



Ensemble based data assimilation for a multi-compartment porous media model

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- Data assimilation in medicine
- Contrast enhanced dynamic MRI
- Multi-compartment porous media model for blood flow
- Data assimilation
- Case studies
- Conclusion

Blood flow simulation



- > A. L. Marsden: “Cardiovascular blood flow simulation. From computation to clinic.” SIAM News, 48 (10), 2015.
 - “There is a rising interest in clinical data assimilation and uncertainty quantification in cardiovascular simulations.”

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- > Boundary value problem
- > Data source: Medical imaging
- > Using variational methods
- > Forward modeling is computationally intensive
- > Adjoints available

Ensemble based approach



S. Pagani, A. Manzoni and A. Quarteroni: "A reduced basis ensemble Kalman filter for state/parameter identification in large-scale nonlinear dynamical systems". Tech. report 18.2016 Mathematics Institute of Computational Science and Engineering, École polytechnique fédérale de Lausanne

Data assimilation in oncology - I



- > TE Yankeelov et. al.: “Toward a science of tumor forecasting for clinical oncology,” *Cancer Research*, 75(6), 2015.
 - “We propose that the quantitative cancer biology community makes a concerted effort to apply lessons from weather forecasting to develop an analogous methodology for predicting and evaluating tumor growth and treatment response.”

Data assimilation in oncology - II



- > EJ Kostelic et. al.: “Accurate state estimation from uncertain data and models: an application of data assimilation to mathematical models of human brain tumors.” *Biology Direct*, 6:64, 2011.
 - Synthetic study using two models for glioblastoma, MRI data as observations.
 - Local ensemble transform Kalman filter

Contrast enhanced dynamic MRI



By Jan Ainali - Own work, CC BY 3.0,
<https://commons.wikimedia.org/w/index.php?curid=3546051>

Contrast enhanced dynamic MRI



- > Gadolinium Contrast Medium (MRI Contrast agents)

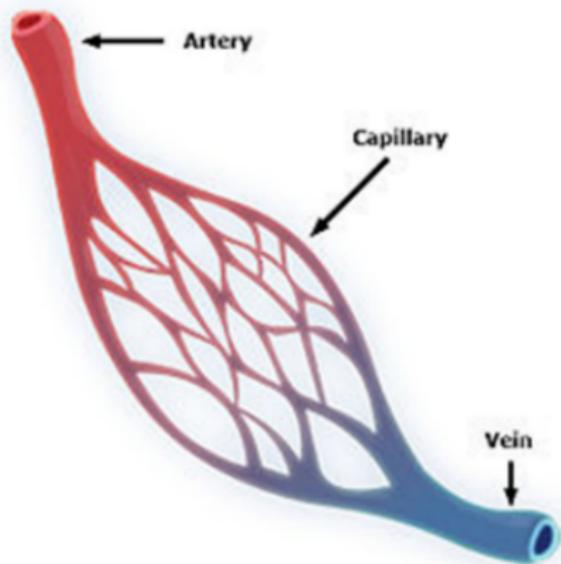


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- > Determine blood perfusion

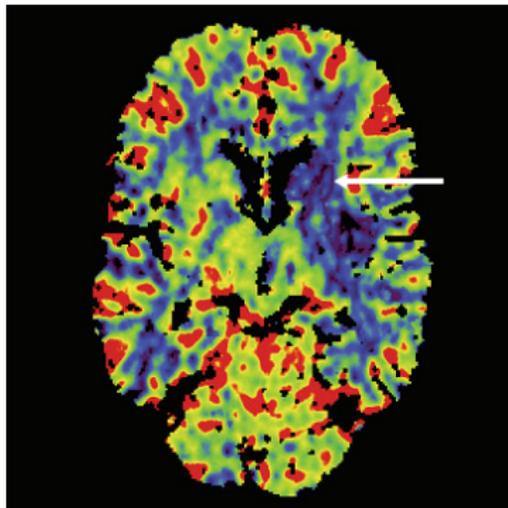


<https://en.wikipedia.org/wiki/Capillary>

Contrast enhanced dynamic MRI



- > Gadolinium Contrast Medium (MRI Contrast agents)
- > Determine blood perfusion
- > Diagnosis and treatment of cancer, strokes

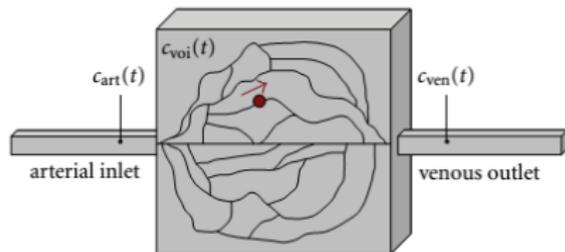


Fieselmann et. al., 2011,
Int. Journal of Biomedical Computing
doi:10.1155/2011/467563

Contrast enhanced dynamic MRI



- > Gadolinium Contrast Medium (MRI Contrast agents)
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Contrast enhanced dynamic MRI



- > Gadolinium Contrast Medium (MRI Contrast agents)
- > Determine blood perfusion
- > Diagnosis and treatment of cancer, strokes
- > Today: Calculated voxel by voxel
- > **Here: Model blood flow and use data assimilation**

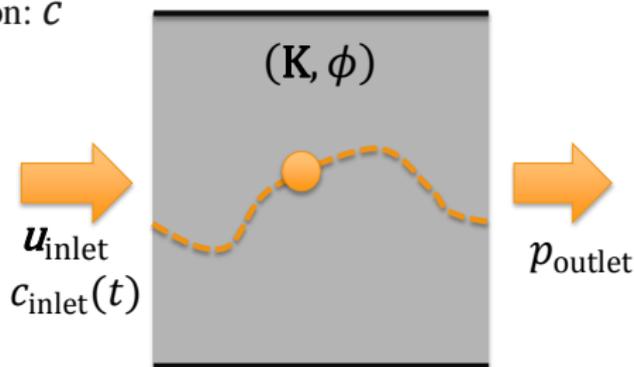
Flow of blood and contrast indicator

Incompressible porous media: $\mathbf{u} = -\mu^{-1}\mathbf{K} \cdot \nabla p$, $\nabla \cdot \mathbf{u} = 0$

Passive tracer: $\phi \frac{\partial c}{\partial t} - \nabla \cdot (c\mathbf{u}) = 0$

- Contrast indicator concentration: c
- Filtration velocity: \mathbf{u}
- Pressure: p

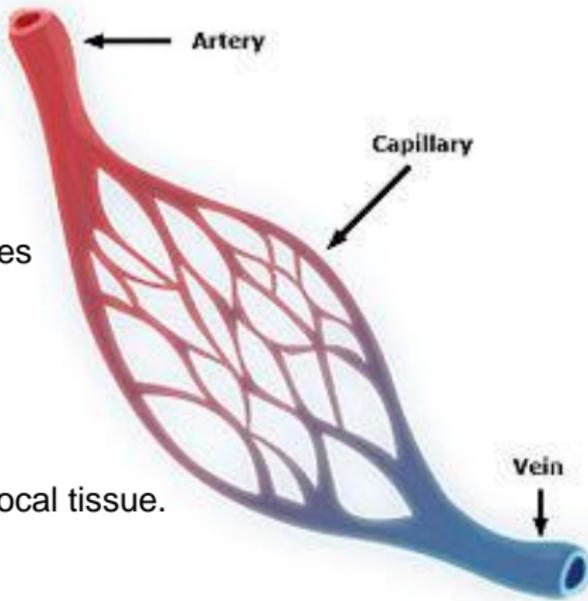
-
- Blood viscosity: μ
 - Flow conductivity: $\mu^{-1}\mathbf{K}$
 - Porosity: ϕ



Two-compartment model (“dual por. / dual perm.”)

The amount of contrast indicator observed within a «voxel» comprises

- Arterial transit.
- Venular transit.
- Capillary perfusion feeding the local tissue.



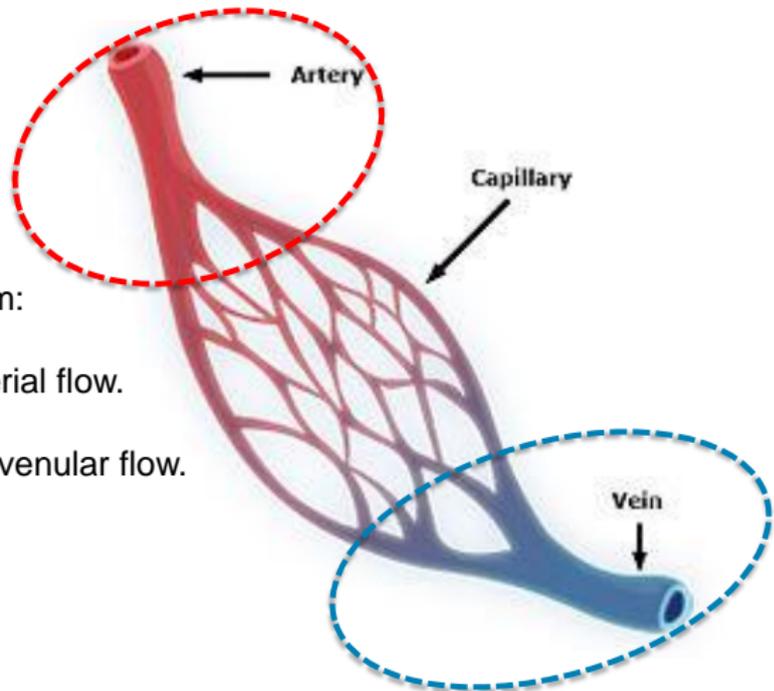
(<https://en.wikipedia.org/wiki/Capillary>)

Two-compartment model (“dual por. / dual perm.”)



Decompose the flow problem:

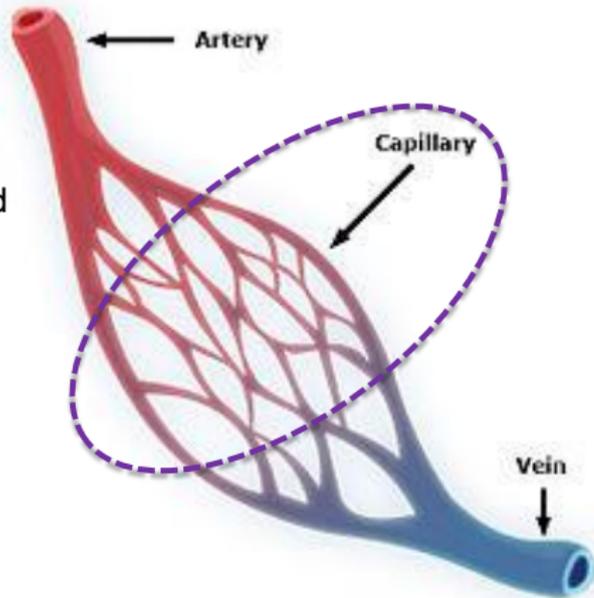
- One global model for arterial flow.
- Another global model for venular flow.
- ...



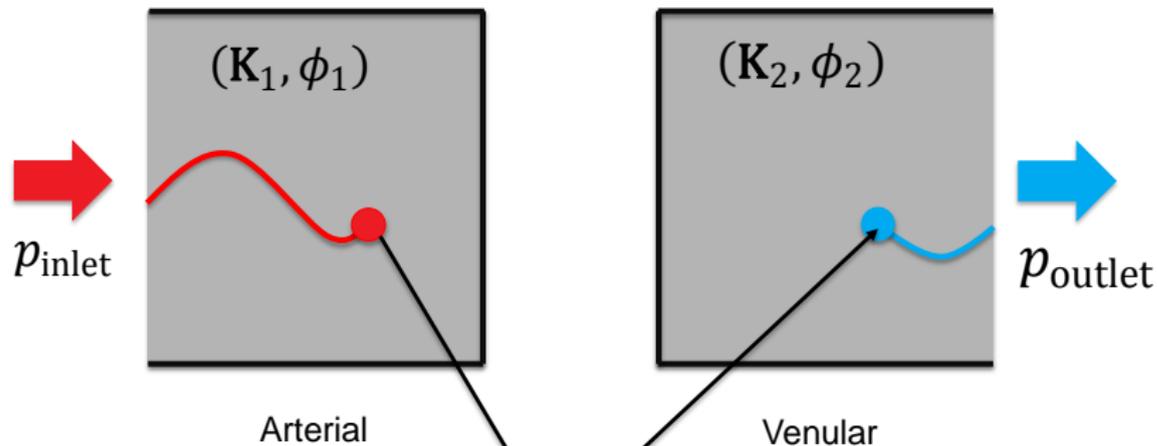
Two-compartment model (“dual por. / dual perm.”)

Capillary perfusion is represented by local transfer functions:

- Sinks for the arterial flow.
- Sources for venular flow.



Two-compartment model (“dual por. / dual perm.”)



Transfer between arterial and venular system, relates explicitly to perfusion as «feeding blood flow to the tissue».

$$\nabla \cdot \mathbf{u}_1 = -Q = -\mu^{-1} K_X \sigma (p_2 - p_1)$$

$$\nabla \cdot \mathbf{u}_2 = Q$$

Ensemble Kalman filter (Evensen (1994))

$$x_n = F(x_{n-1}) + \epsilon_n$$

$$y_n = Gx_n + \eta_n$$

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Ensemble Kalman filter solution:

$$X_n = [x_{n,1} \dots x_{n,N}]$$

$$x_{n,i} = F(x_{n-1,i}) + \epsilon_{n,i}$$

$$y_{n,i} = Gx_{n,i} + \eta_{n,i}$$

$$\bar{x}_n = \frac{1}{N} \sum_{i=1}^N x_{n,i}$$

$$\bar{C}_n = \frac{1}{N-1} \sum_{i=1}^N (x_{n,i} - \bar{x}_n)(x_{n,i} - \bar{x}_n)^T$$

$$K_n = \bar{C}_n G^T (G \bar{C}_n G^T + C_D)^{-1}$$

$$\hat{x}_{n,i} = x_{n,i} + K_n (y_{o,n} - y_{n,i})$$

ensemble of size N

(linear observations)

Estimated Kalman gain

$$i = 1, \dots, N$$

Parameter estimation using EnKF

$$\begin{bmatrix} x_n \\ \rho_n \\ y_n \end{bmatrix} = \begin{bmatrix} F(x_{n-1}) \\ \rho_{n-1} \\ G(x_n) \end{bmatrix}$$

- ρ_n : unknown parameter vector
(porosity, tissue permeability)
- x_n : pressure, saturations
- $y_n = G(x_n)$: non-linear measurements

Lorentzen et. al. 2001 (parameter estimation)
Nævdal et. al. 2002 (+ non-linear measurements)

Implementation for presented cases

Here: Half-iterative EnKF (or modification)

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Case 1:

- > **Adaptive Gaussian mixture filter**
 - Stordal et. al., Computational Geosciences, Vol. 15, 2011
- > **500** model realizations

Implementation for presented cases

Here: Half-iterative EnKF (or modification)

Case 1:

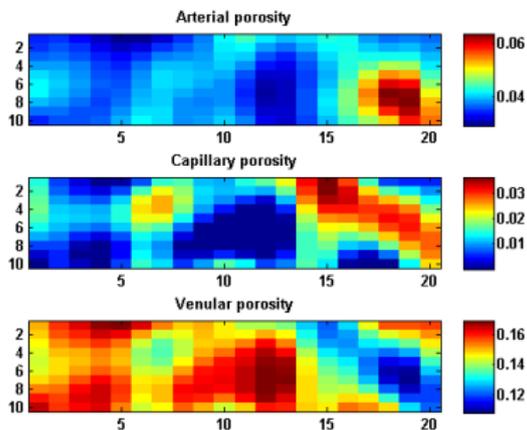
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Case 2:

- > EnKF with extreme localization
- > Only updating grid block where contrast is measured

Case study 1

- > 10 cm × 10 cm
- > Upper, lower and right side have zero-flow boundary conditions
- > Pressure at boundary:
Arterial: 13300 Pa
Venular: 133 Pa
- > Arterial inlet: Pulse lasting 4 seconds, $c_a = 1$
- > Contrast agent concentration: $m_{mri}(\vec{x}) = \phi_a \cdot c_a + \phi_{av} \cdot c_{av} + \phi_v \cdot c_v$



Porosity values

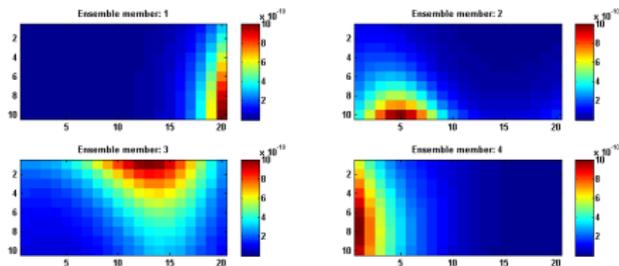
- > Measurement every 0.6sec
- > Measurement noise: 10^{-4}

Estimating perfusion

- > Darcy law: $\vec{u}_i = -\mu^{-1} K_i(\vec{x}) \nabla p_i$
- > Estimate $K_i(\vec{x})$
- > $K_a(\vec{x}) = K_v(\vec{x})$
- > Conductivity factor $K_{av}(\vec{x}) \sigma_{av}(\vec{x}) \sim 10 K_a(\vec{x})$

Estimating perfusion

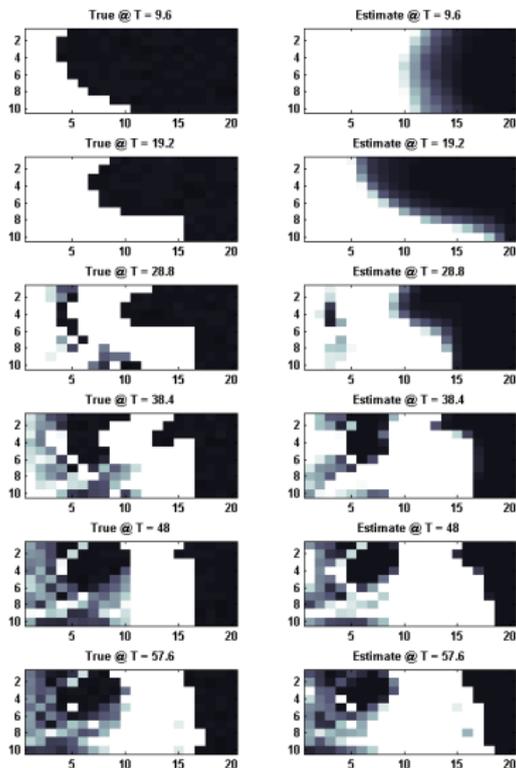
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K_a

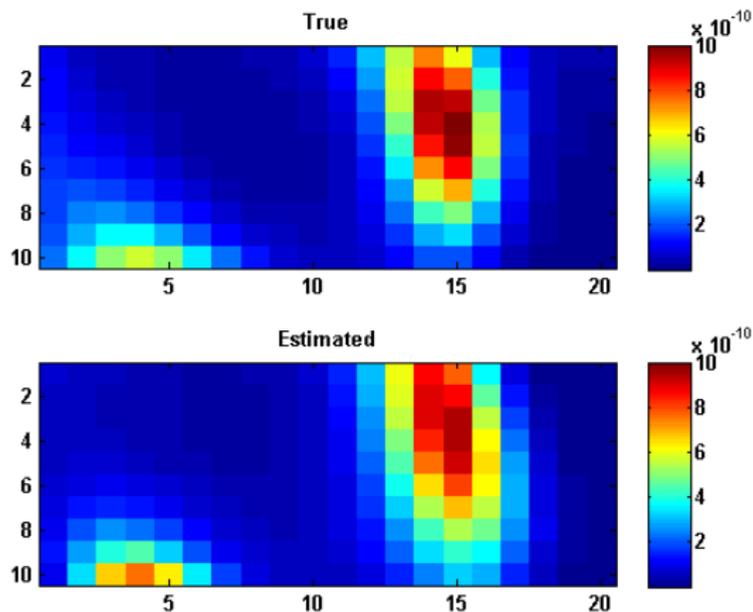
Four initial ensemble members
The units are [m^2].

Observed and simulated MRI data

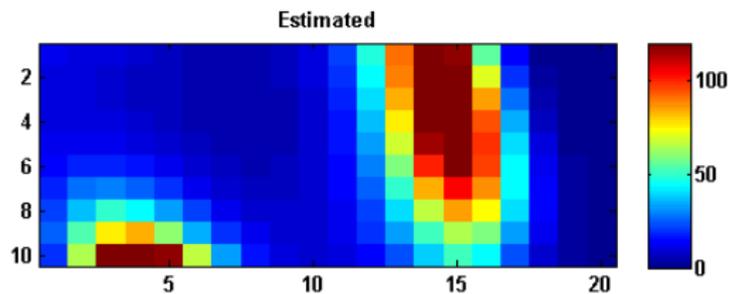
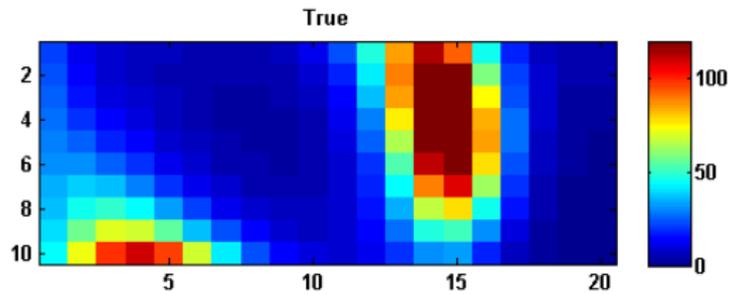


- > Black: Low concentration
- > White: High concentration
- > Range: $[0, 10^{-2}]$.

Estimated K_a field



Estimated perfusion

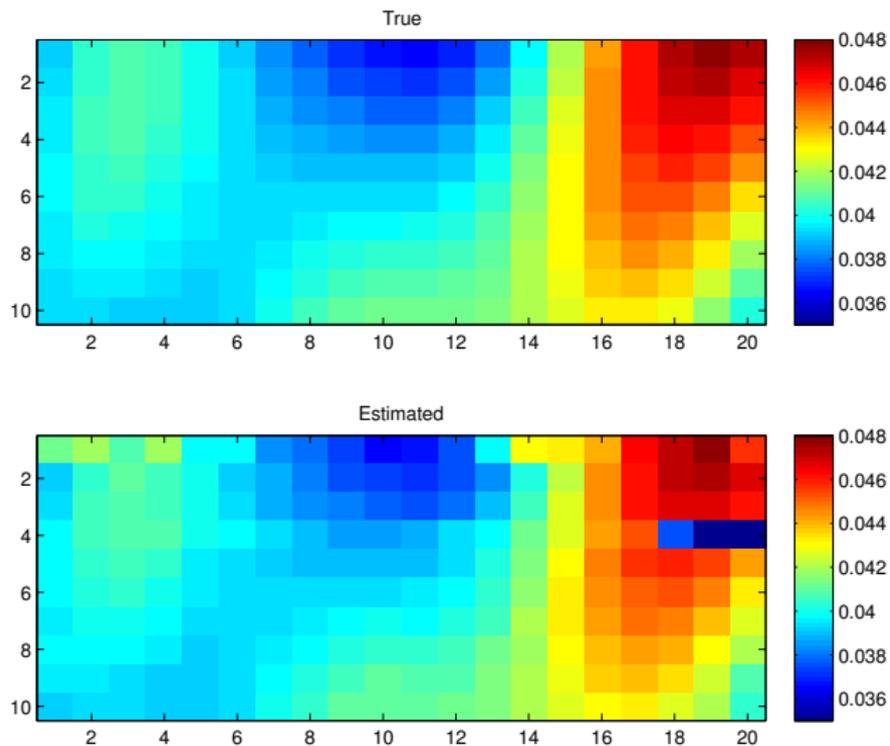


mL/min/100mL

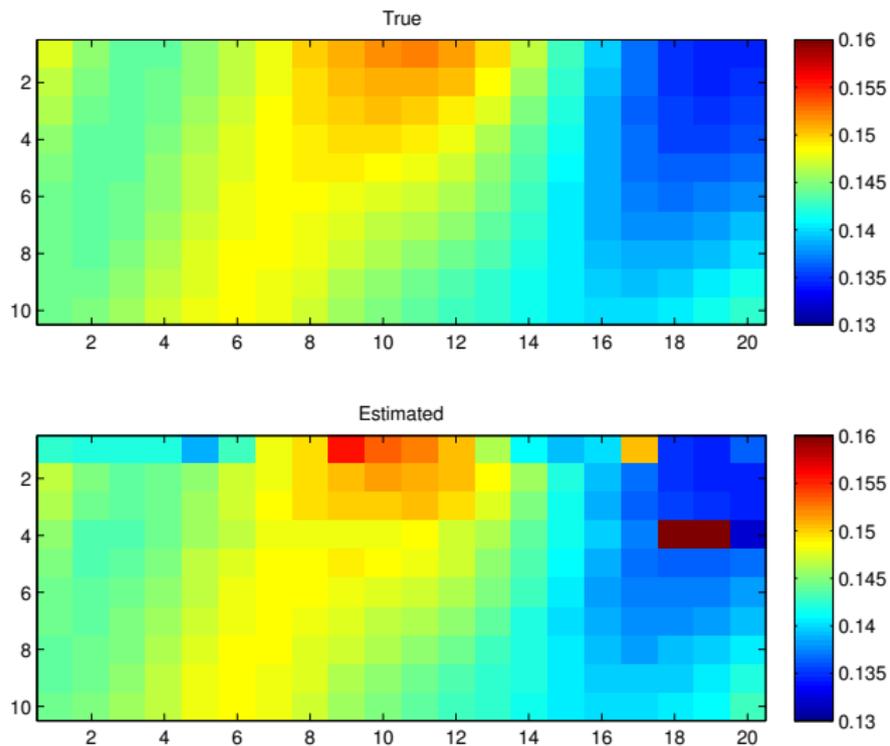
Case 2: Porosity of compartments

- > Goal: Estimate $\phi_a(\vec{X})$, $\phi_v(\vec{X})$ and $\phi_{av}(\vec{X})$
- > Constant hydraulic conductivity:
 - $K_{av} = 2 \cdot 10^{-9} \text{m}^{-2}$
 - $K_a = K_v = 2 \cdot 10^{-10} \text{m}^{-2}$
- > Initial ensemble:
 - geostatistical distribution of the fields
 - $\phi_v + \phi_a + \phi_{av} = 0.2$
- > EnKF, ensemble size 200
- > Localization: Only update porosities based on observations in its own grid block

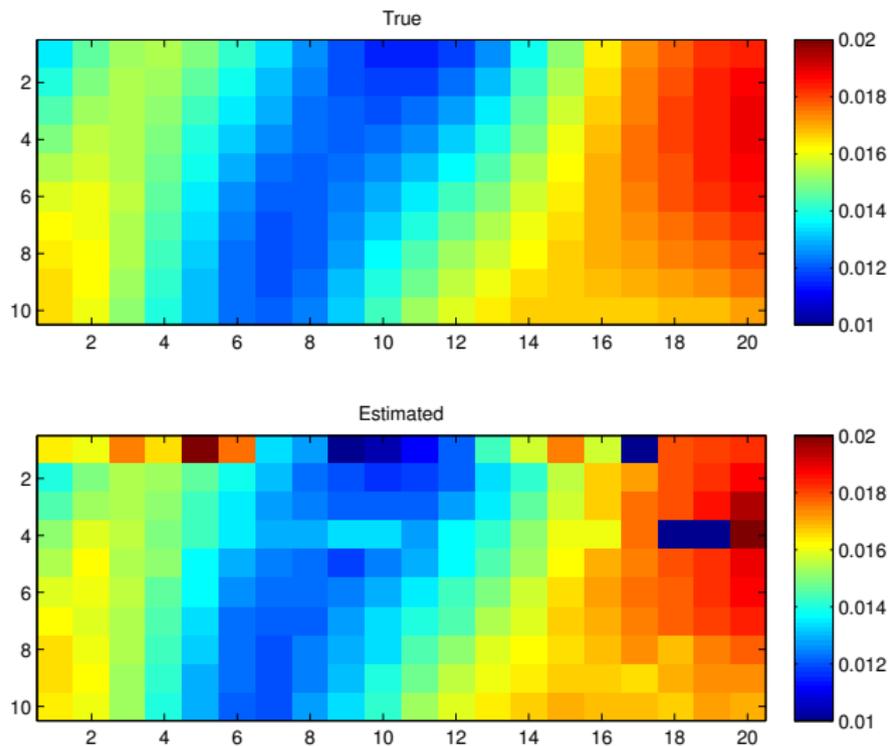
True and estimated ϕ_a



True and estimated ϕ_v



True and estimated ϕ_{av}



Conclusion



- > Paper available at eccomas2016.org/proceedings/pdf/9975.pdf

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Thank you!