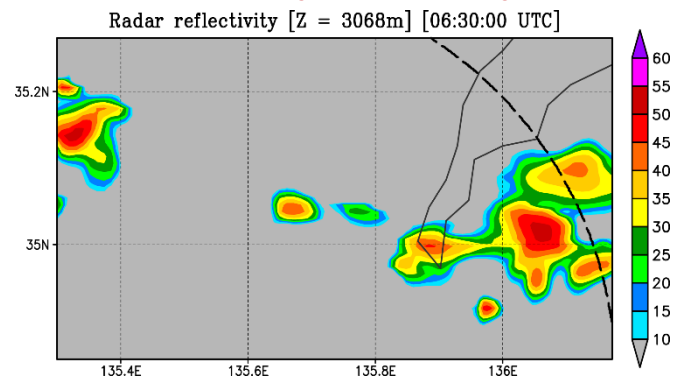
30 sec



5 min (4D)



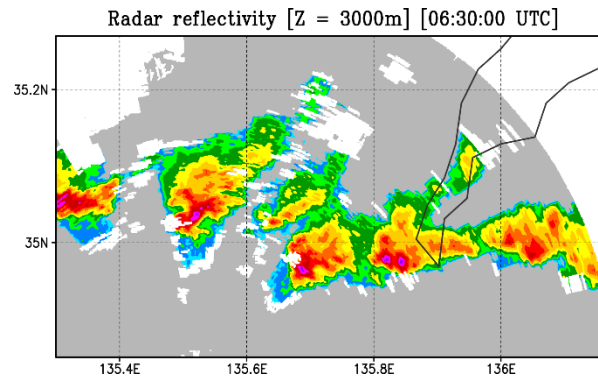
5 min (1/10 data)



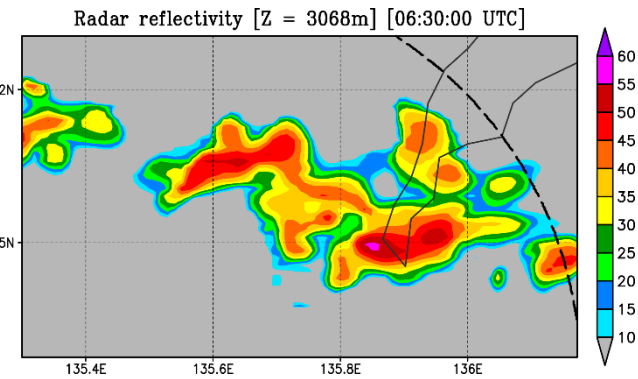
20-min forecast: 15:30L

Lien et al. (in prep.)

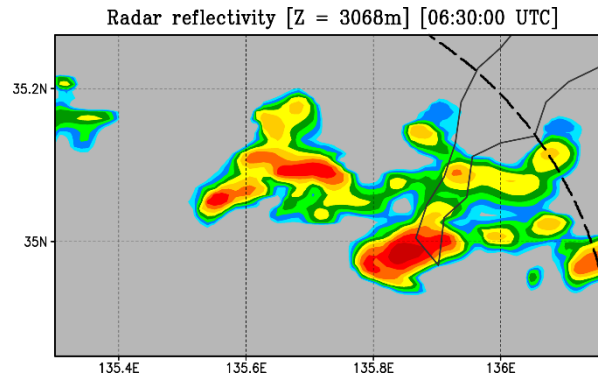
OBS after QC



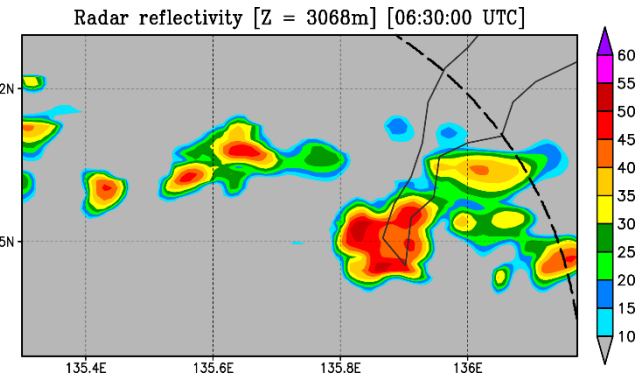
30 sec



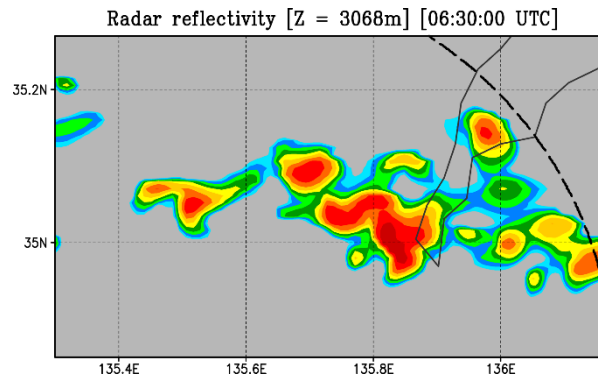
2 min (4D)



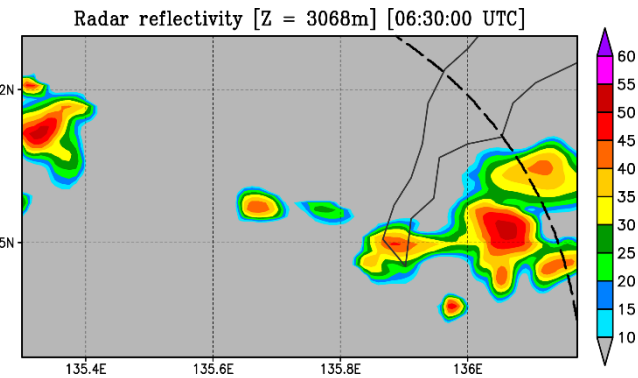
5 min (4D)



2 min (1/4 data)



5 min (1/10 data)



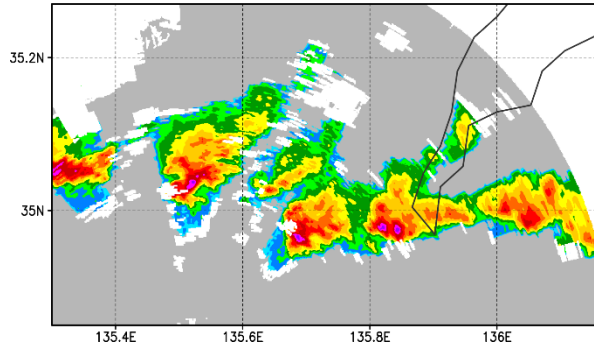
20-min forecast: 15:30L

OBS after QC

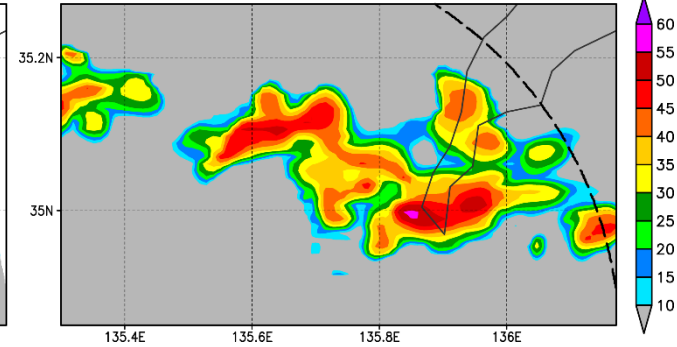
30 sec

Lien et al. (in prep.)

Radar reflectivity [Z = 3000m] [06:30:00 UTC]

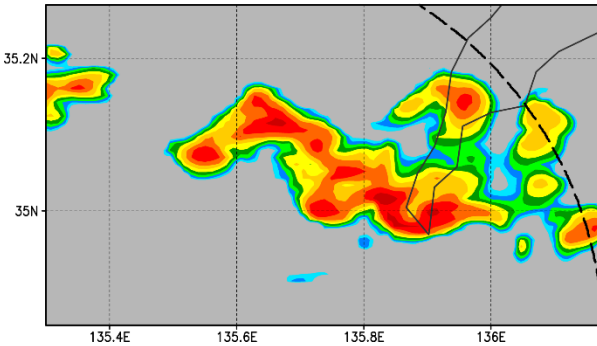


Radar reflectivity [Z = 3068m] [06:30:00 UTC]



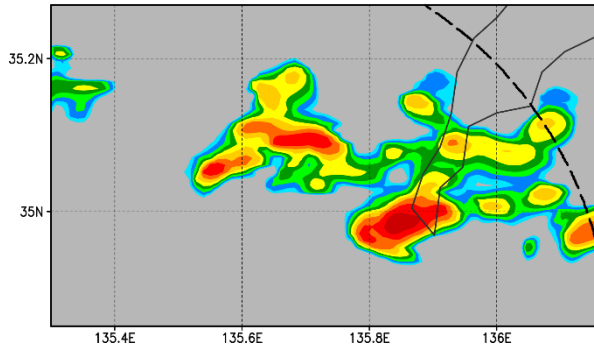
1 min (4D)

Radar reflectivity [Z = 3068m] [06:30:00 UTC]



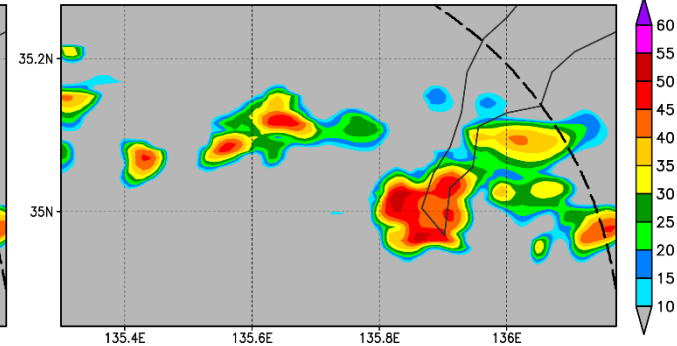
2 min (4D)

Radar reflectivity [Z = 3068m] [06:30:00 UTC]



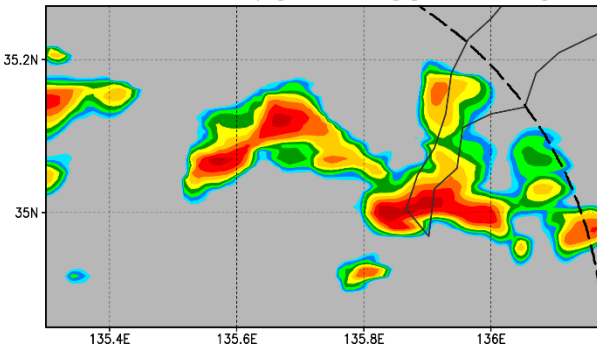
5 min (4D)

Radar reflectivity [Z = 3068m] [06:30:00 UTC]



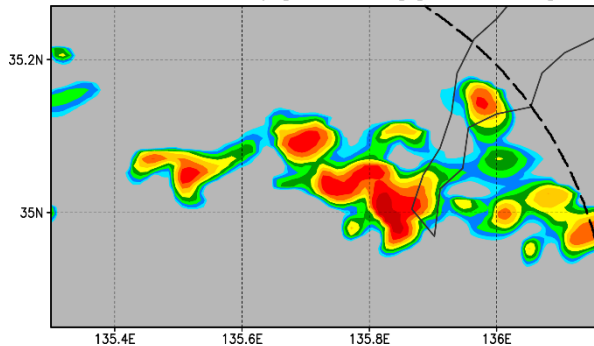
1 min (1/2 data)

Radar reflectivity [Z = 3068m] [06:30:00 UTC]



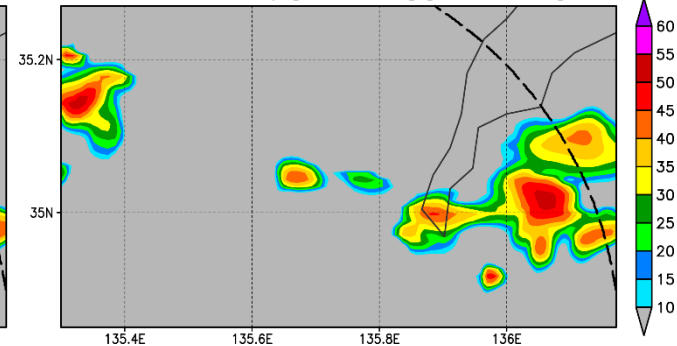
2 min (1/4 data)

Radar reflectivity [Z = 3068m] [06:30:00 UTC]



5 min (1/10 data)

Radar reflectivity [Z = 3068m] [06:30:00 UTC]



Phased-Array Weather Radar 3D precipitation nowcasting

RIKEN Weather Forecast Research

RIKEN AICS Data Assimilation Research Team

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Global Precipitation

Kansai area Precipitation

About DA Team

English / 日本語

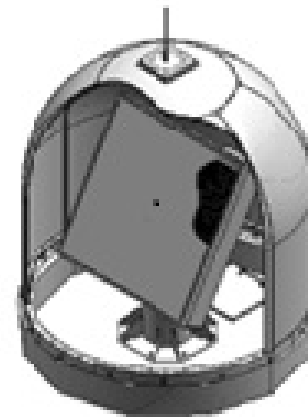
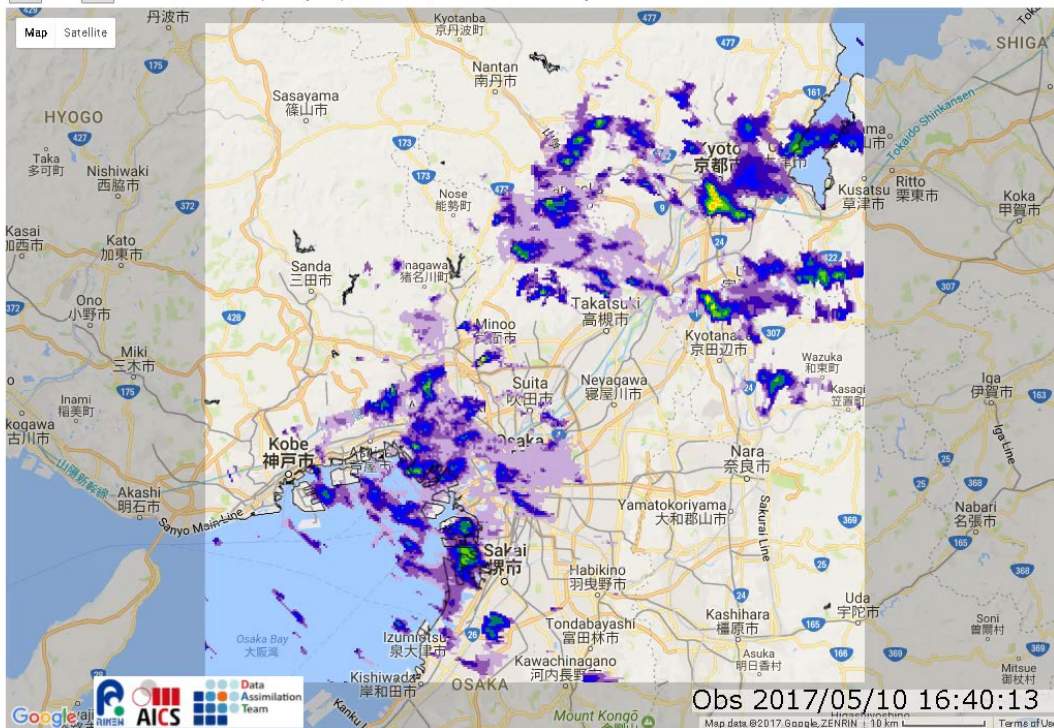
KANSAI PRECIPITATION NOWCAST

30 second update, 10 minute forecast

Init time: 2017/05/10 16:45:13

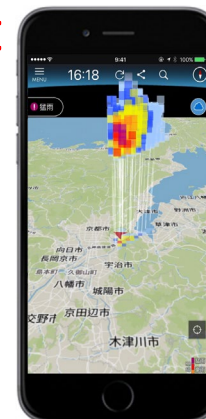
Warnings / Advisories (Japan)

<< 0 >> Animate Auto update (every 30 seconds, auto turn-off in 30mins)



(NICT)

30-second-update
10-min forecast



App by MTI

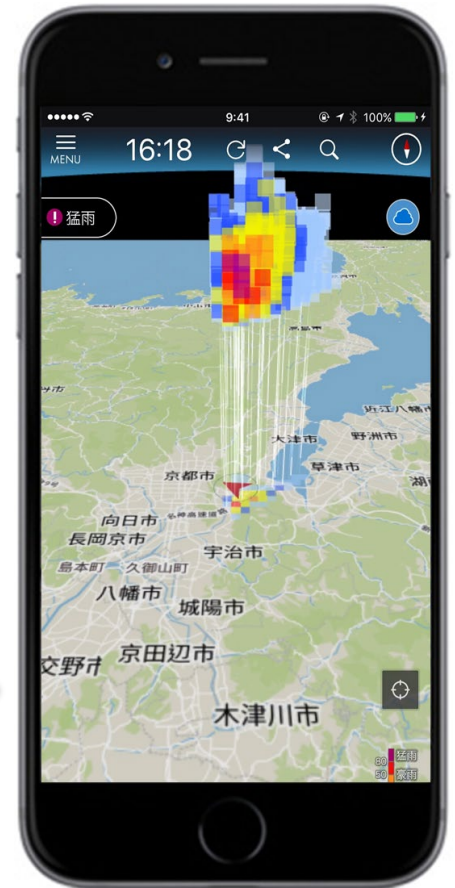
Real-time dissemination started on 7/27/2017 in collaboration with MTI Ltd.

PR TIMES Top | テクノロジー | モバイル | アプリ | エンタメ | ビューティー | ファッション | ライフスタイル | ビジネス

プレスリリース・ニュースリリース配信サービスのPR TIMES

>150,000
downloads!

Making societal impact



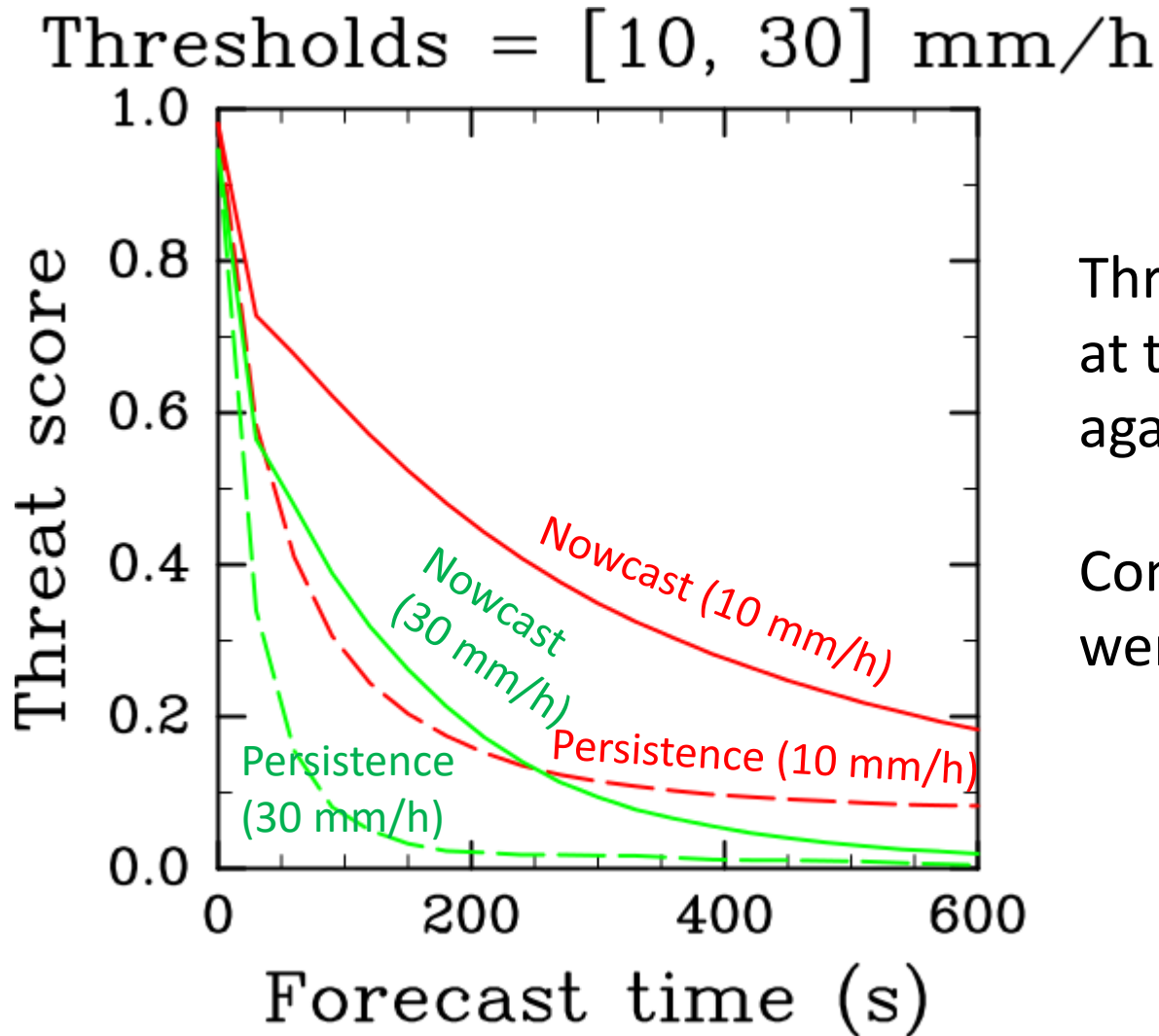
ゲリラ豪雨検知アプリ『3D雨雲ウォッチ〜フェーズドアレイレーダ〜』実証実験 東エリアへ拡大
～隅田川花火大会の
株式会社エムティーアイ
2017年7月27日 12時11分
いいね! シェア ツイート
(株)エムティーアイが運営する天気総合サイト『ライフレンジャー』は昨年に続き、国立研究開発法人情報通信研究機構との共同研究により開発した、ゲリラ豪雨検知アプリ『3D雨雲ウォッチ〜フェーズドアレイレーダ〜』の実証実験を、7月27日(木)より開始します。

今年で3年目
られた予測
らのデータ提供
サービスの有用性
また今回ア
サポートを行います。

◆理研との共同研究による予測データを用いてゲリラ豪雨の発生を10分前に通知!

本アプリは、最先端の気象レーダ「フェーズドアレイレーダ」のデータを用いてゲリラ豪雨の発生をリアルタイムでお知らせするサービスです。今まで察知が難しかったゲリラ豪雨が発生する可能性を、瞬時にスマートフォンでプッシュ通知で受け取ります。

2018/7/6 10-15 JST, Average of 388 forecasts



Threat scores of rain rate at the 2-km altitude against PAWR

Convective features were well predicted

Convolutional LSTM

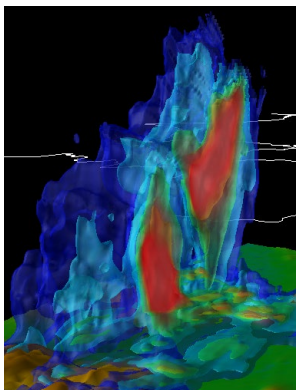
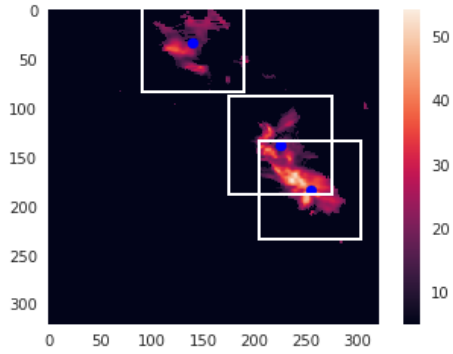
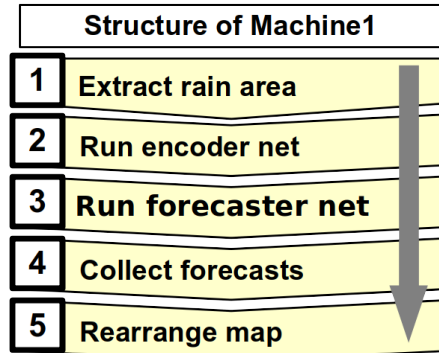
Shi et.al (2015)

(Work with Mr. Viet Phi Huynh and Prof. Pierre Tandeo)

OUTPUT

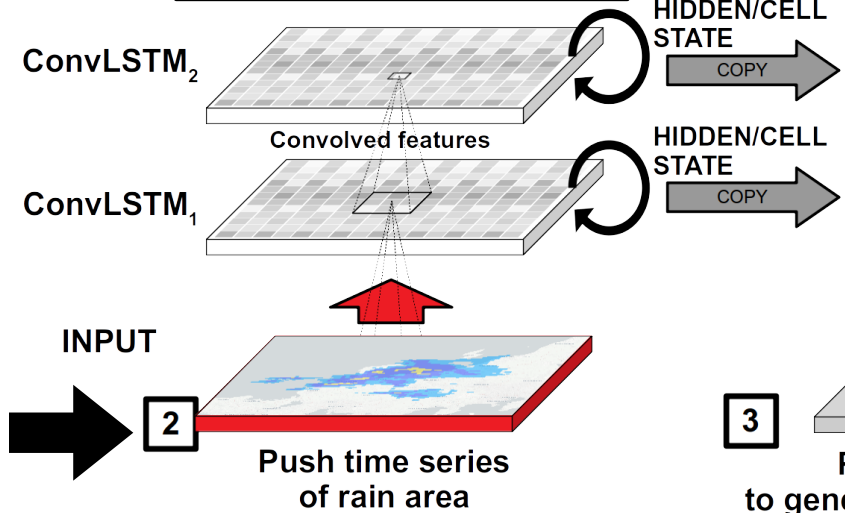
5 time steps (2.5min)

Future 3D forecast

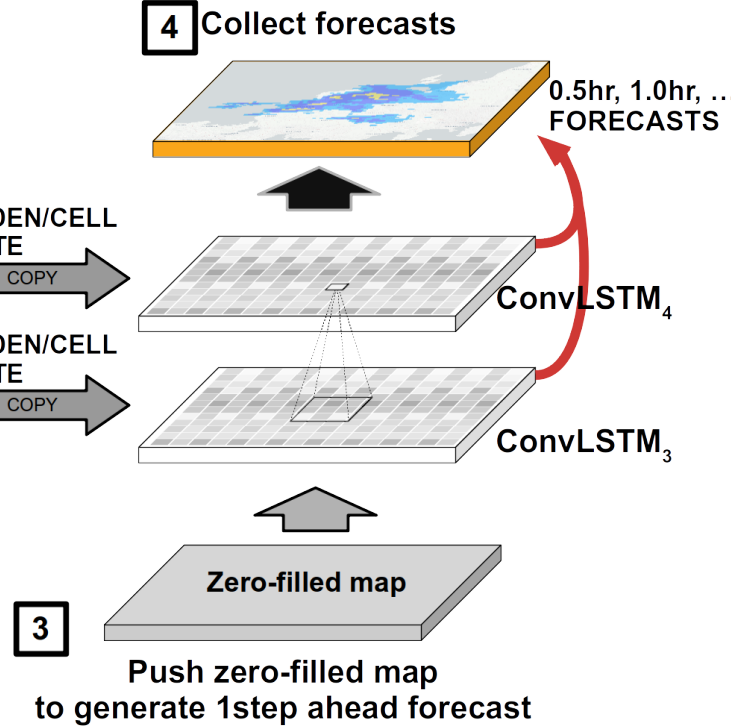


INPUT 6 time steps (3min)
Past 3D observation

Extract feature of spacial development
ENCODER NETWORK



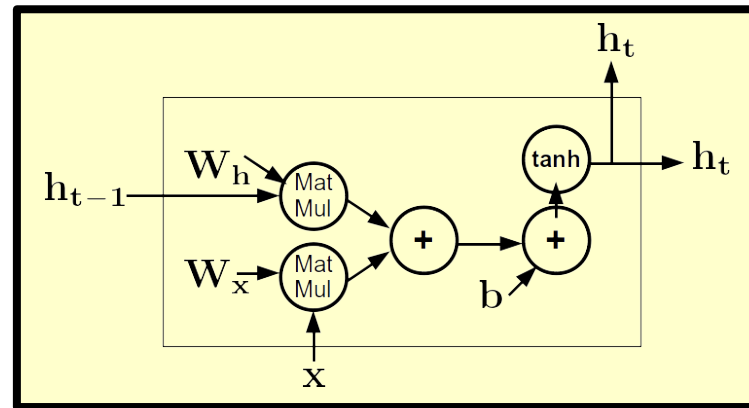
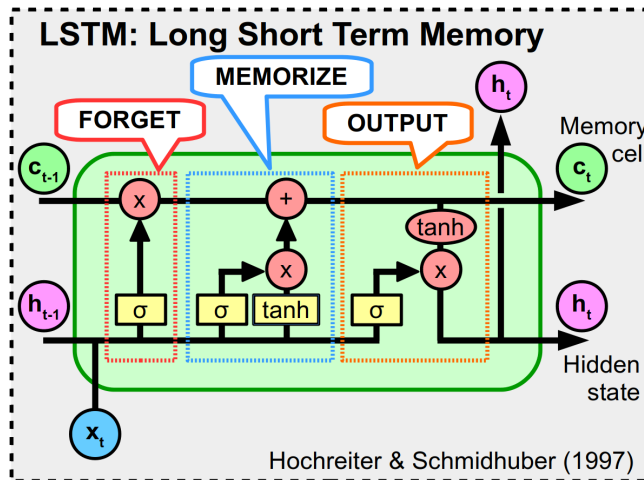
FORECASTER NETWORK



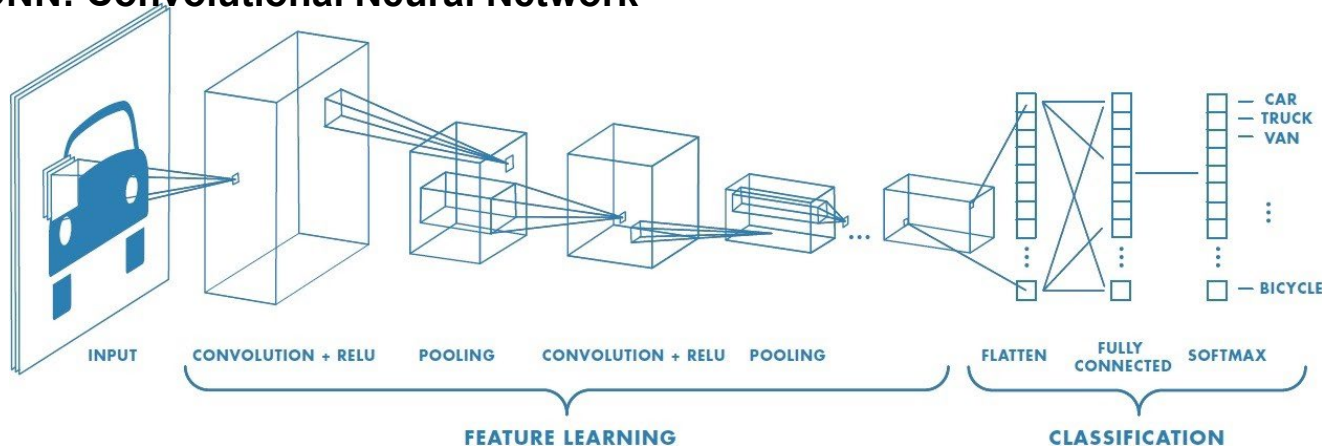
Forecast rain-map based on extracted features

Strategy

- Combine 2 well known neural network structure **LSTM & CNN** → **Convolutional LSTM**



CNN: Convolutional Neural Network



Settings

(Work with Mr. Viet Phi Huynh and Prof. Pierre Tando)

DATASET

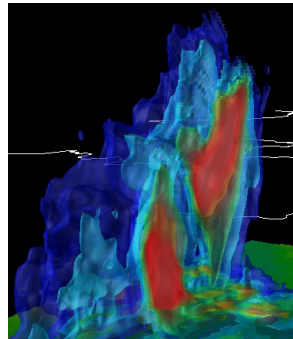
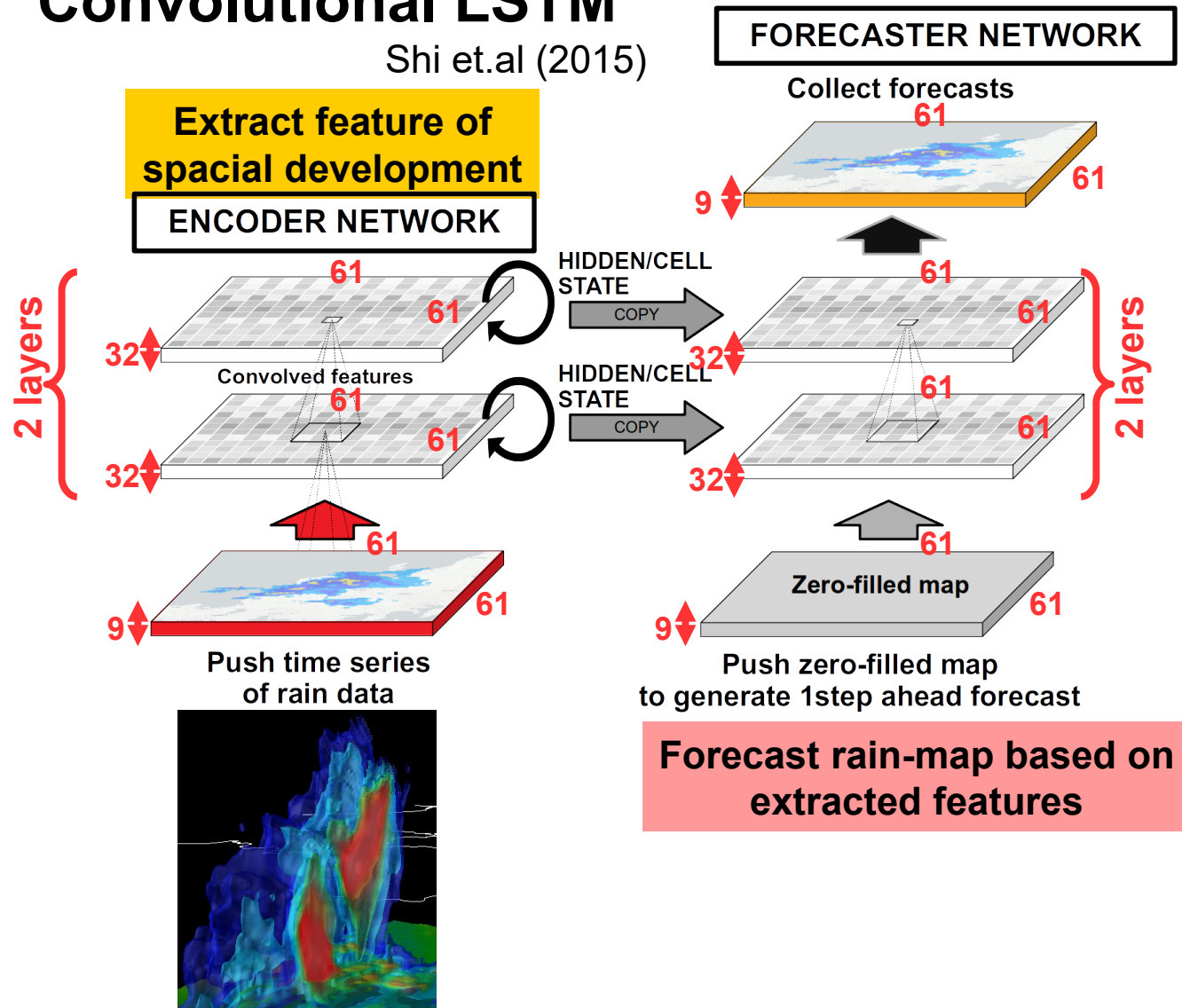
- NICT
Phased Array Radar
- 250m
 - Every 30 second radar echo
 - Min-max normalization
 - Input past 3 mins
 - Forecast 2.5 mins
- Training period:
31 May & 26-27 July, 2018

Training settings

- Library: Theano
Loss function:
Balanced MSE
Optimizer:
AdaDelta (lr=1e-4)
Mini batch: 10

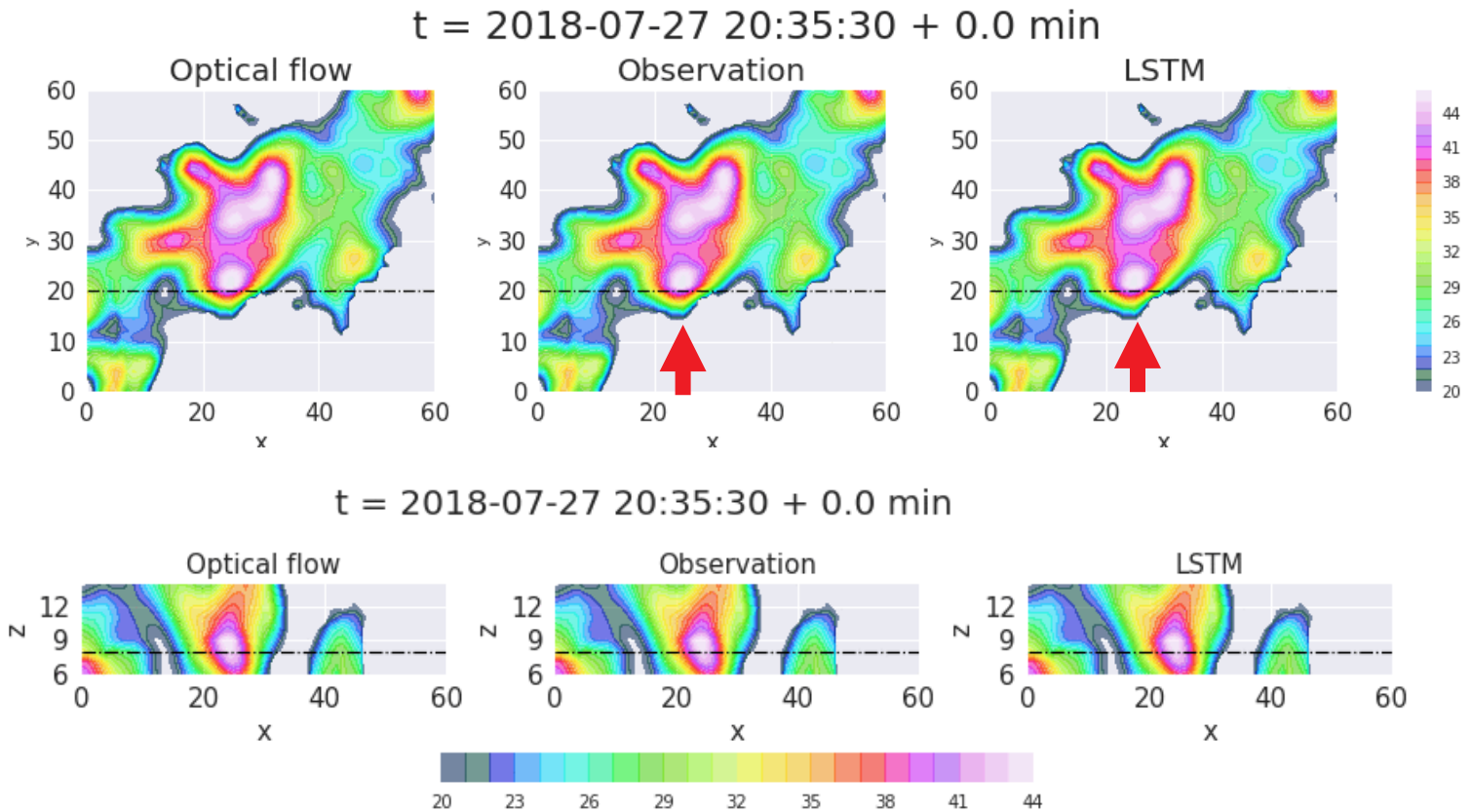
“Convolutional LSTM”

Shi et.al (2015)



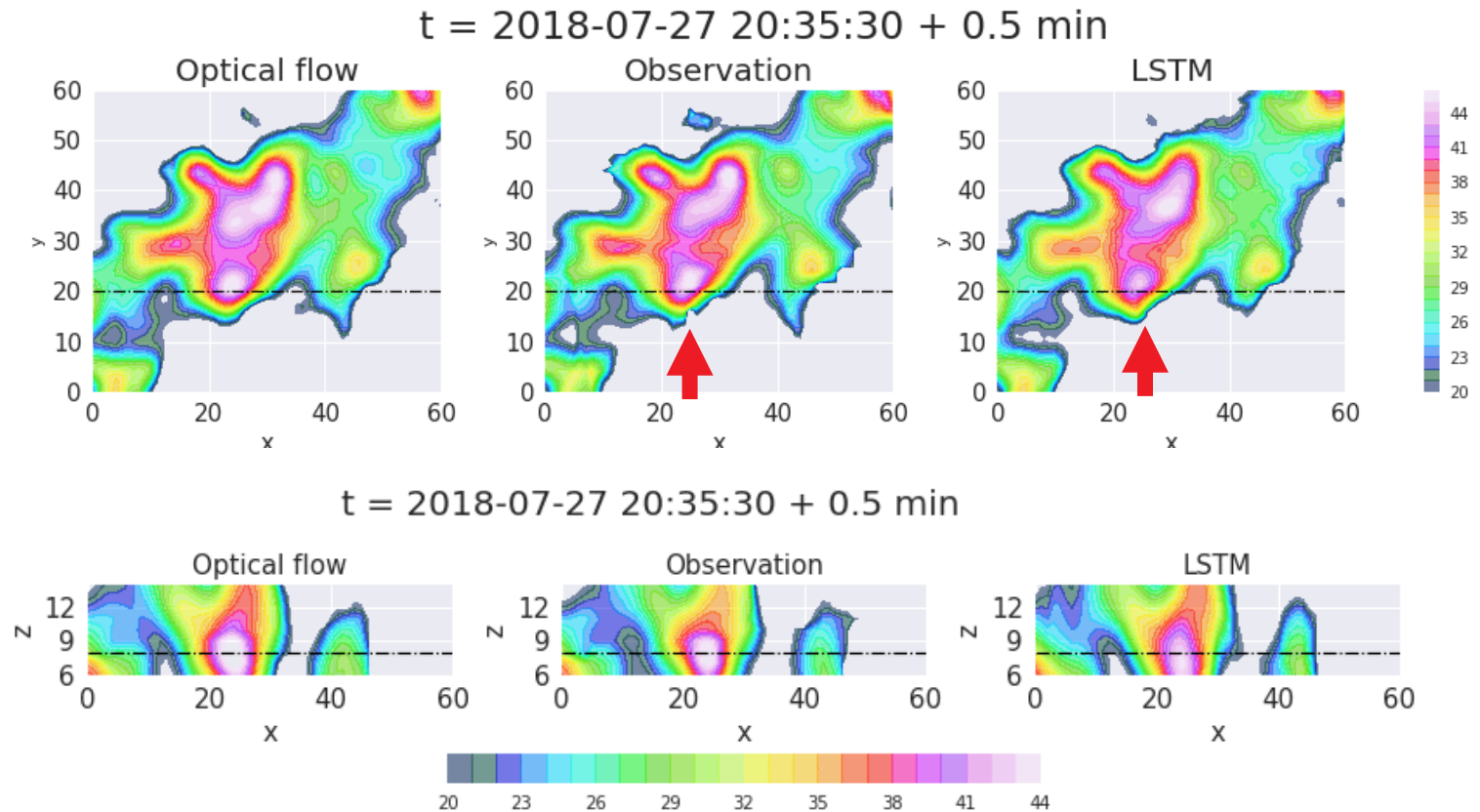
3D Nowcast by Conv-LSTM

(Work with Mr. Viet Phi Huynh and Prof. Pierre Tandeo)



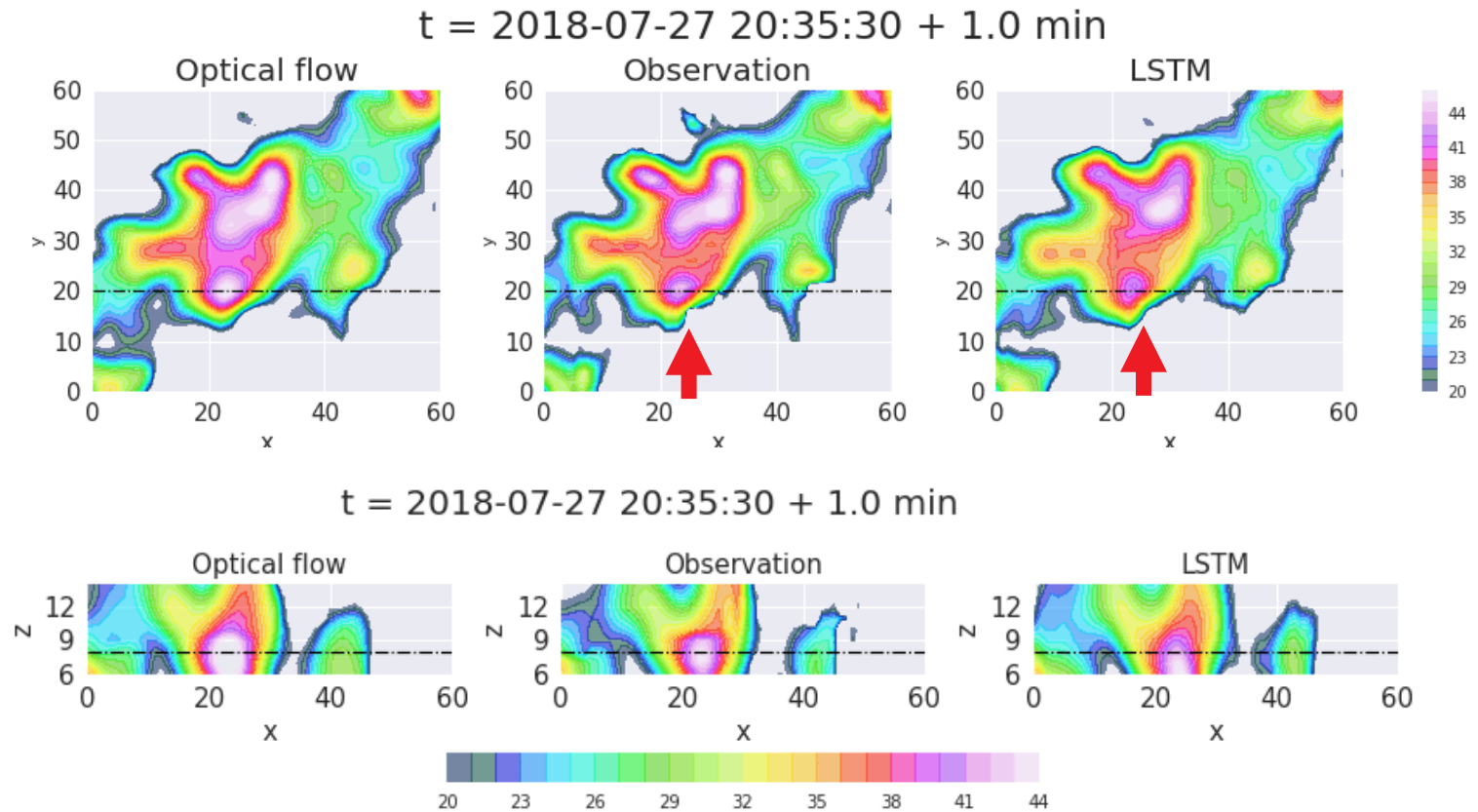
3D Nowcast by Conv-LSTM

(Work with Mr. Viet Phi Huynh and Prof. Pierre Tandeo)



3D Nowcast by Conv-LSTM

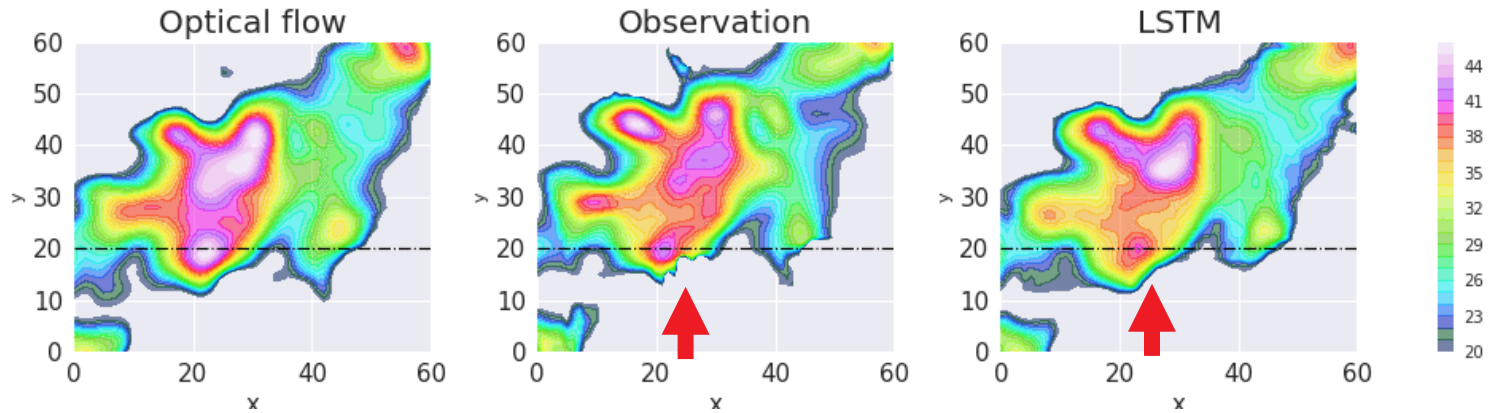
(Work with Mr. Viet Phi Huynh and Prof. Pierre Tandeo)



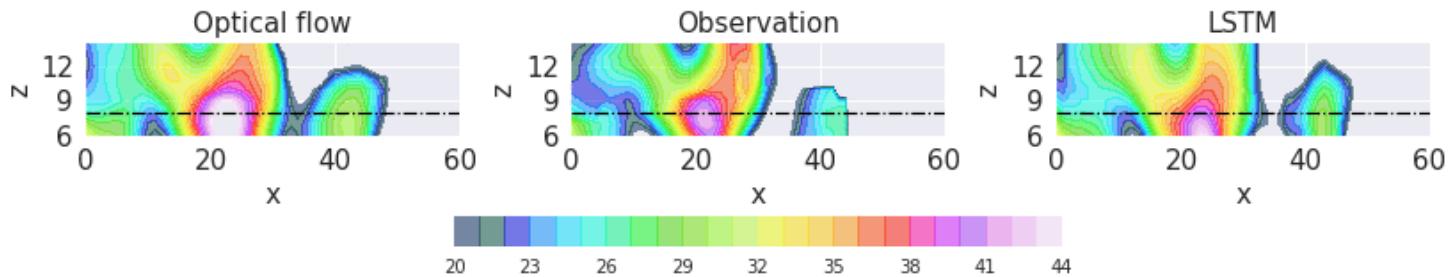
3D Nowcast by Conv-LSTM

(Work with Mr. Viet Phi Huynh and Prof. Pierre Tandeo)

t = 2018-07-27 20:35:30 + 1.5 min



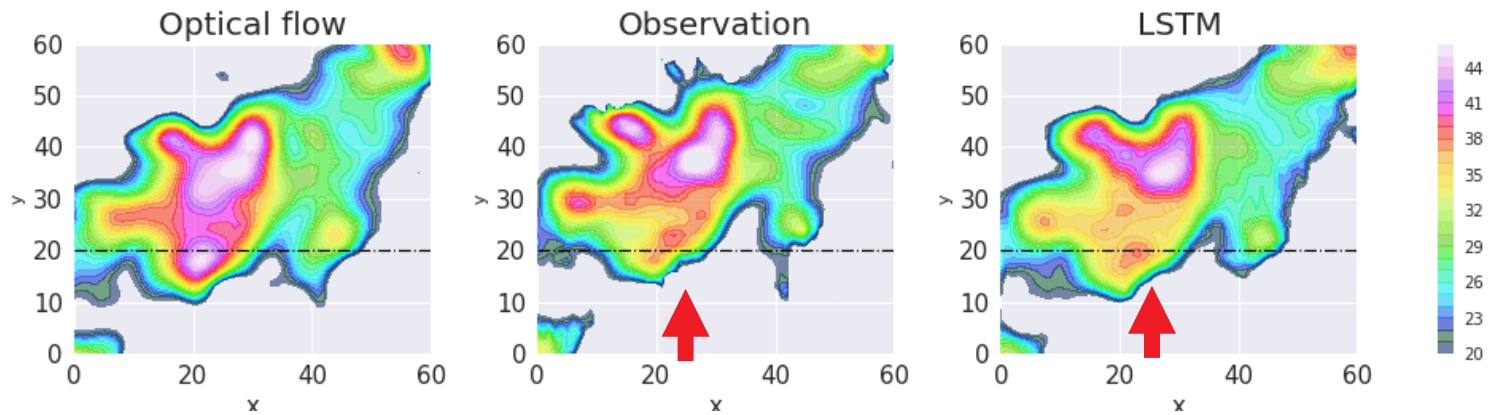
t = 2018-07-27 20:35:30 + 1.5 min



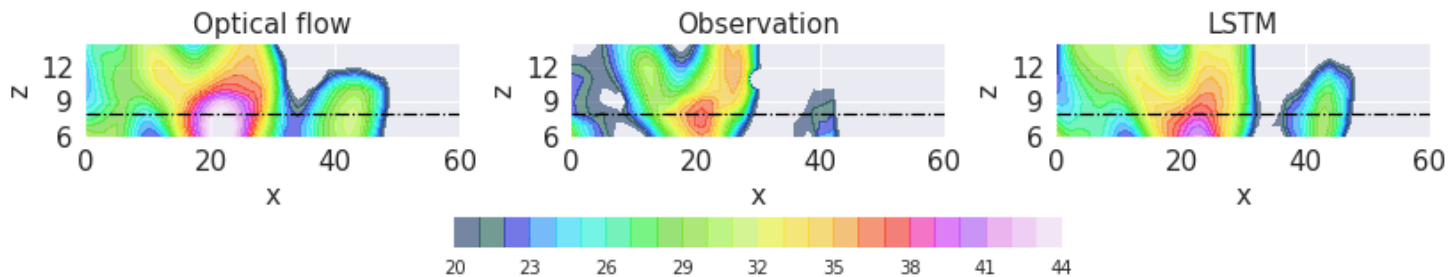
3D Nowcast by Conv-LSTM

(Work with Mr. Viet Phi Huynh and Prof. Pierre Tandeo)

t = 2018-07-27 20:35:30 + 2.0 min



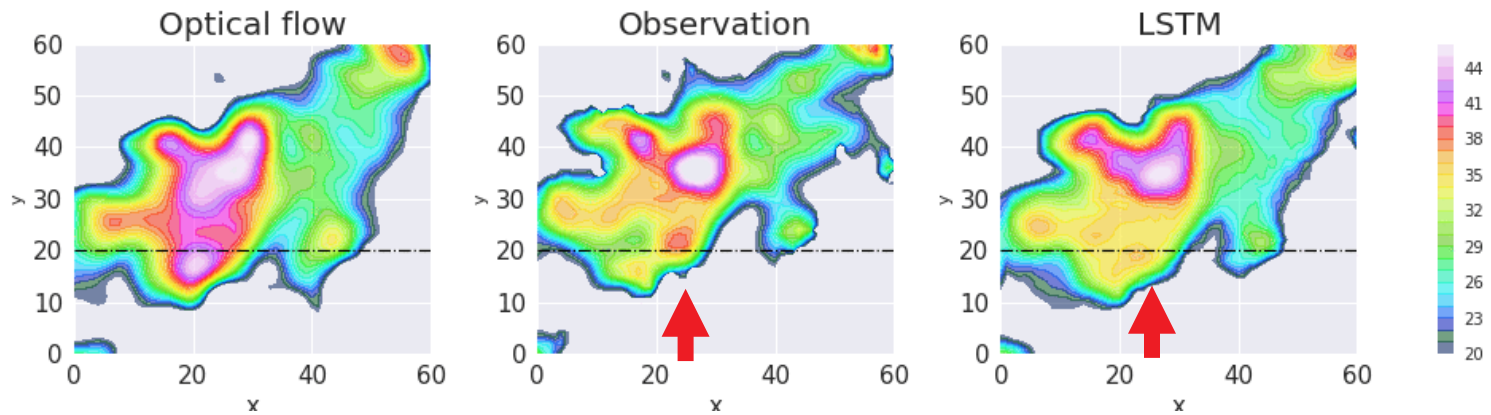
t = 2018-07-27 20:35:30 + 2.0 min



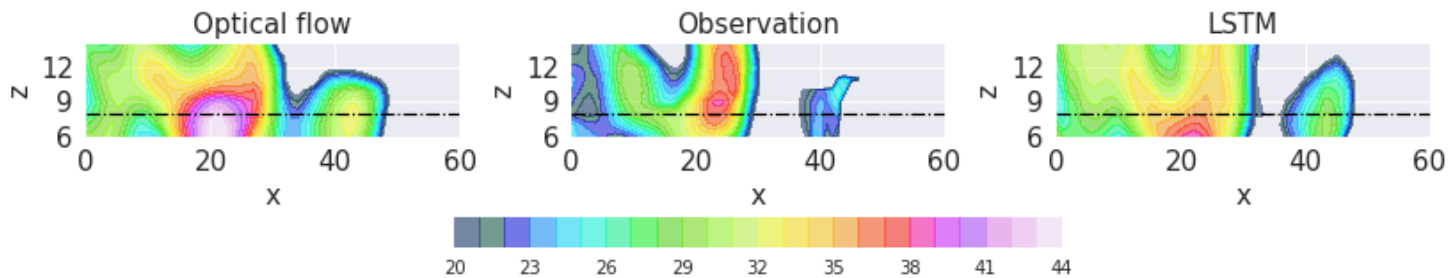
3D Nowcast by Conv-LSTM

(Work with Mr. Viet Phi Huynh and Prof. Pierre Tandeo)

t = 2018-07-27 20:35:30 + 2.5 min



t = 2018-07-27 20:35:30 + 2.5 min



Toward Weather-Ready Society 5.0 with

Cyberspace

synchronize
predict & control

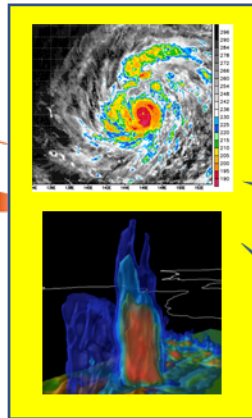
Real world

Simulation



Big Data Assimilation
Data Assimilation

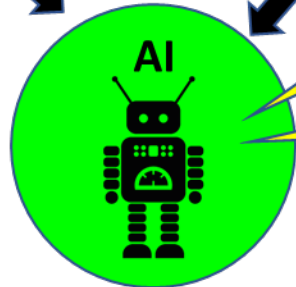
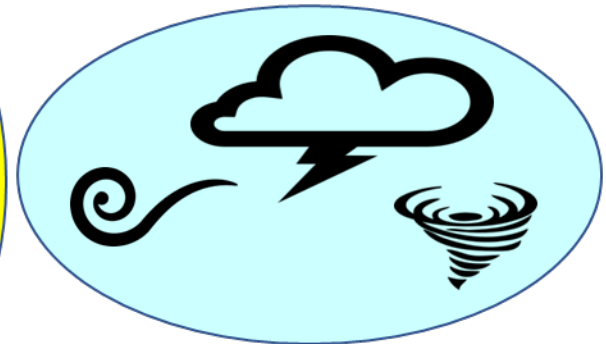
Big Data



Sensing



Nature



IoT



Human society and economy

Toward Weather-Ready Society 5.0 with



Cyberspace

synchronize
predict & control

Real world

Simulation

Big Data

Sensing

Nature

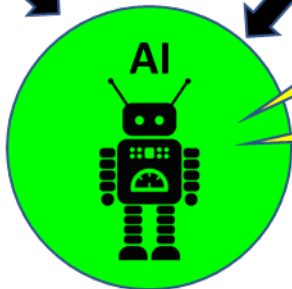
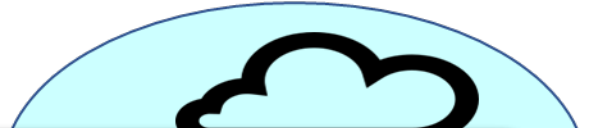
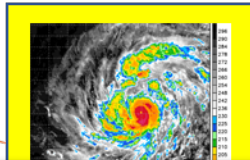
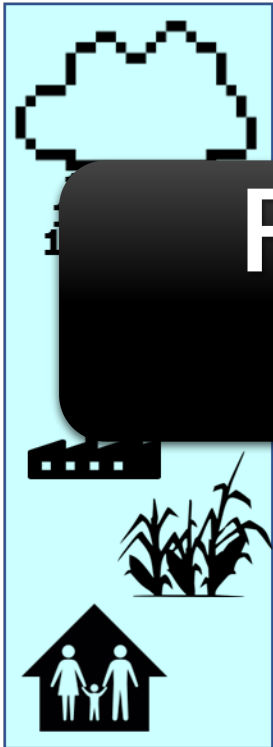
Big Data Assimilation

Potential demonstration at
TOKYO 2020

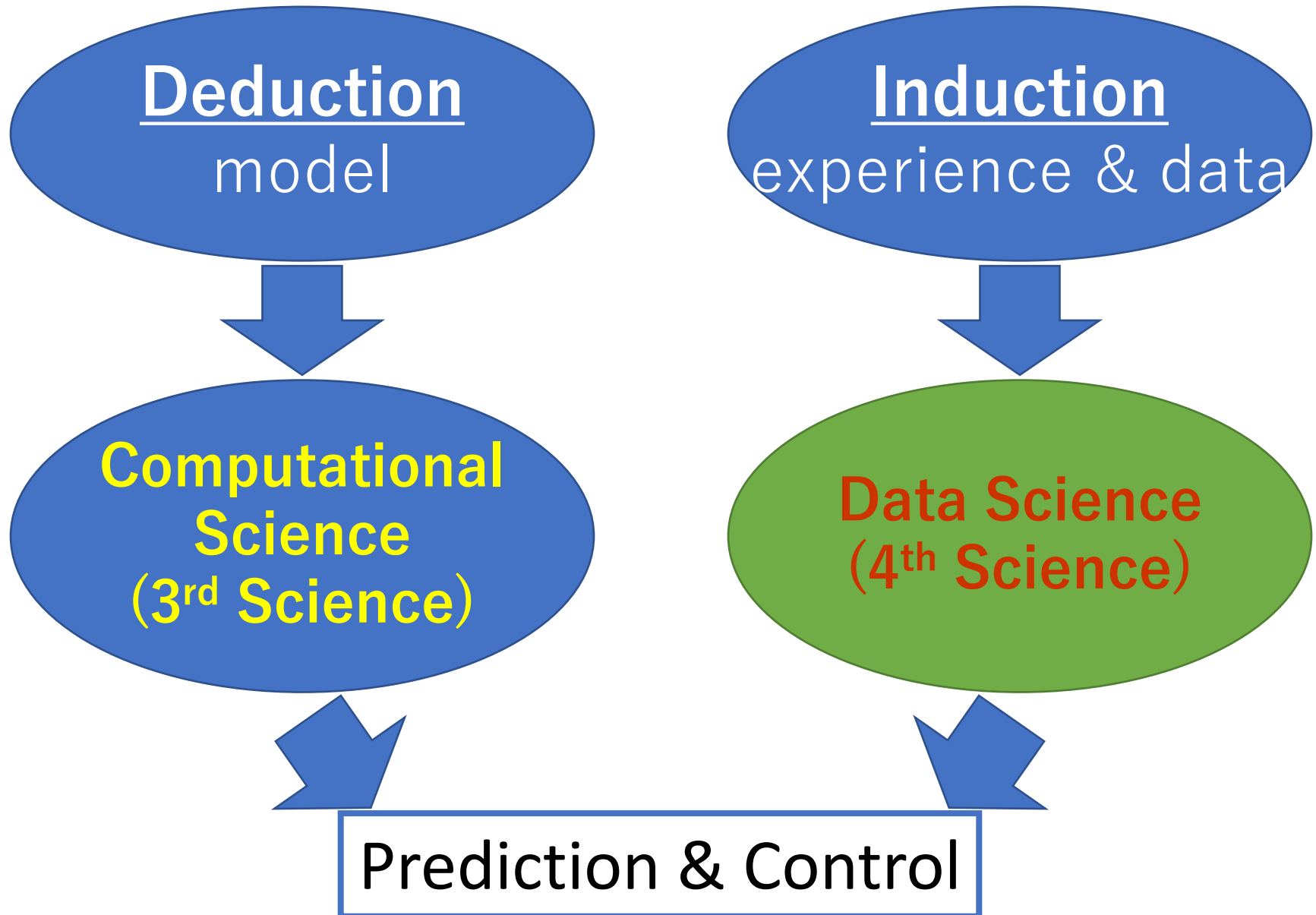
AI

IoT

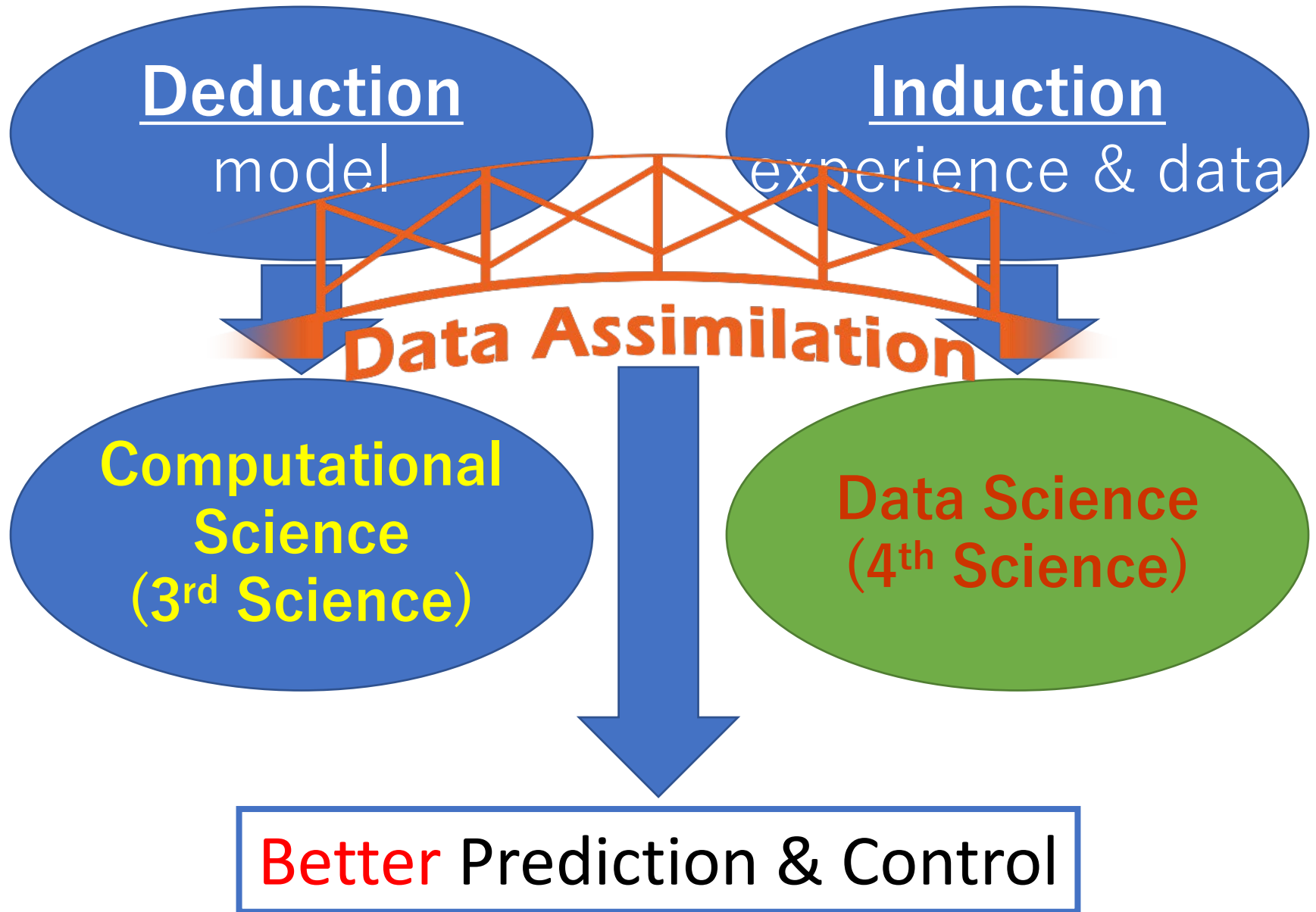
Human society and economy



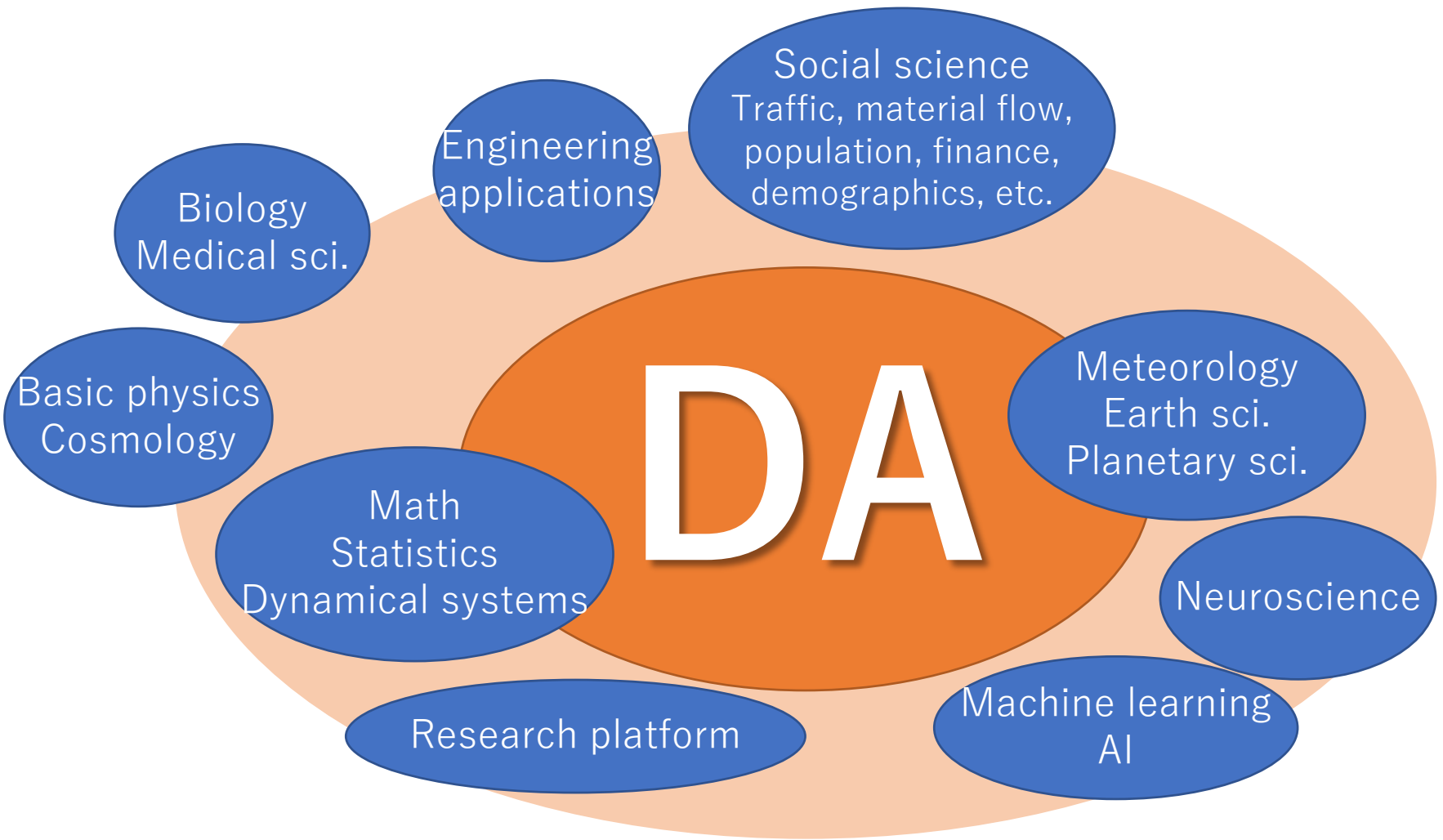
Methods for prediction & control

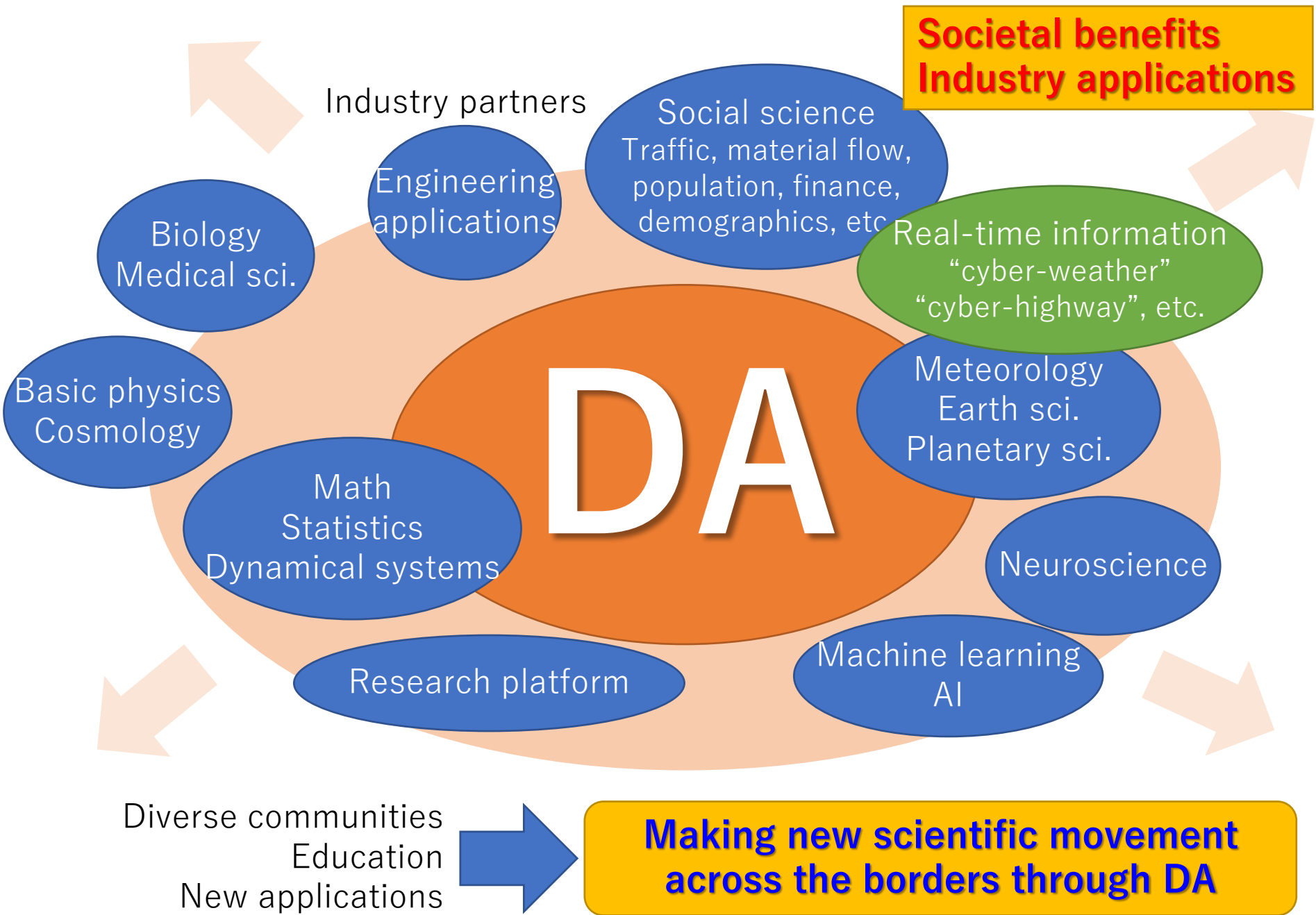


Methods for prediction & control

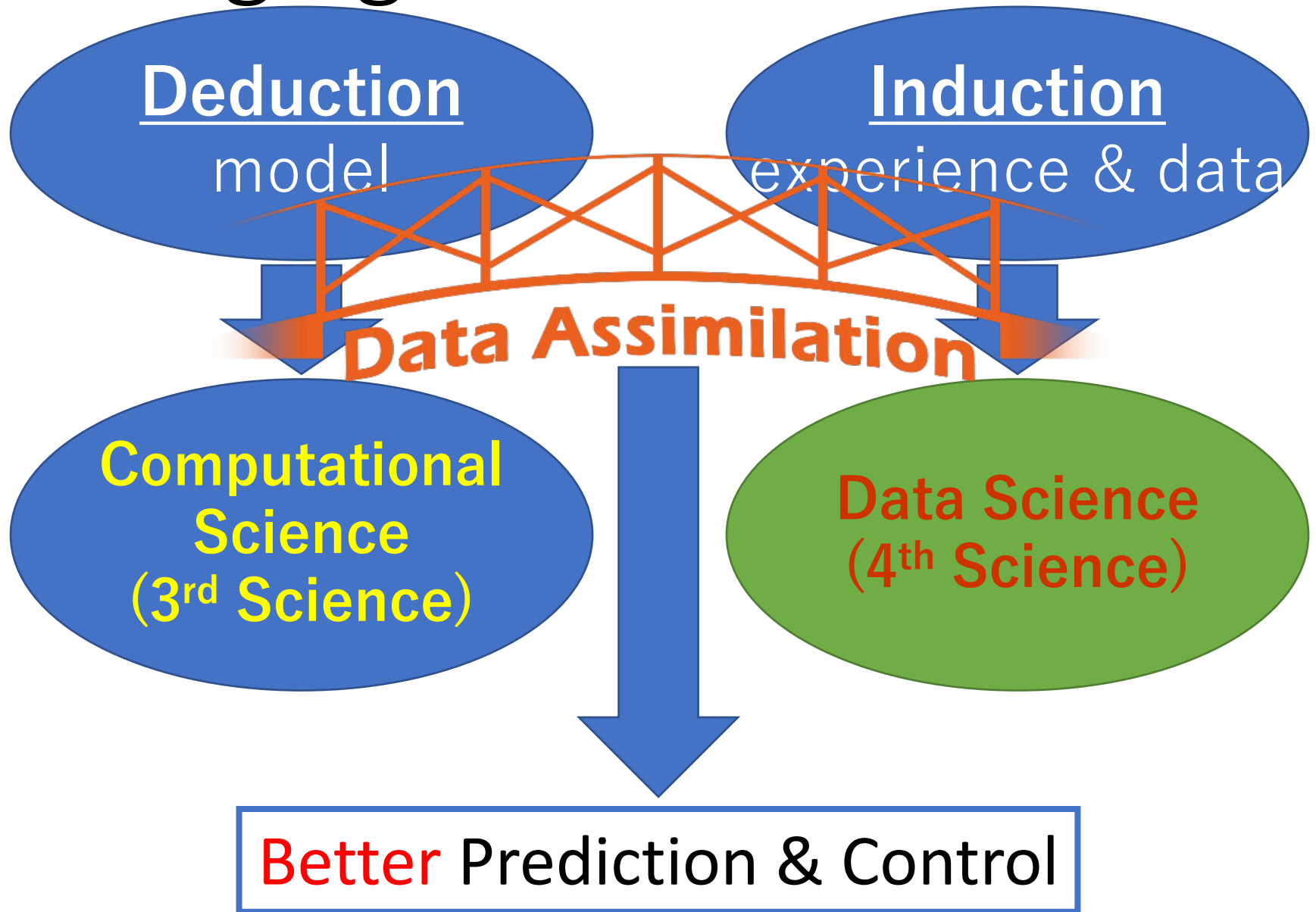






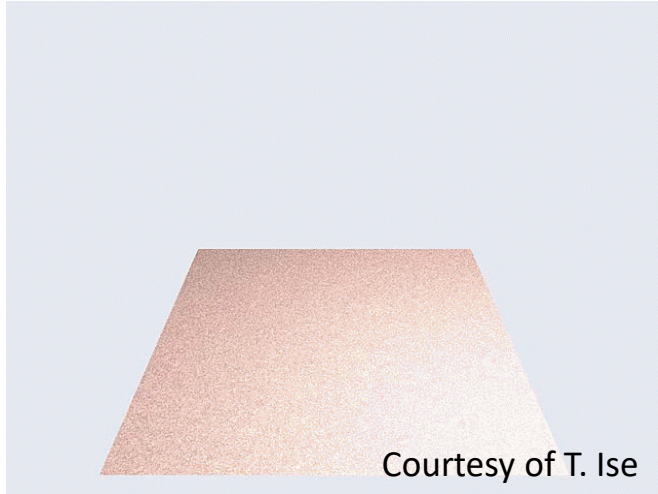


Bringing DA into new areas



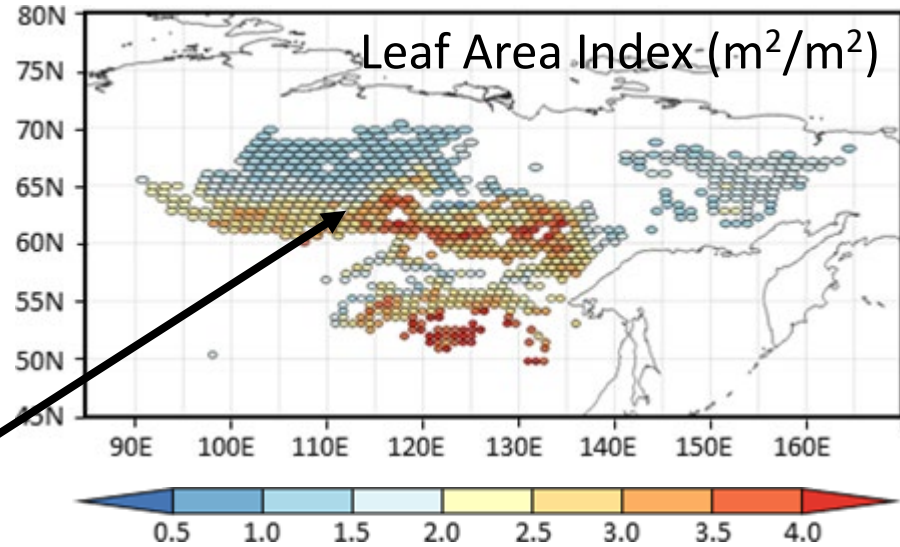
Ecosystem control with DA

Forest simulation



for 100 years at
a single location

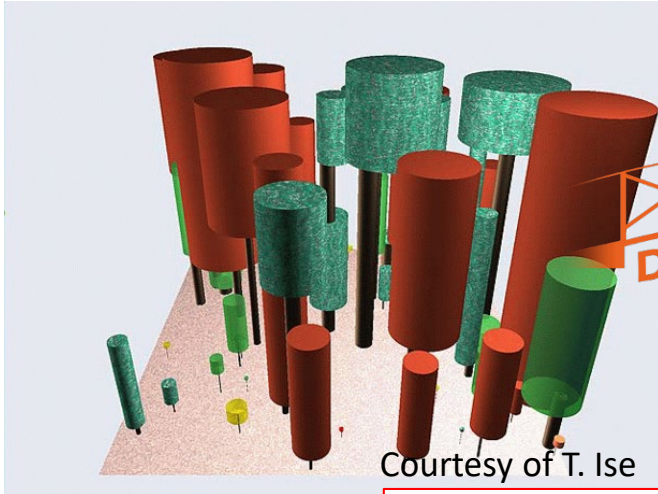
Satellite observation



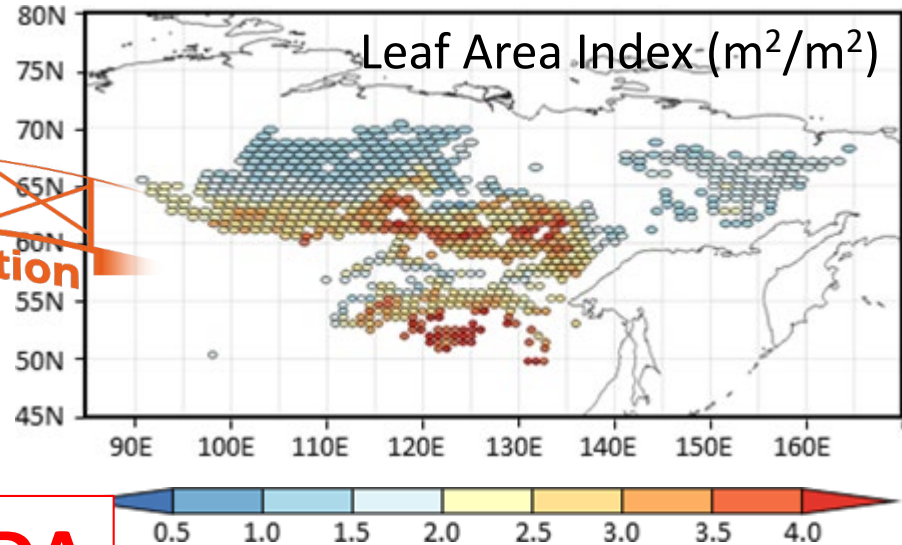
every 4 days

Ecosystem control with DA

Forest simulation



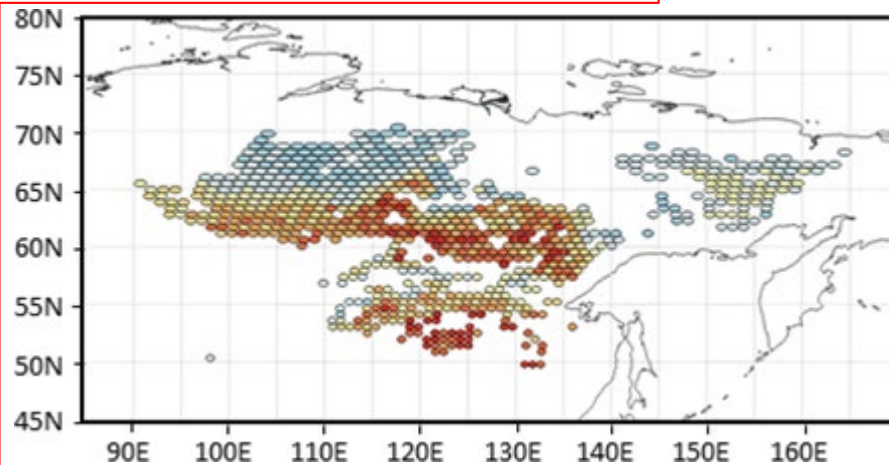
Satellite observation



Data Assimilation

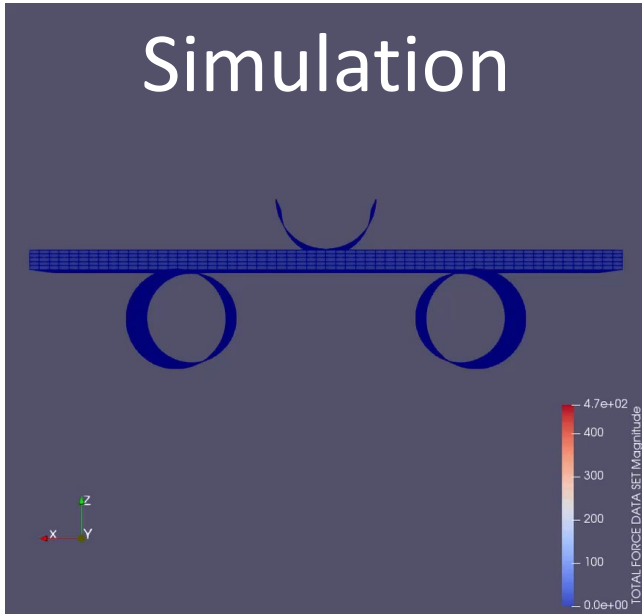


Simulation w/ DA



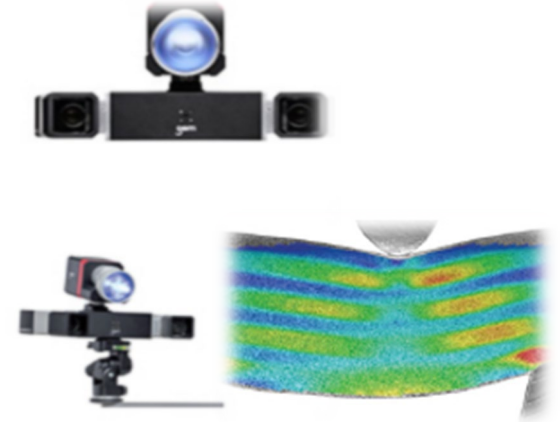
*Arakida, Miyoshi,
et al. (2018)*

DA for press-forming simulation



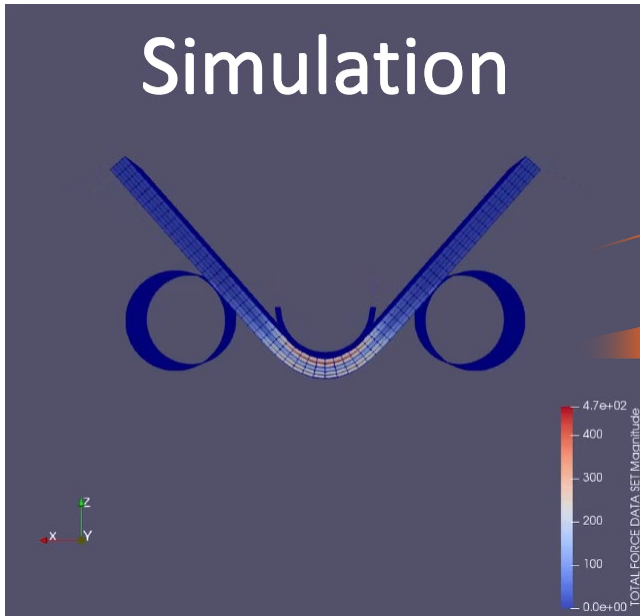
(Sakamoto, Takamura)

Sensor data



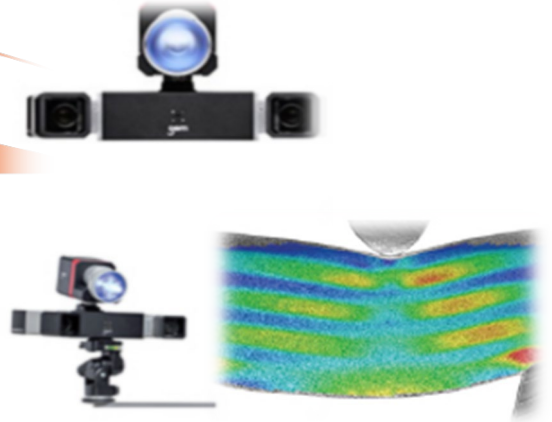
Surface strain measured by ARAMIS

DA for press-forming simulation

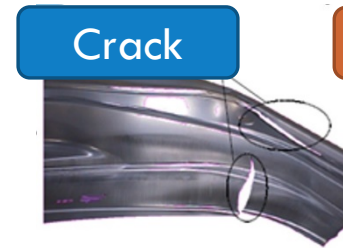


Data Assimilation

Sensor data



Optimize press-forming parameters



The 5th Paradigm

5th Science

The diagram features a large magenta oval containing a bridge structure. The bridge has an orange truss top and a blue base. The text 'Data Assimilation' is written in orange across the bridge. Below the bridge, a blue arrow points downwards. On either side of the arrow are two ovals: a blue one on the left and a green one on the right. Below these ovals is a white box with an orange border containing the word 'Mathematics'. At the bottom of the diagram is a white box with a blue border containing the text 'New Prediction & Control'.

Data Assimilation

Computational
Science
(3rd Science)

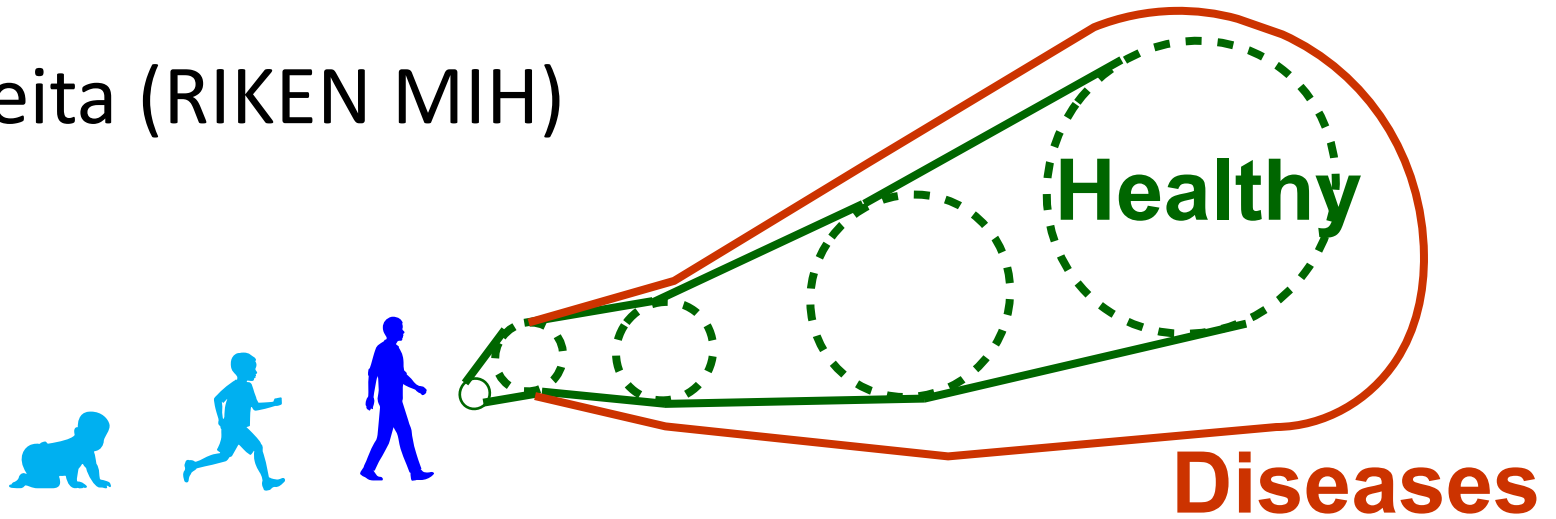
Data Science
(4th Science)

Mathematics

New Prediction & Control

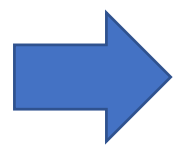
Hybrid DA for human life

J. Seita (RIKEN MIH)

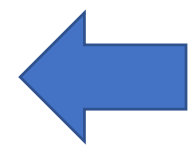


Too complex model

Data-driven model



Hybrid DA



Regular DA

